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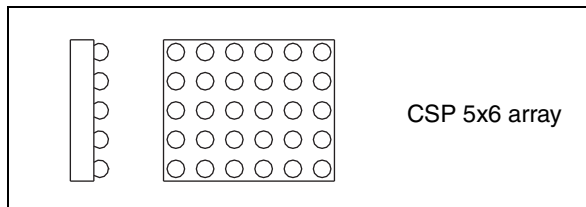
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## Sound Terminal<sup>®</sup>

### 2-channel high-efficiency digital audio system

Datasheet - production data



### Features

- Wide-range supply voltage (4.5 V - 20 V)
- 2 channels of ternary PWM (stereo mode)
- 2 channels of 24-bit FFX<sup>™</sup>
- 100 dB SNR and dynamic range
- Selectable 32- to 192-kHz input sampling rates
- Digital gain -80 dB to +48 dB in 0.5 dB steps
- Software volume update
- Individual channel and master gain/attenuation
- Individual channel and master software and hardware mute
- Independent channel volume bypass
- Automatic zero-detect mute
- Automatic invalid input detect mute
- Short-circuit detection at startup (Out-Vcc, Out-Gnd, Out 1b-Out 2a)
- 2-channel I<sup>2</sup>S input data interface
- 2 Hz DC cut filter (input)
- Input channel mapping
- Automatic volume control for limiting maximum power
- 96 kHz internal processing sampling rate, 24-bit precision
- Advanced modes for AM interference frequency switching and noise suppression
- Embedded thermal-overload and short-circuit protection
- Video application: 576 \* f<sub>S</sub> input mode support

### Applications

- LCDs
- DVDs
- Cradles
- Digital speakers
- Wireless-speaker cradles

### Description

The STA333IS is an integrated circuit comprising digital audio processing, digital amplifier control and an FFX<sup>™</sup> power output stage to create a high-power, single-chip FFX solution for all-digital amplification with high quality and high efficiency.

The STA333IS power section consists of four independent half-bridge stages. Two channels can be provided by two full bridges, delivering up to 10 W + 10 W of power.

Also featured in the STA333IS are new advanced modes for reducing AM radio interference. The serial audio data input interface accepts all possible formats, including the popular I<sup>2</sup>S format. Two channels of FFX<sup>™</sup> processing are provided.

The STA333IS is part of the Sound Terminal<sup>®</sup> family that provides full digital audio streaming to the speaker, offering cost effectiveness, low-power dissipation and sound enrichment.

**Table 1. Device summary**

Order code	Package	Packaging
STA333IS	CSP 5x6 array	Tape and reel

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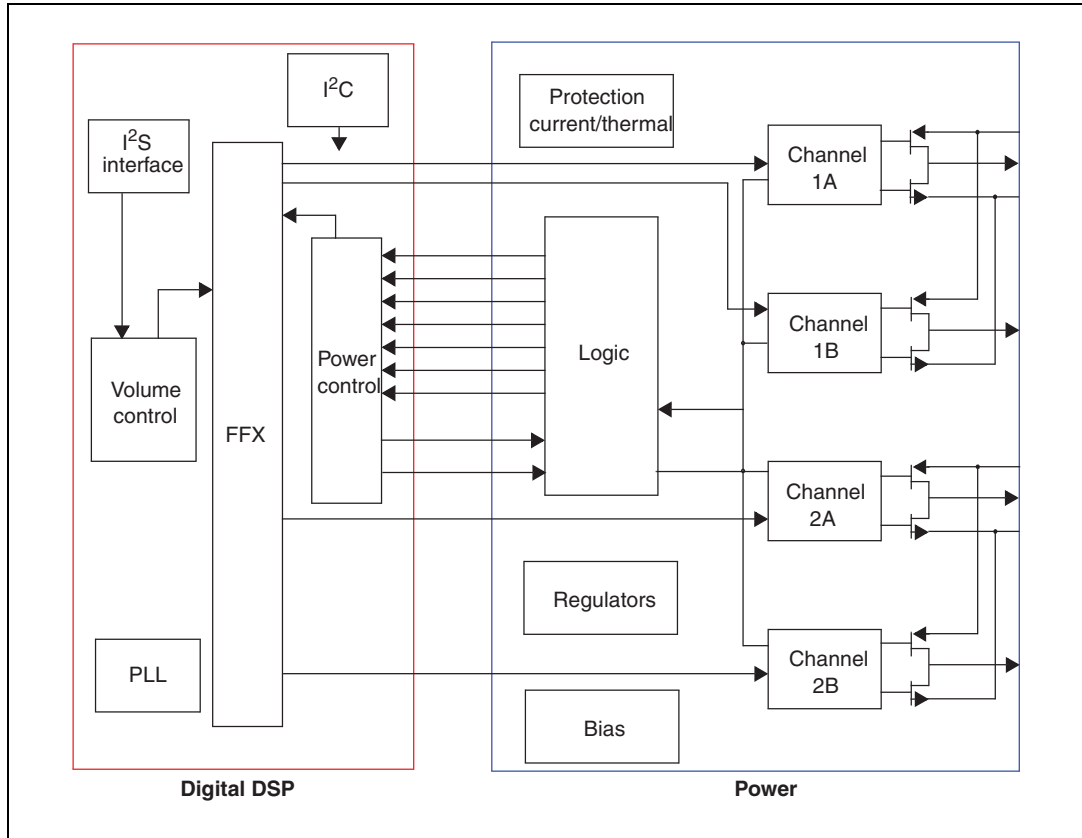
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# 1 Block diagram

Figure 1. Block diagram





## 2 Pin description

### 2.1 Pinout

Figure 2. Pin connections (package top view)

	1	2	3	4	5
A	GND1	OUT1	NC	VDDREG	SDI
B	GND1	VCC1	NC	LRCKI	VDD_DIG
C	OUT1B	VCC1	GNDREG	BICKI	GND_DIG
D	OUT2A	VCC2	VCCREG	SDA	XTI
E	GND2	VCC2	NC	SCL	VDD_PLL
F	GND2	OUT2B	NC	VSS	GND_PLL

## 2.2 Pin list

Table 2. Pin description

Pin number	Name	Description	Pad information
<b>I/O pins</b>			
B4	LRCKI	I <sup>2</sup> S Left/Right clock	
C4	BICKI	I <sup>2</sup> S serial clock	
A5	SDI	I <sup>2</sup> S serial data channels 1 & 2	
D5	XTI	Master clock input	
E4	SCL	I <sup>2</sup> C serial clock	
D4	SDA	I <sup>2</sup> C serial data	
<b>Power output pins</b>			
A2	OUT1A	Positive output 1	
C1	OUT1B	Negative output 1	
D1	OUT2A	Positive output 2	
F2	OUT2B	Negative output 2	
<b>Power supplies (preliminary)</b>			
B2/C2	VCC1	Positive supply (upper MOSFET) to left H-bridge P output	
E2/D2	VCC2	Positive supply (upper MOSFET) to right H-bridge P output	
A1/B1	GND1	Negative supply (lower MOSFET) to left H-bridge P output	
E1/F1	GND2	Negative supply (lower MOSFET) to right H-bridge P output	
D3	VCCREG	Reference voltage to Vcc	These pins are output pins that must be externally filtered. Do not connect these pins to external supply voltage.
C3	GNDREG	Reference voltage to ground	
A4	VDDREG	Reference voltage to 3.3 V	
F4	VSS	Reference voltage to Vcc - 3.3 V	
B5	VDD_DIG	Digital supply	
C5	GND_DIG	Digital ground	
E5	VDD_PLL	PLL supply	
F5	GND_PLL	PLL ground	
A3, B3, E3, F3	NC	Not connected	

## 3 Electrical specifications

### 3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings

Symbol	Parameter	Min	Typ	Max	Unit
V <sub>CC</sub>	Analog supply voltage (pins VCCx)	-0.3	-	22	V
V <sub>DD</sub>	Digital supply voltage (pins VDD_DIG)	-0.3	-	4.0	V
I <sub>L</sub>	Logic input interface	-0.3	-	4.0	V
T <sub>op</sub>	Operating junction temperature	0	-	150	°C
T <sub>stg</sub>	Storage temperature	-40	-	150	°C

**Warning:** Stresses beyond those listed in [Table 3: Absolute maximum ratings](#) may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in [Table 5: Recommended operating conditions](#) are not implied. Exposure to absolute maximum rated conditions for extended periods may affect device reliability. In the real application, a power supply with nominal value rated within the limits of the recommended operating conditions may rise beyond the maximum operating conditions for a short time when no or very low current is sunk (amplifier in mute state). In this case the reliability of the device is guaranteed, provided that the absolute maximum ratings are not exceeded.

### 3.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Min	Typ	Max	Unit
R <sub>Th(j-a)</sub>	Thermal resistance junction-to-ambient <sup>(1)</sup>	-	45	-	°C/W
T <sub>sd</sub>	Thermal shutdown junction temperature	140	150	160	°C
T <sub>w</sub>	Thermal warning temperature	-	130	-	°C
T <sub>hsd</sub>	Thermal shutdown hysteresis	18	20	22	°C

1. Measurements performed on ST 2-layer reference board (1 oz. PCB, 3.8 cm<sup>2</sup> exposed copper dissipation area)

### 3.3 Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Min	Typ	Max	Unit
$V_{CC}$	Analog supply voltage (VCCx)	4.5	-	20	V
$V_{DD}$	Digital supply voltage (VDD_DIG)	3.0	3.3	3.6	V
$I_L$	Logic input interface	3.0	3.3	3.6	V
$T_{amb}$	Ambient temperature	0	-	70	°C

### 3.4 Electrical specifications - digital section

Table 6. Electrical characteristics for digital section

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{il}$	Input current, no pull-up or pull-down resistor	$V_i = 0\text{ V}$	-	-	$\pm 10$	$\mu\text{A}$
$I_{ih}$		$V_i = V_{DD} = 3.6\text{ V}$	-	-	$\pm 10$	$\mu\text{A}$
$V_{il}$	Low-level input voltage	-	-	-	$0.2^* V_{DD}$	V
$V_{ih}$	High-level input voltage	-	$0.8^* V_{DD}$	-	-	V
$V_{ol}$	Low-level output voltage	$I_{ol} = 2\text{ mA}$	-	-	0.3V	V
$V_{oh}$	High-level output voltage	$I_{oh} = 2\text{ mA}$	$V_{DD} - 0.3\text{V}$	-	-	V
$I_{pu}$	Pull-up current	-	25	66	125	$\mu\text{A}$
$R_{pu}$	Equivalent pull-up resistance	-	-	50	-	$\text{k}\Omega$

### 3.5 Electrical specifications - power section

The specifications in [Table 7](#) below are given for the conditions  $V_{CC} = 13\text{ V}$ ,  $V_{DD} = 3.3\text{ V}$ ,  $f_{SW} = 384\text{ kHz}$ ,  $T_{amb} = 25\text{ °C}$  and  $R_L = 8\text{ }\Omega$ , unless otherwise specified.

**Table 7. Electrical specifications for power section**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Po	Output power BTL	THD = 1%	-	8	-	W
		THD = 10%	-	10	-	
$R_{dsON}$	Power P-channel/N-channel MOSFET (total bridge)	$I_d = 1\text{ A}$	-	110	-	m $\Omega$
$I_{dss}$	Power P-channel/N-channel leakage	$V_{CC} = 20\text{ V}$	-	-	10	$\mu\text{A}$
gP	Power P-channel $R_{dsON}$ matching	$I_d = 1\text{ A}$	95	-	-	%
gN	Power N-channel $R_{dsON}$ matching	$I_d = 1\text{ A}$	95	-	-	%
$I_{LDT}$	Low-current dead time (static)	Resistive load, refer to <a href="#">Figure 4</a>	-	5	10	ns
$I_{HDT}$	High-current dead time (dynamic)	Refer to <a href="#">Figure 5</a>	-	10	20	ns
$t_r$	Rise time	Resistive load, refer to <a href="#">Figure 4</a>	-	8	10	ns
$t_f$	Fall time	Resistive load, refer to <a href="#">Figure 4</a>	-	8	10	ns
$V_{CC}$	Supply voltage	-	4.5	-	20	V
$I_{VCC}$	Supply current from $V_{CC}$ in power-down	At power-ON (EAPD bit = 0)	30	60	200	$\mu\text{A}$
	Supply current from $V_{CC}$ in operation	PCM input signal = -60 dBfs Internal clock = 49.152 MHz	-	30	50	mA
$I_{VDD\_DIG}$	Supply current for FFX processing (reference only)	Switching frequency = 384 kHz No LC filters	-	30	50	mA
	Supply current in standby	(PWDN bit = 0)	-	11	25	mA
$I_{LIM}$	Overcurrent limit	Non-linear output <sup>(1)</sup>	2.2	3.5	4.3	A
$I_{SCP}$	Short-circuit protection	High-impedance output <sup>(2)</sup>	2.7	3.8	5.0	A
$V_{UVP}$	Undervoltage protection threshold	-	-	3.5	4.3	V
$t_{min}$	Output minimum pulse width	No load	20	30	60	ns
THD+N	Total harmonic distortion and noise	FFX stereo mode, $P_o = 1\text{ W}$ , $f = 1\text{ kHz}$	-	0.05	-	%
DR	Dynamic range	-	-	100	-	dB
SNR	Signal to noise ratio in ternary mode	A-weighted	-	100	-	dB
	Signal to noise ratio in binary mode	A-weighted	-	90	-	
PSRR	Power supply rejection ratio	FFX stereo mode, < 5 kHz, $V_{RIPPLE} = 1\text{ V RMS}$ audio input = dither only	-	80	-	dB

**Table 7. Electrical specifications for power section (continued)**

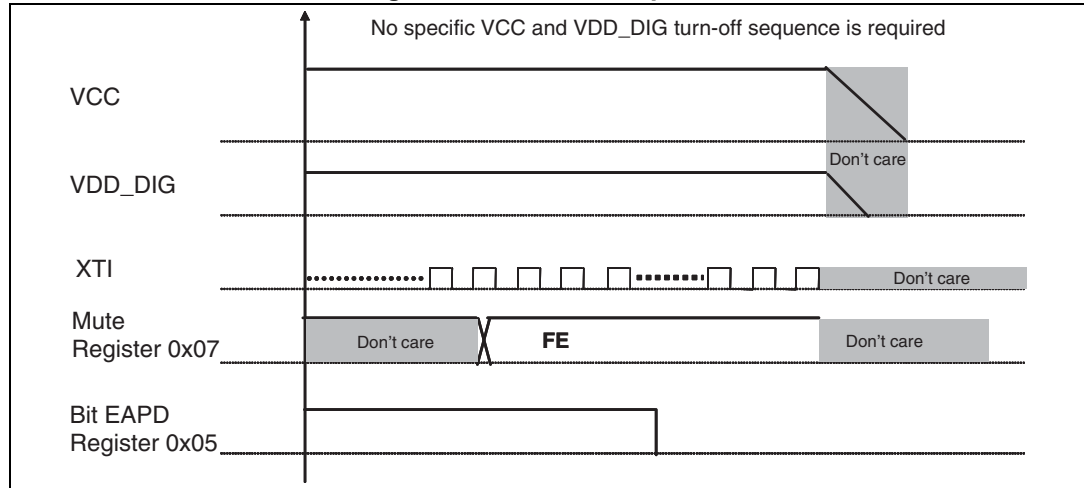
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
X <sub>TALK</sub>	Crosstalk	FFX stereo mode, < 5 kHz, One channel driven at 1 W the other channel measured	-	80	-	dB
η	Peak efficiency in FFX mode	P <sub>o</sub> = 2 x 10 W into 8 Ω	-	90	-	%

1. The I<sub>LIM</sub> data is for 1 channel of BTL configuration, thus, 2 \* I<sub>LIM</sub> drives the 2-channel BTL configuration. The current limit is active when OCRB = 0 (see [Table 23: Overcurrent warning detect adjustment bypass on page 26](#)). When OCRB = 1, then I<sub>SC</sub> applies.
2. The I<sub>SCP</sub> current limit data is for 1 channel of BTL configuration, thus, 2 \* I<sub>SCP</sub> drives the 2-channel BTL configuration. The short-circuit current is applicable when OCRB = 1 (see [Table 23: Overcurrent warning detect adjustment bypass on page 26](#)).

### 3.6 Power-off sequence

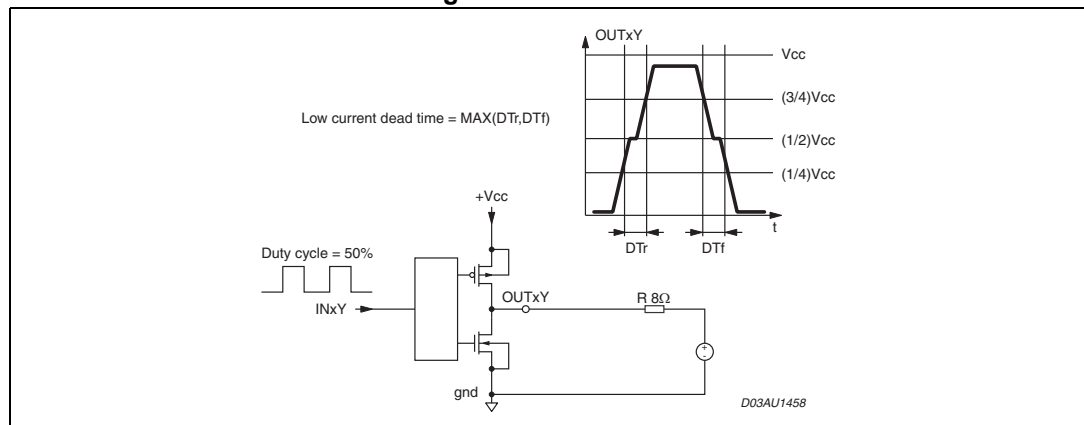
The power-off sequence shown in *Figure 3* below ensures a pop-free turn-off.

**Figure 3. Power-off sequence**

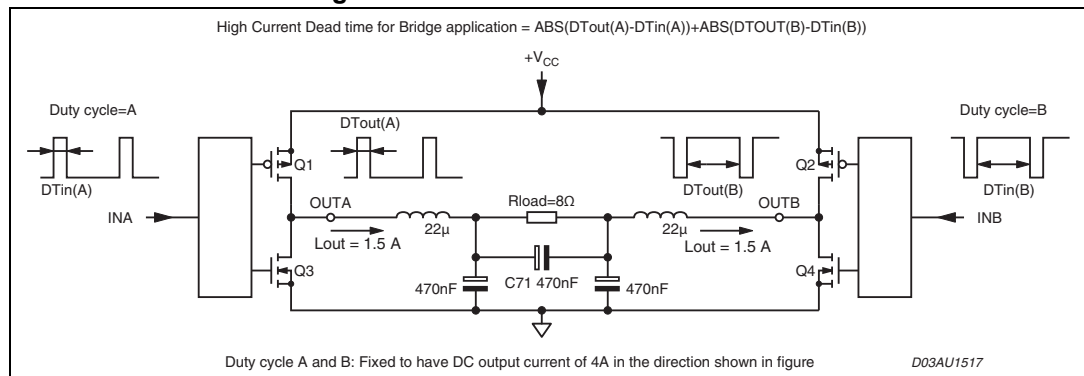


### 3.7 Testing

**Figure 4. Test circuit**



**Figure 5. Current deadtime test circuit**



### 3.8 Serial audio interface description

#### 3.8.1 Serial audio interface protocols

The STA333IS serial audio input was designed to interface with standard digital audio components and to accept serial data formats. The STA333IS always acts as a slave when receiving audio input from standard digital audio components. Serial data for two channels is provided using 3 input pins: left/right clock LRCKI (pin B4), serial clock BICKI (pin C4), and serial data SDI (pin A5).

The available formats are shown in [Figure 6](#) and [Figure 7](#), and set through [Configuration register B \(addr 0x01\) on page 22](#).

Figure 6. I<sup>2</sup>S

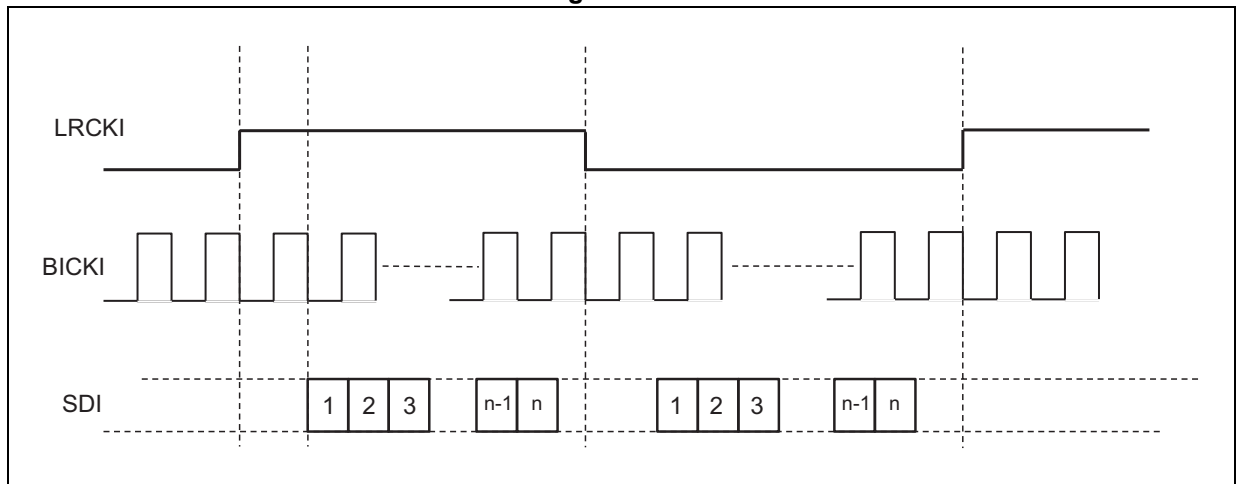
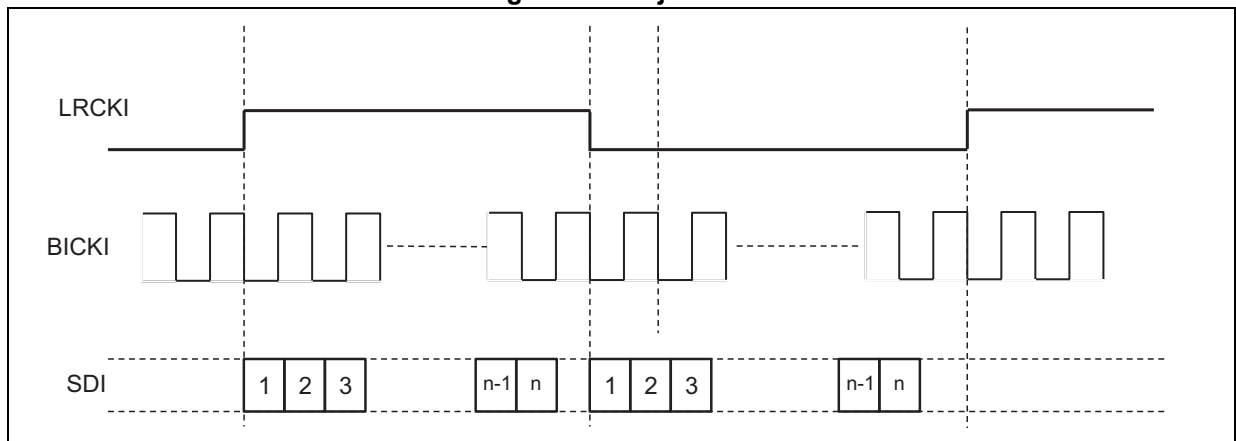


Figure 7. Left-justified





## 4 I<sup>2</sup>C bus specification

The STA333IS supports the I<sup>2</sup>C protocol via the input ports SCL and SDA. This protocol defines any device that sends data to the bus as a transmitter and any device that reads the data as a receiver. The device that controls the data transfer is known as the master and the other as the slave. The master always starts the transfer and provides the serial clock for synchronization. The STA333IS is always a slave device in all of its communications. It supports up to 400 kb/s (fast-mode bit rate).

### 4.1 Communication protocol

#### 4.1.1 Data transition or change

Data changes on the SDA line must only occur when the SCL clock is low. An SDA transition while the clock is high is used to identify a START or STOP condition.

#### 4.1.2 Start condition

START is identified by a high-to-low transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A START condition must precede any command for data transfer.

#### 4.1.3 Stop condition

STOP is identified by a low-to-high transition of the data bus SDA signal while the clock signal SCL is stable in the high state. A STOP condition terminates communication between the STA333IS and the bus master.

#### 4.1.4 Data input

During data input the STA333IS samples the SDA signal on the rising edge of clock SCL. For correct device operation the SDA signal must be stable during the rising edge of the clock and the data can change only when the SCL line is low.

### 4.2 Device addressing

To start communication between the master and the STA333IS, the master must initiate a start condition. Following this, the master sends to the SDA line 8 bits (MSB first) corresponding to the device select address and read or write mode.

The 7 most significant bits are the device address identifiers, corresponding to the I<sup>2</sup>C bus definition. In the STA333IS the I<sup>2</sup>C interface has device address 0x38.

The 8<sup>th</sup> bit (LSB) identifies the read or write operation RW, this bit is set to 1 for read mode and 0 for write mode. After a START condition the STA333IS identifies the device address on the SDA bus and if a match is found, acknowledges the identification during the 9<sup>th</sup> bit time. The byte following the device identification byte is the internal space address.

### 4.3 Write operation

Following the START condition the master sends a device select code with the RW bit set to 0. The STA333IS acknowledges this and then waits for the byte of internal address. After receiving the internal byte address, the STA333IS again responds with an acknowledgement.

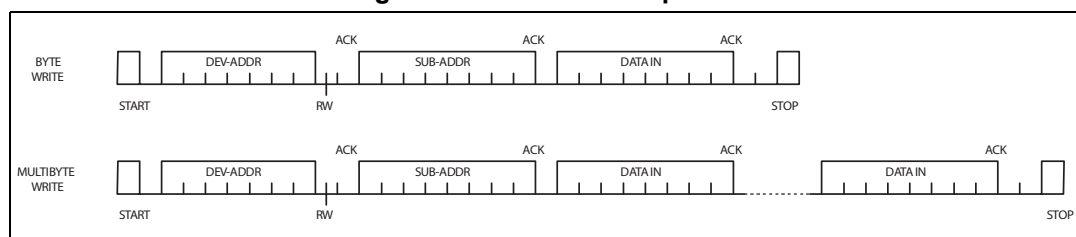
#### 4.3.1 Byte write

In the byte write mode the master sends one data byte which is acknowledged by the STA333IS. The master then terminates the transfer by generating a STOP condition.

#### 4.3.2 Multi-byte write

The multi-byte write modes can start from any internal address. The master generating a STOP condition terminates the transfer.

Figure 8. Write-mode sequence



### 4.4 Read operation

#### 4.4.1 Current address byte read

Following the START condition the master sends a device select code with the RW bit set to 1. The STA333IS acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

#### 4.4.2 Current address multi-byte read

The multi-byte read modes can start from any internal address. Sequential data bytes are read from sequential addresses within the STA333IS. The master acknowledges each data byte read and then generates a STOP condition, terminating the transfer.

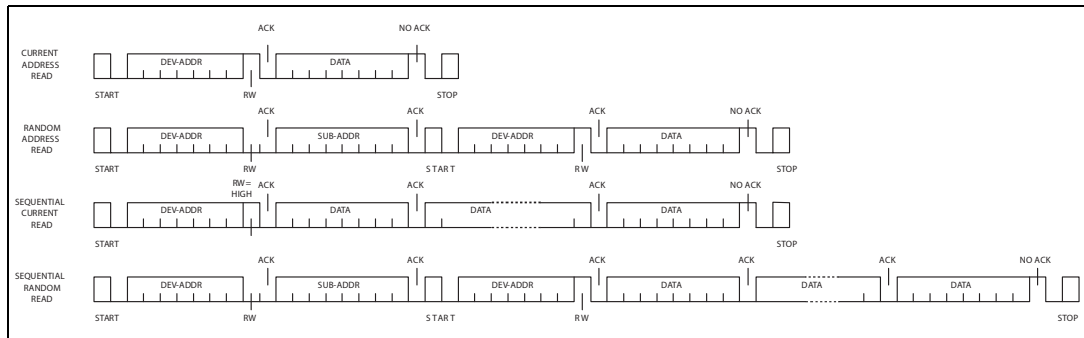
#### 4.4.3 Random address byte read

Following the START condition the master sends a device select code with the RW bit set to 0. The STA333IS acknowledges this and then the master writes the internal address byte. After receiving the internal byte address, the STA333IS again responds with an acknowledgement. The master then initiates another START condition and sends the device select code with the RW bit set to 1. The STA333IS acknowledges this and then responds by sending one byte of data. The master then terminates the transfer by generating a STOP condition.

### 4.4.4 Random address multi-byte read

The multi-byte read modes can start from any internal address. Sequential data bytes are read from sequential addresses within the STA333IS. The master acknowledges each data byte read and then generates a STOP condition to terminate the transfer.

Figure 9. Read-mode sequence



## 5 Register description

**Table 8. Register summary**

Addr	Name	D7	D6	D5	D4	D3	D2	D1	D0
0x00	CONFA	FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0x01	CONFB	C2IM	C1IM	Reserved	SAIFB	SAI3	SAI2	SAI1	SAI0
0x02	CONFC	OCRB	Reserved	CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
0x03	CONFD	Reserved	ZDE	Reserved					
0x04	CONF E	SVE	ZCE	DCCV	PWMS	AME	NSBW	MPC	MPCV
0x05	CONFF	EAPD	PWDN	ECLE	LDTE	BCLE	IDE	Reserved	
0x06	MUTE	Reserved					C2M	C1M	MMUTE
0x07	MVOL	MV7	MV6	MV5	MV4	MV3	MV2	MV1	MV0
0x08	C1VOL	C1V7	C1V6	C1V5	C1V4	C1V3	C1V2	C1V1	C1V0
0x09	C2VOL	C2V7	C2V6	C2V5	C2V4	C2V3	C2V2	C2V1	C2V0
0x0C	AUTO	Reserved				AMAM2	AMAM1	AMAM0	AMAME
0x0E	C1CFG	Reserved					C1VBP	Reserved	
0x0F	C2CFG	Reserved					C2VBP	Reserved	
0x27	MPCC1	MPCC15	MPCC14	MPCC13	MPCC12	MPCC11	MPCC10	MPCC9	MPCC8
0x28	MPCC2	MPCC7	MPCC6	MPCC5	MPCC4	MPCC3	MPCC2	MPCC1	MPCC0
0x29	DCC1	DCC15	DCC14	DCC13	DCC12	DCC11	DCC10	DCC9	DCC8
0x2A	DCC2	DCC7	DCC6	DCC5	DCC4	DCC3	DCC2	DCC1	DCC0
0x2B	FDRC1	FDRC15	FDRC14	FDRC13	FDRC12	FDRC11	FDRC10	FDRC9	FDRC8
0x2C	FDRC2	FDRC7	FDRC6	FDRC5	FDRC4	FDRC3	FDRC2	FDRC1	FDRC0
0x2D	STATUS	PLLUL	FAULT	UVFAULT	OVFAULT	OCFAULT	OCWARN	TFault	TWARN
0x2E	BIST1	Reserved		RO1BACT	R5BACT				R1BACT
0x2F	BIST2	Reserved		R01BEND	R5BEND				R1BEND
0x30	BIST3	Reserved			R5BBAD				R1BBAD
0x31	TSTCTL	Reserved							
0x32	C1PS	C1PS7	C1PS6	C1PS5	C1PS4	C1PS3	C1PS2	C1PS1	C1PS0
0x33	C2PS	C2PS7	C2PS6	C2PS5	C2PS4	C2PS3	C2PS2	C2PS1	C2PS0
0x34	OLIM	OLIM7	OLIM6	OLIM5	OLIM4	OLIM3	OLIM2	OLIM1	OLIM0
0x35	SHEN	Reserved						ENABLE_SH	Reserved
0x36	Reserved								
0x37	SHORT	SHGND1A	SHGND1B	SHGND2A	SHGND2B	SHVCC1A	SHVCC1B	SHVCC2A	SHVCC2B
0x38	SHOUT	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	SHOUT

## 5.1 Configuration registers (addr 0x00 to 0x05)

### 5.1.1 Configuration register A (addr 0x00)

D7	D6	D5	D4	D3	D2	D1	D0
FDRB	TWAB	TWRB	IR1	IR0	MCS2	MCS1	MCS0
0	1	1	0	0	0	1	1

#### Master clock select

Table 9. Master clock select

Bit	R/W	RST	Name	Description
0	R/W	1	MCS0	Master clock select: Selects the ratio between the input I <sup>2</sup> S sampling frequency and the input clock.
1	R/W	1	MCS1	
2	R/W	0	MCS2	

The STA333IS supports sampling rates of 32 kHz, 44.1 kHz, 48 kHz, 88.2 kHz, 96 kHz, 176.4 kHz, and 192 kHz. Therefore the internal clock is:

- 32.768 MHz for 32 kHz
- 45.1584 MHz for 44.1 kHz, 88.2 kHz, and 176.4 kHz
- 49.152 MHz for 48 kHz, 96 kHz, and 192 kHz

The external clock frequency provided to the XTI pin must be a multiple of the input sampling frequency ( $f_S$ ).

The relationship between the input clock and the input sampling rate is determined by both the MCSx and the IR (input rate) register bits. The MCSx bits determine the PLL factor generating the internal clock and the IR bit determines the oversampling ratio used internally.

Table 10. MCS bits

Input sampling rate $f_S$ (kHz)	IR	MCS[2:0]					
		101	100	011	010	001	000
32, 44.1, 48	00	$576 * f_S$	$128 * f_S$	$256 * f_S$	$384 * f_S$	$512 * f_S$	$768 * f_S$
88.2, 96	01	NA	$64 * f_S$	$128 * f_S$	$192 * f_S$	$256 * f_S$	$384 * f_S$
176.4, 192	1X	NA	$32 * f_S$	$64 * f_S$	$96 * f_S$	$128 * f_S$	$192 * f_S$

**Interpolation ratio select**

**Table 11. Interpolation ratio select**

Bit	R/W	RST	Name	Description
4:3	R/W	00	IR [1:0]	Interpolation ratio select: Selects internal interpolation ratio based on input I <sup>2</sup> S sampling frequency.

The STA333IS has variable interpolation (oversampling) settings such that internal processing and FFX output rates remain consistent. The first processing block interpolates by either 2 times or 1 time (pass-through) or provides a 2-time downsampling. The oversampling ratio of this interpolation is determined by the IR bits.

**Table 12. IR bit settings as a function of input sampling rate**

Input sampling rate $f_s$ (kHz)	IR	1 <sup>st</sup> stage interpolation ratio
32	00	2-time oversampling
44.1	00	2-time oversampling
48	00	2-time oversampling
88.2	01	Pass-through
96	01	Pass-through
176.2	10	2-time downsampling
192	10	2-time downsampling

**Thermal warning recovery bypass**

**Table 13. Thermal warning recovery**

Bit	R/W	RST	Name	Description
5	R/W	1	TWRB	Thermal warning recovery bypass: 0: thermal warning recovery enabled 1: thermal warning recovery disabled

If the thermal warning adjustment is enabled (TWAB = 0), then the thermal warning recovery determines if the -3 dB output limit is removed when thermal warning is negative.

If TWRB = 0 and TWAB = 0, then when a thermal warning disappears, the -3 dB output limit is removed and the gain is added back to the system. If TWRB = 1 and TWAB = 0, then when a thermal warning disappears, the -3 dB output limit remains until TWRB is changed to zero or the device is reset.

### Thermal warning adjustment bypass

Table 14. Thermal warning adjustment

Bit	R/W	RST	Name	Description
6	R/W	1	TWAB	Thermal warning adjustment bypass: 0: thermal warning adjustment enabled 1: thermal warning adjustment disabled

The on-chip STA333IS power output block provides feedback to the digital controller using inputs to the power control block. The TWARN input is used to indicate a thermal warning condition. When TWARN is asserted (set to 0) for a period of time greater than 400 ms, the power control block will force a -3 dB output limit (determined by TWOCL in coefficient RAM) to the modulation limit in an attempt to eliminate the thermal warning condition. Once the thermal warning output limit adjustment is applied, it remains in this state until reset unless FDRB = 0.

### Fault-detect recovery bypass

Table 15. Fault-detect recovery

Bit	R/W	RST	Name	Description
7	R/W	0	FDRB	Fault-detect recovery bypass: 0: fault-detect recovery enabled 1: fault-detect recovery disabled

The on-chip STA333IS power output block provides feedback to the digital controller using inputs to the power control block. The FAULT input is used to indicate a fault condition (either overcurrent or thermal). When FAULT is asserted (set to 0), the power control block attempts a recovery from the fault by asserting the 3-state output (setting it to 0 which directs the power output block to begin recovery), holding it at 0 for period of time in the range of 0.1 ms to 1 second as defined by the fault-detect recovery constant register (FDRC registers 0x2B, 0x2C), then toggling it back to 1. This sequence is repeated as long as the fault indication exists. This feature is enabled by default but can be bypassed by setting the FDRB control bit to 1.

## 5.1.2 Configuration register B (addr 0x01)

D7	D6	D5	D4	D3	D2	D1	D0
C2IM	C1IM	Reserved	SAIFB	SAI3	SAI2	SAI1	SAI0
1	0	0	0	0	0	0	0

**Serial audio input interface format**

**Table 16. Serial audio input interface format**

Bit	R/W	RST	Name	Description
0	R/W	0	SAI0	Determines the interface format of the input serial digital audio interface.
1	R/W	0	SAI1	
2	R/W	0	SAI2	
3	R/W	0	SAI3	

**Serial data interface**

The STA333IS audio serial input interfaces with standard digital audio components and accepts a number of serial data formats. The STA333IS always acts as a slave when receiving audio input from standard digital audio components. Serial data for two channels is provided using three inputs: left/right clock LRCKI, serial clock BICKI, and serial data SDI.

Bits SAIx and bit SAIFB are used to specify the serial data format. The default serial data format is I<sup>2</sup>S, MSB first. Available formats are shown in the tables that follow.

**Serial data first bit**

**Table 17. Serial data first bit**

SAIFB	Format
0	MSB-first
1	LSB-first

**Table 18. Support serial audio input formats for MSB-first (SAIFB = 0)**

BICKI	SAI [3:0]	SAIFB	Interface format
32 * f <sub>S</sub>	0000	0	I <sup>2</sup> S 15-bit data
	0001	0	Left/right justified 16-bit data
48* f <sub>S</sub>	0000	0	I <sup>2</sup> S 16- to 23-bit data
	0001	0	Left-justified 16- to 24-bit data
	0010	0	Right-justified 24-bit data
	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
64* f <sub>S</sub>	1110	0	Right-justified 16-bit data
	0000	0	I <sup>2</sup> S 16- to 24-bit data
	0001	0	Left-justified 16- to 24-bit data
	0010	0	Right-justified 24-bit data
	0110	0	Right-justified 20-bit data
	1010	0	Right-justified 18-bit data
	1110	0	Right-justified 16-bit data



**Table 19. Supported serial audio input formats for LSB-first (SAIFB = 1)**

BICKI	SAI[3:0]	SAIFB	Interface format
32* f <sub>S</sub>	1100	1	I <sup>2</sup> S 15-bit data
	1110	1	Left/right justified 16-bit data
48* f <sub>S</sub>	0100	1	I <sup>2</sup> S 20-bit data
	1000	1	I <sup>2</sup> S 18-bit data
	1100	1	LSB-first I <sup>2</sup> S 16-bit data
	0001	1	Left-justified 24-bit data
	0101	1	Left-justified 20-bit data
	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
48* f <sub>S</sub>	0010	1	Right-justified 24-bit data
	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
64* f <sub>S</sub>	1110	1	Right-justified 16-bit data
	0000	1	I <sup>2</sup> S 24-bit data
	0100	1	I <sup>2</sup> S 20-bit data
	1000	1	I <sup>2</sup> S 18-bit data
	1100	1	LSB-first I <sup>2</sup> S 16-bit data
	0001	1	Left-justified 24-bit data
	0101	1	Left-justified 20-bit data
	1001	1	Left-justified 18-bit data
	1101	1	Left-justified 16-bit data
	0010	1	Right-justified 24-bit data
	0110	1	Right-justified 20-bit data
	1010	1	Right-justified 18-bit data
1110	1	Right-justified 16-bit data	

**Channel input mapping**

**Table 20. Channel input mapping**

Bit	R/W	RST	Name	Description
6	R/W	0	C1IM	0: processing channel 1 receives left I <sup>2</sup> S input 1: processing channel 1 receives right I <sup>2</sup> S input
7	R/W	0	C2IM	0: processing channel 2 receives left I <sup>2</sup> S input 1: processing channel 2 receives right I <sup>2</sup> S input

Each channel received via I<sup>2</sup>S can be mapped to any internal processing channel via the channel input mapping registers. This allows for flexibility in processing. The default settings of these registers map each I<sup>2</sup>S input channel to its corresponding processing channel.

**5.1.3 Configuration register C (addr 0x02)**

D7	D6	D5	D4	D3	D2	D1	D0
OCRB	Reserved	CSZ3	CSZ2	CSZ1	CSZ0	OM1	OM0
1	0	0	1	0	1	1	1

**FFX power output mode**

**Table 21. FFX power output mode**

Bit	R/W	RST	Name	Description
0	R/W	1	OM0	The FFX power output mode selects the configuration of the FFX output: 00: drop compensation 01: discrete output stage: tapered compensation 10: full-power mode 11: variable drop compensation (CSZx bits)
1	R/W	1	OM1	

**FFX compensation pulse size register**

**Table 22. FFX compensating pulse size**

Bit	R/W	RST	Name	Description
2	R/W	1	CSZ0	When OM[1:0] = 11, this register determines the size of the FFX compensating pulse from 0 to 15 clock periods: 0000: 0 ns (0 ticks) compensating pulse size 0001: 20 ns (1 tick) clock period compensating pulse size 1111: 300 ns (15 ticks) clock period compensating pulse size
3	R/W	0	CSZ1	
4	R/W	1	CSZ2	
5	R/W	0	CSZ3	