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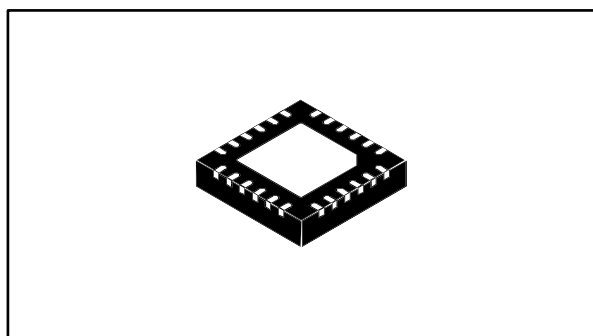
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## Autonomous USB PD controller with integrated discharge path

Datasheet - production data



### Features

- USB power delivery (PD) controller
- Type-C attach and cable orientation detection
- Single role: provider - DFP
- Full hardware solution - no software
- I<sup>2</sup>C interface + Interrupt (optional connection to MCU)
- Support all USB PD profiles: up to 5 power data objects (PDO)
- Configurable startup profiles
- Integrated V<sub>BUS</sub> voltage monitoring
- Internal and/or external V<sub>BUS</sub> discharge path
- High voltage protection
- Dual power supply (V<sub>sys</sub> and/or V<sub>DD</sub>):
  - V<sub>sys</sub> = [3.0 V; 5.5 V]
  - V<sub>DD</sub> = [4.1 V; 22 V]
- Temperature range: -40 °C up to 105 °C
- Fully compatible with:
  - USB Type-C™ rev 1.2
  - USB PD rev 2.0
  - Certification test ID 1010037

### Applications

- AC adapters and power supplies for: computer, consumer or portable consumer applications
- Smart plugs and wall adapters
- Power hubs and docking stations
- Displays
- Any Type-C source device

### Description

The STUSB4700 is a new family of USB power delivery controllers communicating over Type-C™ configuration channel pins (CC) to negotiate a given amount of power to be sourced to an inquiring consumer device.

The STUSB4700 addresses provider/DFP devices such as notebooks, tablets and AC adapters. The device can handle any connections to a UFP or DRP without any MCU attachment support, from device attachment to power negotiation, including V<sub>BUS</sub> discharge and protections.

**Table 1: Device summary table**

Order code	Description	Package	Marking
STUSB4700QTR	Autonomous USB PD controller (provider)	QFN24 EP (4x4 mm)	4700

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# 1 Functional description

The STUSB4700 is an autonomous USB power delivery controller optimized as a provider. It offers an open drain GPIO interface to make direct interconnection with a power regulation stage.

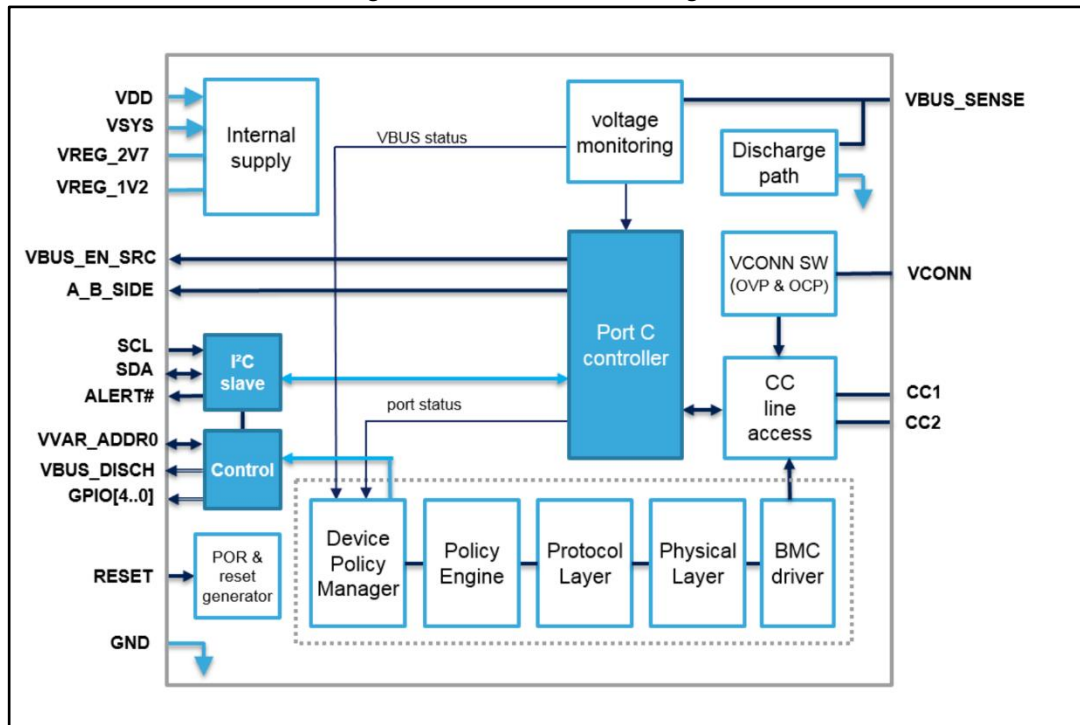
The STUSB4700 offers the benefits of a full hardware USB PD stack allowing robust and safe USB PD negotiation in line with USB PD standard. The STUSB4700 is ideal for provider applications in which digital or software intelligence is limited or missing.

The STUSB4700 main functions are:

- Detect the connection between two USB ports (attach detection)
- Establish a valid host to device connection
- Discover and configure  $V_{BUS}$ : Type-C low, medium or high current mode
- Resolve cable orientation
- Negotiate a USB power delivery contract with a PD capable device
- Configure the power source accordingly
- Monitor  $V_{BUS}$ , manage transitions, handle protections and ensure user and device safety

Additionally, the STUSB4700 offers 5 customizable power data objects (PDOs), 5 general purpose I/Os, an integrated discharge path, and is natively robust to high voltage peaks.

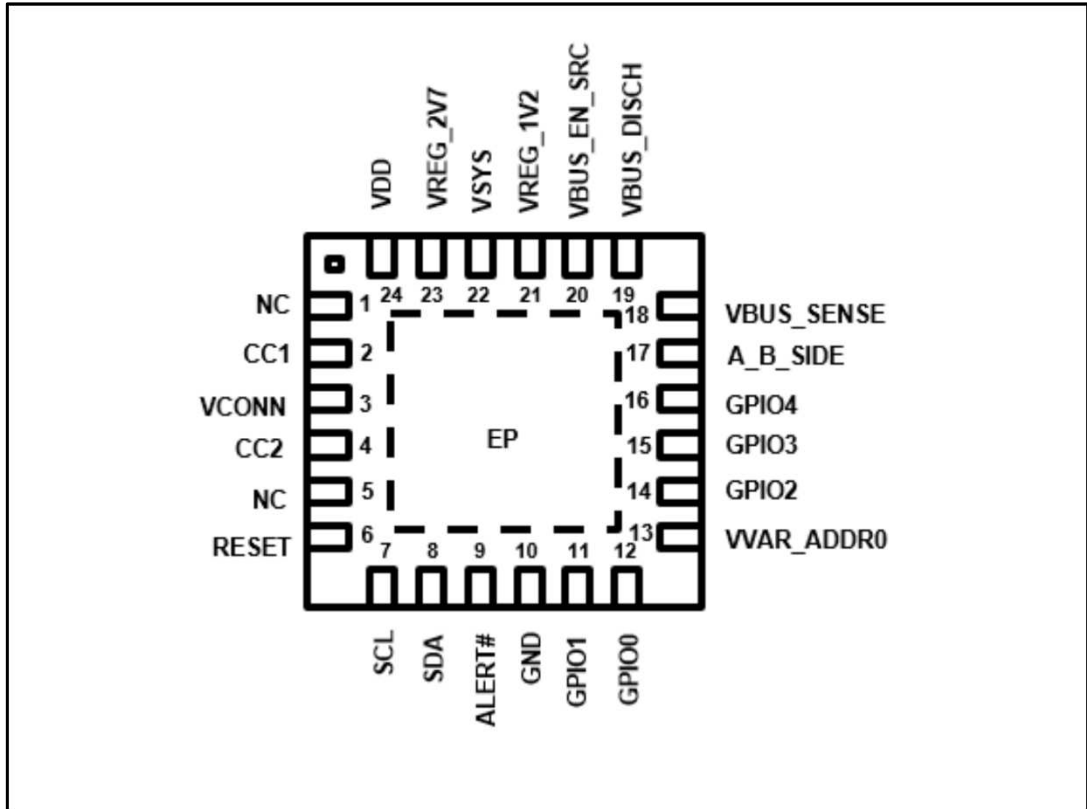
Figure 1: Functional block diagram



## 2 Inputs/outputs

### 2.1 Pinout

Figure 2: STUSB4700 pin connections (top view)



### 2.2 Pin list

Table 2: Pin functions list

Pin	Name	Type	Description	Connection
1	NC	NC	Not connected	
2	CC1	20 V analog IO	Configuration channel 1	Type-C receptacle A5
3	VCONN	PWR	Power input for active plug	5 V power source
4	CC2	20 V analog IO	Configuration channel 2	Type-C receptacle B5
6	RESET	DI	Reset input (active high)	
7	SCL	DI	I <sup>2</sup> C clock	To I <sup>2</sup> C master – Ext. pull-up
8	SDA	DI/OD	I <sup>2</sup> C data input/output – active low open drain	To I <sup>2</sup> C master – Ext. pull-up
9	ALERT#	OD	I <sup>2</sup> C interrupt – active low open drain	To I <sup>2</sup> C master – Ext. pull-up
10	GND	Power	Ground	
11	GPIO1	OD	General purpose I/O #1	

Pin	Name	Type	Description	Connection
12	GPIO0	OD	General purpose I/O #0	
13	VVAR_ADDR0	Analog	Variable voltage output	
14	GPIO2	OD	General purpose I/O #2	
15	GPIO3	OD	General purpose I/O #3	
16	GPIO4	OD	General purpose I/O #4	
17	A_B_SIDE	OD	Cable orientation - active low open drain	USB SuperSpeed mux select – Ext. pull-up
18	VBUS_SENSE	20 V AI	V <sub>BUS</sub> voltage monitoring and discharge path	From V <sub>BUS</sub>
19	VBUS_DISCH	Output	External output discharge path	
20	VBUS_EN_SRC	20 V OD	V <sub>BUS</sub> source power path enable – active low open drain	To switch or power system – Ext. pull-up
21	VREG_1V2	Analog	1.2 V regulator output	1 μF typ decoupling capacitor
22	VSYS	Power	System power supply	System low power (connect to ground if not used)
23	VREG_2V7	Analog	2.7 V regulator output	1 μF typ decoupling capacitor
24	VDD	20 V power	Main power supply (USB power line)	From V <sub>BUS</sub> (system side)
-	EP	Exposed pad	Exposed pad is connected to ground	To Ground

Table 3: Legend

Type	Description
D	Digital
A	Analog
O	Output pad
I	Input pad
IO	Bidirectional pad
OD	Open drain output
PD	Pull-down
PU	Pull-up
PWR	Power supply
GND	Ground

## 2.3 Pin description

### 2.3.1 CC1 / CC2

CC1 and CC2 are the configuration channel pins used for connection and attachment detection, plug orientation determination and system configuration management across USB Type-C cable. CC1/CC2 are HiZ during reset.

### 2.3.2 RESET

Active high reset. This pin resets all analog signals, states machine and reloads configuration.

### 2.3.3 I2C interface pins

Table 4: I2C interface pins list

Name	Description
SCL	I <sup>2</sup> C clock – need external pull-up
SDA	I <sup>2</sup> C data – need external pull-up
ALERT#	I <sup>2</sup> C interrupt – need external pull-up

### 2.3.4 A\_B\_SIDE

This output pin provides cable orientation. It is used to establish USB SuperSpeed signals routing. The cable orientation is also provided by an internal I<sup>2</sup>C register. This signal is not required in case of USB 2.0 support or in case of supply only.

Table 5: USB Data mux select

Value	CC pin position
HiZ	CC pin detected on CC1 (A5)
0	CC pin detected on CC2 (B5)

### 2.3.5 VBUS\_SENSE

This input pin is used to sense V<sub>BUS</sub> presence, monitor V<sub>BUS</sub> voltage and discharge V<sub>BUS</sub> on USB Type-C receptacle side.

### 2.3.6 VBUS\_EN\_SRC

In Source power role, this pin allows enabling of the outgoing V<sub>BUS</sub> power when the connection to a Sink is established and V<sub>BUS</sub> is in the valid operating range. The open drain output allows to drive directly a PMOS transistor. The logic value of the pin is also advertised in a dedicated I<sup>2</sup>C register bit.

### 2.3.7 V<sub>sys</sub>

V<sub>sys</sub> is the low voltage power supply from the system (if any). V<sub>sys</sub> connection is optional, and can be connected directly to a single cell Lithium battery or a system power supply delivering 3.3 V or 5 V. If not used, it is recommended to connect to GND.

### 2.3.8 V<sub>DD</sub>

V<sub>DD</sub> is the main power supply for applications powered by V<sub>BUS</sub>.



This pin can be used to sense the voltage level of the main power supply providing  $V_{BUS}$ . It allows to consider independently UVLO and OVLO voltage thresholds on VDD pin as additional conditions to enable the  $V_{BUS}$  power path through  $VBUS\_EN\_SRC$  pin.

### 2.3.9 GND

Ground.

### 2.3.10 VVAR\_ADDR0

At startup, this pin is latched to set I<sup>2</sup>C device address 0 bit. During operation, this output can be used as an analog voltage output to control the power management unit. Analog value is one tenth of the requested  $V_{BUS}$  value. This function can be enabled through appropriate NVM configuration.

### 2.3.11 GPIO [4:0]

Table 6: GPIO0 (pin #12) configuration

Select	Value	Configuration	Comments
GPIO0_sel	11b <sup>(NVM)</sup>	GPIO0 = Sel_PDO2	Active Low

Table 7: GPIO1 (pin #11) configuration

Select	Value	Configuration	Comments
GPIO1_sel	11b <sup>(NVM)</sup>	GPIO1 = Sel_PDO3	Active Low

Table 8: GPIO2 (pin #14) – GPIO3 (pin #15) – GPIO4 (pin #16) configuration

Select	Value	Configuration	Comments
GPIO234_sel[1:0]	11b <sup>(NVM)</sup>	GPIO2 = Sel_PDO4	Active Low
		GPIO3 = Sel_PDO5	Active Low
		GPIO4 = Attached	Active Low

Other configurations are available (please contact our customer support).

### 2.3.12 VREG2V7

This pin is used only for external decoupling of 2.7 V internal regulator.  
Recommended decoupling capacitor: 1  $\mu$ F typ. (0.5  $\mu$ F min; 10  $\mu$ F max).  
This pin must not be used to supply any external component.

### 2.3.13 VREG1V2

This pin is used for external decoupling of 1.2 V internal regulator.  
Recommended decoupling capacitor: 1  $\mu$ F typ. (0.5  $\mu$ F min; 10  $\mu$ F max).

### 2.3.14 VBUS\_DISCH

Control signal for external  $VBUS\_DISCH$  path.

### 2.3.15 VCONN

This power input is connected to a power source that can be a 5 V power supply, or a lithium battery. It is used to supply e-marked cables. It is internally connected to power

switches that are protected against short-circuit and overvoltage. When a valid source-to-sink connection is determined and  $V_{\text{CONN}}$  power switches enabled,  $V_{\text{CONN}}$  is provided by the Source to the unused CC pin.

## 3 Block descriptions

### 3.1 CC interface

The STUSB4700 controls the connection to the configuration channel (CC) pins, CC1 and CC2, through two main blocks, the CC lines interface block and the CC control logic block.

The CC lines interface block is used to:

- Configure the termination mode on the CC pins relative to the power mode supported, i.e. pull-up for source power role
- Monitor the CC pin voltage values relative to the attachment detection thresholds
- Configure  $V_{CONN}$  on the unconnected CC pin when required
- Protect the CC pins against over voltage

The CC control logic block is used to:

- Execute the Type-C FSM relative to the Type-C power mode supported
- Determine the electrical state for each CC pins relative to the detected thresholds
- Evaluate the conditions relative to the CC pin states and  $V_{BUS}$  voltage value to transition from one state to another in the Type-C FSM
- Detect and establish a valid source-to-sink connection
- Determine the attached mode: source, accessory
- Determine cable orientation to allow external routing of the USB super speed data
- Manage  $V_{BUS}$  power capability: USB default, Type-C medium or Type-C high current mode
- Handle hardware faults

The CC control logic block implements the Type-C FSM's corresponding to source power role with accessory support.

### 3.2 BMC

This block is the physical link between USB PD protocol layer and CC pin. In TX mode, it converts the data into biphase mark coding (BMC), and drives the CC line to correct voltages. In RX mode, it recovers BMC data from the CC line, and converts to baseband signaling for the protocol layer.

### 3.3 Protocol layer

The protocol layer has the responsibility to manage the messages from/to the physical layer. It automatically manages the protocol receive timeouts, the message counter, the retry counter and the GoodCRC messages.

It communicates with the internal policy engine.

### 3.4 Policy engine

The policy engine implements the power negotiation with the connected device according to its source role, it implements all states machine that controls protocol layer forming and scheduling the messages.

The policy engine uses the protocol layer to send/receive messages.

The policy engine interprets the device policy manager's input in order to implement policy for port and directs the protocol layer to send appropriate messages.

### 3.5 Device policy manager

The device policy manager is managing the power resources.

### 3.6 V<sub>BUS</sub> power path control

#### 3.6.1 V<sub>BUS</sub> monitoring

The V<sub>BUS</sub> monitoring block supervises (from the VBUS\_SENSE input pin) the V<sub>BUS</sub> voltage on the USB Type-C receptacle side.

This block is used to check that V<sub>BUS</sub> is within a valid voltage range:

- To establish a valid source-to-sink connection according to USB Type-C standard specification
- To enable safely the V<sub>BUS</sub> power path through VBUS\_EN\_SRC pin

It allows detection of unexpected V<sub>BUS</sub> voltage conditions such as undervoltage or overvoltage relative to the valid V<sub>BUS</sub> voltage range. When such conditions occur, the STUSB4700 reacts as follows:

- At attachment, it prevents the source-to-sink connection and the V<sub>BUS</sub> power path assertion
- After attachment, it deactivates the source-to-sink connection and disables the V<sub>BUS</sub> power path. The device goes into error recovery state.

The V<sub>BUS</sub> voltage value is automatically adjusted at attachment and at each PDO transition. The monitoring is then disabled during T\_PDO\_transition (default 280 ms changed through NVM programming). Additionally, if a transition occurs to a lower voltage, the discharge path is activated during this time.

The valid V<sub>BUS</sub> voltage range is defined from the V<sub>BUS</sub> nominal voltage by a high threshold voltage and a low threshold voltage whose minimal values are respectively V<sub>BUS</sub>+5% and V<sub>BUS</sub>-5%. The nominal threshold limits can be shifted by a fraction of V<sub>BUS</sub> from +1% to +15% for the high threshold voltage and from -1% to -15% for the low threshold voltage. This means the threshold limits can vary from V<sub>BUS</sub>+5% to V<sub>BUS</sub>+20% for the high limit and from V<sub>BUS</sub>-5% to V<sub>BUS</sub>-20% for the low limit.

The threshold limits are preset by default in the NVM with different shift coefficients (see [Section 8.3: "Electrical and timing characteristics"](#)). The threshold limits can be changed independently through NVM programming (see [Section 4: "User-defined startup configuration"](#)) and also by software during attachment through the I<sup>2</sup>C interface (see [Section 6: "I<sup>2</sup>C register map"](#)).

#### 3.6.2 V<sub>BUS</sub> discharge

The monitoring block handles also the internal V<sub>BUS</sub> discharge path connected to the VBUS\_SENSE input pin. The discharge path is activated at detachment, or when the device goes into the error recovery state (see [Section 3.8: "Hardware fault management"](#)).

The V<sub>BUS</sub> discharge path is enabled by default in the NVM and can be disabled through NVM programming only (see [Section 4: "User-defined startup configuration"](#)). Discharge time duration (T\_PDO\_transition and T\_Transition to 0 V) are also preset by default in the NVM (see [Section 8.3: "Electrical and timing characteristics"](#)). The discharge time duration can be changed through NVM programming (see [Section 4: "User-defined startup configuration"](#)) and also by software through the I<sup>2</sup>C interface (see [Section 6: "I<sup>2</sup>C register map"](#)).

### 3.6.3 V<sub>BUS</sub> power path assertion

The STUSB4700 can control the assertion of the V<sub>BUS</sub> power path on USB Type-C port, directly or indirectly, through VBUS\_EN\_SRC pin.

The following table summarizes the configurations and the conditions that determine the logic value of VBUS\_EN\_SRC pin during system operation.

**Table 9: Conditions for VBUS power path assertion**

Pin	Electrical value	Operation conditions			Comment
		Attached state	V <sub>DD</sub> monitoring	V <sub>BUS</sub> monitoring	
VBUS_EN_SRC	0	Attached.SRC	VDD > UVLO if VDD_UVLO enabled and/or VDD < OVLO if VDD_OVLO enabled	V <sub>BUS</sub> within valid voltage range if VBUS_VALID_RANGE enabled or V <sub>BUS</sub> > UVLO if VBUS_VALID_RANGE disabled	The signal is asserted only if all the valid operation conditions are met.
		UnorientedDebug Accessory.SRC			
		OrientedDebug Accessory.SRC			
HiZ		Any other state	VDD < UVLO if VDD_UVLO enabled and/or VDD > OVLO if VDD_OVLO enabled	V <sub>BUS</sub> is out of valid voltage range if VBUS_VALID_RANGE enabled or V <sub>BUS</sub> < UVLO if VBUS_VALID_RANGE disabled	The signal is de-asserted when at least one non-valid operation condition is met.



Activation of the UVLO and OVLO threshold detections can be done through NVM programming (see [Section 4: "User-defined startup configuration"](#)) and also by software through the I<sup>2</sup>C interface (see [Section 6: "I<sup>2</sup>C register map"](#)). When the UVLO and/or OVLO threshold detection is activated, the VBUS\_EN\_SRC pin is asserted only if the device is attached and the valid threshold conditions on V<sub>DD</sub> are met. Once the VBUS\_EN\_SRC pin is asserted, the V<sub>BUS</sub> monitoring is done on VBUS\_SENSE pin instead of the V<sub>DD</sub> pin.

## 3.7 High voltage protection

The STUSB4700 can be safely used in systems or connected to systems that handle high voltage on the V<sub>BUS</sub> power path. The device integrates an internal circuitry on the CC pins that tolerates high voltage and ensures a protection up to 22 V in case of unexpected short circuit with V<sub>BUS</sub> or in case of connection to a device supplying high voltage on V<sub>BUS</sub>.

## 3.8 Hardware fault management

The STUSB4700 handles hardware fault conditions related to the device itself and the V<sub>BUS</sub> power path during system operation.

When such conditions occur, the circuit goes into a transient error recovery state named ErrorRecovery in the Type-C FSM. When entering in this state, the device de-asserts the V<sub>BUS</sub> power path by disabling the VBUS\_EN\_SRC pin, and it removes the terminations from the CC pins during several tens of milliseconds. Then, it transitions to the unattached source state.

The STUSB4700 goes into error recovery state when at least one condition listed below is met:

- If an overtemperature is detected, the “THERMAL\_FAULT” flag is asserted.
- If an internal pull-up voltage on CC pins is below UVLO threshold, the “VPU\_VALID” flag is asserted.
- If an overvoltage is detected on the CC pins, the “VPU\_OVP\_FAULT” flag is asserted.
- If the  $V_{BUS}$  voltage is out of the valid voltage range during attachment, the “VBUS\_VALID” flag is asserted.
- If an undervoltage is detected on the  $V_{DD}$  pin during attachment when UVLO detection is enabled, the “VDD\_UVLO\_DISABLE” flag is asserted.
- If an overvoltage is detected on the  $V_{DD}$  pin during attachment when OVLO detection is enabled, the “VDD\_OVLO\_DISABLE” flag is asserted.

The I<sup>2</sup>C register bits mentioned above in quotes give either the state of the hardware fault when it occurs or the setting condition to detect the hardware fault.

## 3.9 Accessory mode detection

The STUSB4700 supports the detection of audio accessory mode and debug accessory mode as defined in the USB Type-C standard specification source power role with accessory support.

### 3.9.1 Audio accessory mode detection

The STUSB4700 detects an audio accessory device when both the CC1 and CC2 pins are pulled down to ground by a  $R_a$  resistor from the connected device. The audio accessory detection is advertised through the CC\_ATTACHED\_MODE bits of the I<sup>2</sup>C register CC\_CONNECTION\_STATUS.

### 3.9.2 Debug accessory mode detection

The STUSB4700 detects a connection to a debug and test system (DTS) when it operates either in sink power role or source power role. The debug accessory detection is advertised by the DEBUG1 and DEBUG2 pins as well as through the CC\_ATTACHED\_MODE bits of the I<sup>2</sup>C register CC\_CONNECTION\_STATUS.

In source power role, a debug accessory device is detected when both the CC1 and CC2 pins are pulled down to ground by a  $R_d$  resistor from the connected device. The orientation detection is performed in two steps as described in the table below. The DEBUG2 pin is asserted to advertise the DTS detection and the A\_B\_SIDE pin indicates the orientation of the connection. The orientation detection is advertised through the TYPEC\_FSM\_STATE bits of the I<sup>2</sup>C register CC\_OPERATION\_STATUS.

## 4 User-defined startup configuration

### 4.1 Parameter overview

The STUSB4700 has a set of user-defined parameters that can be customized by NVM re-programming and/or by software through I<sup>2</sup>C interface. It allows changing the preset configuration of USB Type-C and PD interface and to define a new configuration to meet specific customer requirements addressing various applications, use cases or specific implementations.

The NVM re-programming overrides the initial default setting to define a new default setting that will be used at power-up or after a reset. The default value is copied at power-up, or after a reset, from the embedded NVM into dedicated I<sup>2</sup>C register bits. The NVM re-programming is possible few times with a customer password.

**Table 10: PDO configurations in NVM**

Feature	Parameter	Value	Default
PDO1	Voltage	5 V	5 V
	Current	Configurable – defined by PDO1_I [3:0]	3 A
PDO2	Voltage	Configurable – defined by PDO2_V [1:0]	9 V
	Current	Configurable – defined by PDO2_I [3:0]	3 A
PDO3	Voltage	Configurable – defined by PDO3_V [1:0]	12 V
	Current	Configurable – defined by PDO3_I [3:0]	3 A
PDO4	Voltage	Configurable – defined by PDO4_V [1:0]	15 V
	Current	Configurable – defined by PDO4_I [3:0]	3 A
PDO5	Voltage	Configurable – defined by PDO5_V [1:0]	20 V
	Current	Configurable – defined by PDO5_I [3:0]	2.25 A

When a default value is changed during system boot by software, the new settings apply as long as STUSB4700 is operating and until it is changed again. But after power-off and power-up, or after a hardware reset, STUSB4700 takes back default values defined in the NVM.

### 4.2 PDO – voltage configuration in NVM

PDO2\_V [1:0], PDO3\_V [1:0], PDO4\_V [1:0] and PDO5\_V [1:0] can be configured with the following values:

**Table 11: PDO NVM voltage configuration**

Value	Configuration
2b00	9 V
2b01	15 V
2b10	PDO_FLEX_V1
2b11	PDO_FLEX_V2

PDO\_FLEX\_V1 and PDO\_FLEX\_V2 are defined in a specific 10-bit register, value being expressed in 50 mV units.

For instance:

- PDO\_FLEX\_V1 = 10b0100100010 → 14.5 V
- PDO\_FLEX\_V2 = 10b0110000110 → 19.5 V

### 4.3 PDO – current configuration in NVM

PDO1\_I [3:0], PDO2\_I [3:0], PDO3\_I [3:0], PDO4\_I [3:0] and PDO5\_I [3:0] can be configured with the following fixed values:

**Table 12: PDO NVM current configuration**

Value	Configuration
4b0000	PDO_FLEX_I
4b0001	1.50 A
4b0010	1.75 A
4b0011	2.00 A
4b0100	2.25 A
4b0101	2.50 A
4b0110	2.75 A
4b0111	3.00 A
4b1000	3.25 A
4b1001	3.50 A
4b1010	3.75 A
4b1011	4.00 A
4b1100	4.25 A
4b1101	4.50 A
4b1110	4.75 A
4b1111	5.00 A

PDO\_FLEX\_I is defined in a specific 10-bit register, value being expressed in 10 mA units. For instance:

- PDO\_FLEX\_I = 10b0011100001 → 2.25 A

### 4.4 Monitoring configuration in NVM

- T\_PDO\_Transition can be configured from 20 to 300 ms by increments of 20 ms (0 is not recommended)
- T\_Transition\_to\_0V can be configured from 84 to 1260 ms by increments of 84 ms (0 is not recommended)
- Vshift\_High can be configured from (5 to 20%)
- Vshift\_Low can be configured from (5 to 20%)

### 4.5 Discharge configuration in NVM

Enable discharge

Internal discharge

Reverse



## 5 I<sup>2</sup>C interface

### 5.1 Read and write operations

The I<sup>2</sup>C interface is used to configure, control and read the status of the device. It is compatible with the Philips I<sup>2</sup>C Bus® (version 2.1). The I<sup>2</sup>C is a slave serial interface based on two signals:

- SCL - serial clock line: input clock used to shift data
- SDA - serial data line: input/output bidirectional data transfers

A filter rejects the potential spikes on the bus data line to preserve data integrity.

The bidirectional data line supports transfers up to 400 Kbit/s (fast mode). The data are shifted to and from the chip on the SDA line, MSB first.

The first bit must be high (START) followed by the 7-bit device address and the read/write control bit.

Eight two 7-bit device addresses are available for STUSB4700 thanks to external programming of DevADDR0, DevADDR1 and/or DevADDR2 through ADDR0, ADDR1/ADDR2 pin setting. It allows to connect two up to 8 STUSB4700 devices on the same I<sup>2</sup>C bus.

ADDR are not available for all configurations.

Device address format:

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
DevADDR6	DevADDR5	DevADDR4	DevADDR3	DevADDR2	DevADDR1	DevADDR0	R/W
0	1	0	1	ADDR2	ADDR1	ADDR0	0/1

Register address format:

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
RegADDR7	RegADDR6	RegADDR5	RegADDR4	RegADDR3	RegADDR2	RegADDR1	RegADDR0

Register data format:

Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
DATA7	DATA6	DATA5	DATA4	DATA3	DATA2	DATA1	DATA0

Figure 3: Read operation

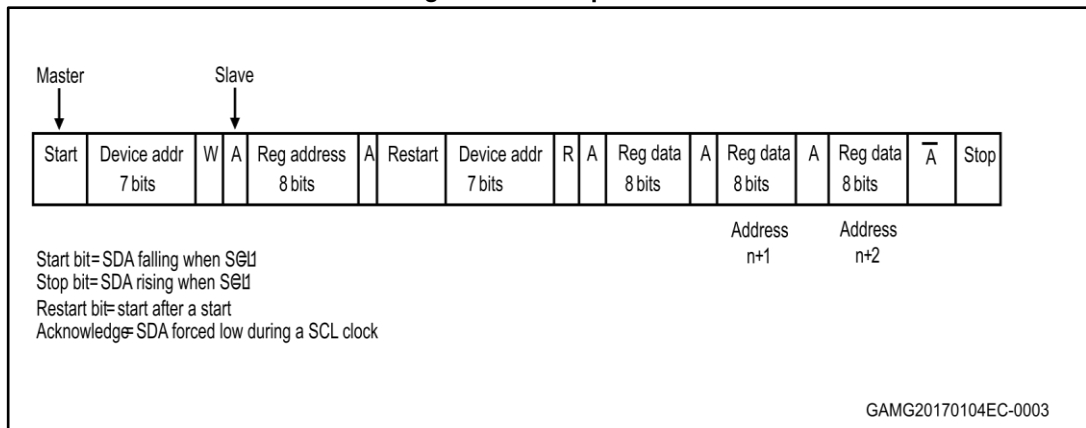
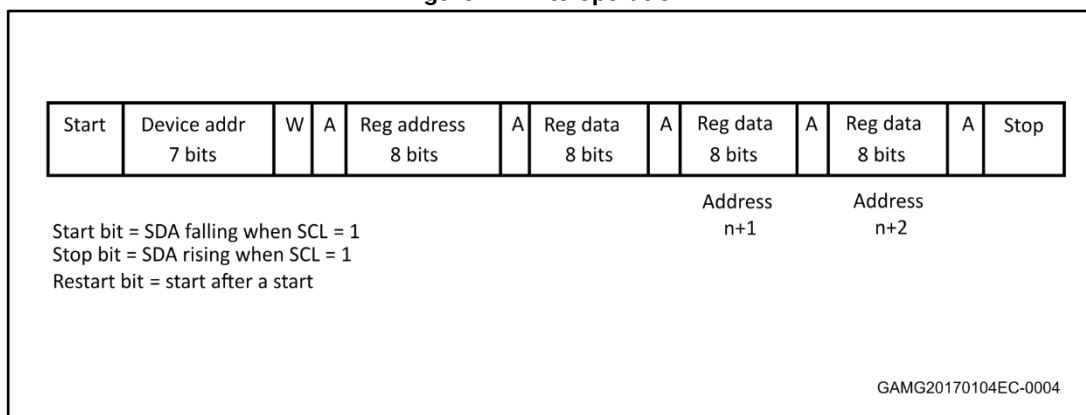


Figure 4: Write operation



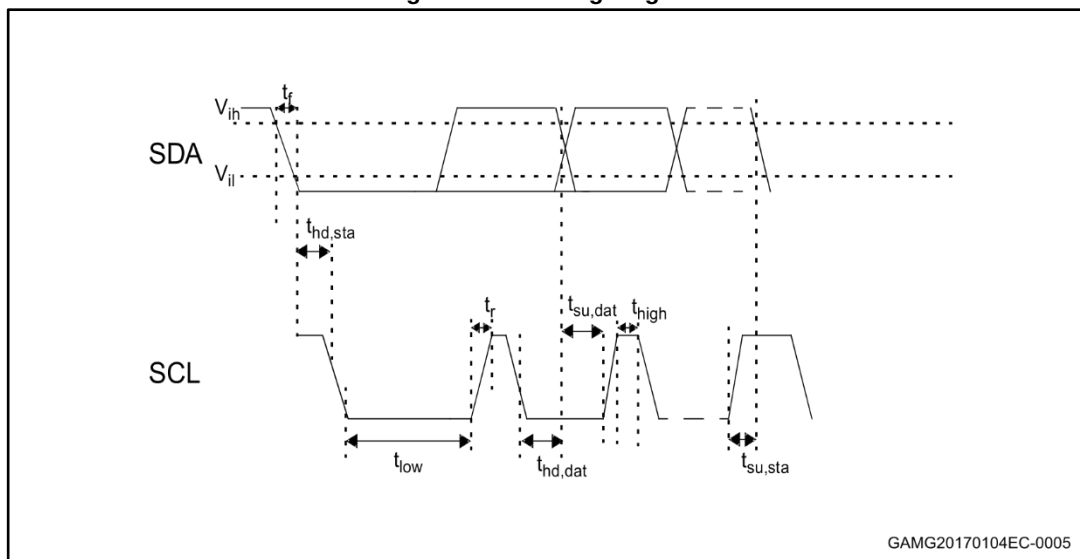
## 5.2 Timing specifications

The device uses a standard slave I<sup>2</sup>C channel at speed up to 400 kHz.

Table 13: I<sup>2</sup>C timing parameters - VDD = 5 V

Symbol	Parameter	Min	Typ	Max	Unit
F <sub>scl</sub>	SCL clock frequency	0	-	400	kHz
t <sub>hd,sta</sub>	Hold time (repeated) START condition	0.6	-	-	μs
t <sub>low</sub>	LOW period of the SCL clock	1.3	-	-	μs
t <sub>high</sub>	HIGH period of the SCL clock	0.6	-	-	μs
t <sub>su,dat</sub>	Setup time for repeated START condition	0.6	-	-	μs
t <sub>hd,dat</sub>	Data hold time	0.04	-	0.9	μs
t <sub>su,dat</sub>	Data setup time	100	-	-	μs
t <sub>r</sub>	Rise time of both SDA and SCL signals	20 + 0.1 C <sub>b</sub>	-	300	ns
t <sub>f</sub>	Fall time of both SDA and SCL signals	20 + 0.1 C <sub>b</sub>	-	300	ns
t <sub>su,sto</sub>	Setup time for STOP condition	0.6	-	-	μs
t <sub>buf</sub>	Bus free time between a STOP and START condition	1.3	-	-	μs
C <sub>b</sub>	Capacitive load for each bus line	-	-	400	pF

Figure 5: I<sup>2</sup>C timing diagram



## 6 I<sup>2</sup>C register map

Table 14: STUSB4700 register map overview

Address	Register name	Access	Description
00h to 0Ah	Reserved	RO	Do not use
0Bh	ALERT_STATUS	RC	Alert register linked to transition registers
0Ch	ALERT_STATUS_MASK_CTRL	R/W	Interrupt mask on ALERT_STATUS register
0Dh	CC_CONNECTION_STATUS_TRANS	RC	Alerts on transition in CC_CONNECTION_STATUS register
0Eh	CC_CONNECTION_STATUS	RO	CC connection status
0Fh	MONITORING_STATUS_TRANS	RC	Alerts on transition in MONITORING_STATUS register
10h	MONITORING_STATUS	RO	Gives status on V <sub>BUS</sub> voltage monitoring
11h	Reserved	RO	Do not use
12h	HW_FAULT_STATUS_TRANS	RC	Alerts on transition in HW_FAULT_STATUS register
13h	HW_FAULT_STATUS	RO	Hardware faults status
14h to 17h	Reserved	RO	Do not use
18h	CC_CAPABILITY_CTRL	R/W	Allows to change the CC capabilities
19h to 22h	Reserved	RO	Do not use
23h	RESET_CTRL	R/W	Controls the device reset by software
24h	Reserved	RO	Do not use
25h	VBUS_DISCHARGE_TIME_CTRL	R/W	Parameters defining V <sub>BUS</sub> discharge time
26h	VBUS_DISCHARGE_CTRL	R/W	Controls the V <sub>BUS</sub> discharge path
27h	VBUS_ENABLE_STATUS	RO	V <sub>BUS</sub> power path activation status
2Eh	VBUS_MONITORING_CTRL	R/W	Allows to change the monitoring conditions of V <sub>BUS</sub> voltage
19h to 1Eh	Reserved	RO	Do not use
71h	SRC_PDO1	R/W	PDO1 capabilities configuration
75h	SRC_PDO2	R/W	PDO2 capabilities configuration
79h	SRC_PDO3	R/W	PDO3 capabilities configuration
7Dh	SRC_PDO4	R/W	PDO4 capabilities configuration
81h	SRC_PDO5	R/W	PDO5 capabilities configuration
91h	SRC_RDO	RO	PDO request status

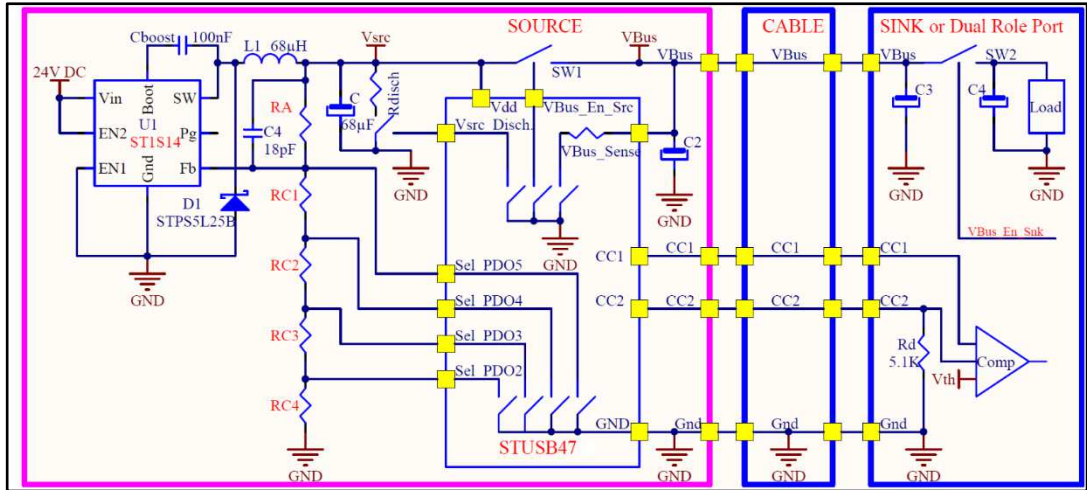
Table 15: Register access legend

Access code	Expanded name	Description
RO	Read only	Register can be read only
R/W	Read / Write	Register can be read or written
RC	Read and clear	Register can be read and is cleared after read

# 7 Typical use cases

## 7.1 Power supply – buck topology

Figure 6: Power supply - buck topology



The STUSB4700 offers the possibility to have up to 5 PDOs using (GPIO0 to GPIO3).

For example PDO1:5V 3A (no GPIO grounded), PDO2:9V 3A (GPIO0 to GND), PDO3:15V 3A (GPIO1 to GND).

Depending on the contract negotiated between source and sink V<sub>BUS</sub> voltage can go up to 20 V.

$$V_{BUS} = V_{ref} \times (1 + R_{1p} / (R_1 + R_2 + R_3 + R_4 + R_5))$$

Table 16: Resistor value

PDO	V <sub>OUT</sub>	Computation	Resistor value (ohm)
–	–	R <sub>1p</sub>	200 k
5	20	$R_1 = \frac{R_{1p} \cdot 1.24}{V_{OUT} - 1.24}$	13 k
4	15	$R_2 = \frac{R_{1p} \cdot 1.24}{V_{OUT} - 1.24} - R_1$	9.53 k
3	12	$R_3 = \frac{R_{1p} \cdot 1.24}{V_{OUT} - 1.24} - R_1 - R_2$	41.2 k
2	9	$R_4 = \frac{R_{1p} \cdot 1.24}{V_{OUT} - 1.24} - R_1 - R_2 - R_3$	9.53 k
1	5	$R_5 = \frac{R_{1p} \cdot 1.24}{V_{OUT} - 1.24} - R_1 - R_2 - R_3 - R_4$	41.2 k

## 7.2 Power supply – flyback topology

The STUSB4700 offers the possibility to have up to 5 PDOs using GPIO0 to GPIO3.

For example PDO1( 5 V; 3 A) (no Sel\_PDO grounded), PDO2 (9 V; 3 A) (GPIO0 to GND), PDO3(15 V; 3 A) (GPIO1 to GND).

Figure 7: Flyback topology

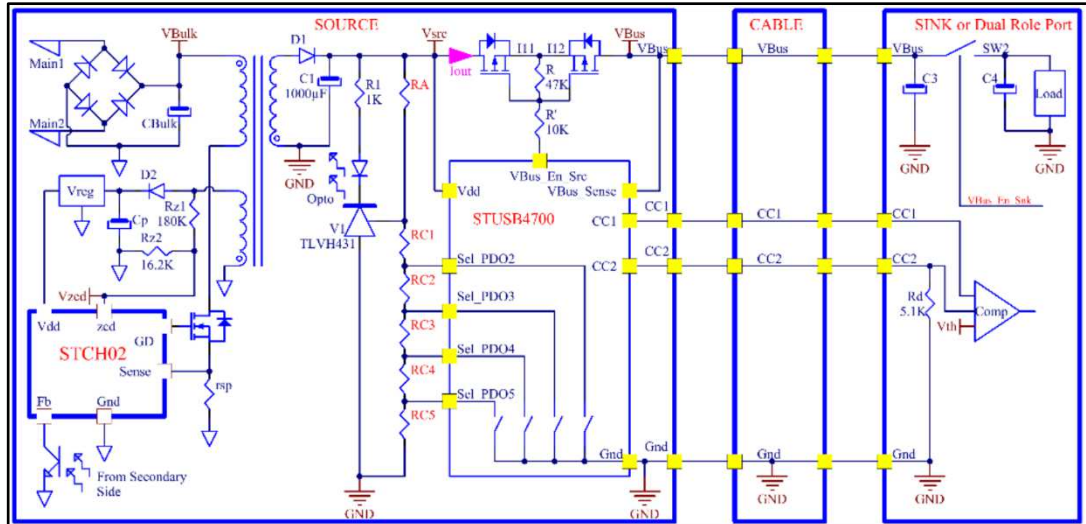


Table 17: Resistor value

PDO	Vout	Resistor	Resistor value (Ω)
–	–	R <sub>4</sub>	200 k
–	–	R <sub>5</sub>	13.2 k
5	20	R <sub>GP3</sub>	0
4	15	R <sub>GP2</sub>	5.36 k
3	12	R <sub>GP1</sub>	12.1 k
2	9	R <sub>GP0</sub>	29.4 k
1	5	R <sub>6</sub>	53.7 k

## 8 Electrical characteristics

### 8.1 Absolute maximum rating

All voltages are referenced to GND.

Table 18: Absolute maximum rating

Symbol	Parameter	Value	Unit
V <sub>DD</sub>	Supply voltage	28	V
V <sub>SYS</sub>	Supply voltage on V <sub>SYS</sub> pin	6	V
V <sub>CC1</sub> , V <sub>CC2</sub>	High voltage on CC pins	22	V
V <sub>VBUS_EN_SRC</sub> V <sub>VBUS_SENSE</sub>	High voltage on V <sub>BUS</sub> pins	28	V
V <sub>SCL</sub> , V <sub>SDA</sub> V <sub>ALERT#</sub> V <sub>RESET</sub> V <sub>A_B_SIDE</sub>	Operating voltage on I/O pins	-0.3 to 6	V
V <sub>CONN</sub>	V <sub>CONN</sub> voltage	6	V
T <sub>STG</sub>	Storage temperature	-55 to 150	°C
T <sub>J</sub>	Maximum junction temperature	145	°C
ESD	HBM	4	kV
	CDM	1.5	

### 8.2 Operating conditions

Table 19: Operating conditions

Symbol	Parameter	Value	Unit
V <sub>DD</sub>	Supply voltage	4.1 to 22	V
V <sub>SYS</sub>	Supply voltage on V <sub>SYS</sub> pin	3.0 to 5.5	V
V <sub>CC1</sub> , V <sub>CC2</sub>	CC pins <sup>(1)</sup>	-0.3 to 5.5	V
V <sub>VBUS_EN_SRC</sub> V <sub>VBUS_DISCH</sub> V <sub>VBUS_SENSE</sub>	High voltage pins	0 to 22	V
V <sub>SCL</sub> , V <sub>SDA</sub> V <sub>ALERT#</sub> V <sub>RESET</sub> V <sub>A_B_SIDE</sub>	Operating voltage on I/O pins	0 to 4.5	V
V <sub>CONN</sub>	V <sub>CONN</sub> voltage	2.7 to 5.5	V
I <sub>CONN</sub>	V <sub>CONN</sub> rated current (default = 0.35 A)	0.1 to 0.6	A
T <sub>A</sub>	Operating temperature	-40 to 105	°C

**Notes:**

<sup>(1)</sup>Transient voltage on CC1 and CC2 pins are allowed to go down to -0.3 during BMC communication from connected devices.



### 8.3 Electrical and timing characteristics

Unless otherwise specified:  $V_{DD} = 5\text{ V}$ ,  $T_A = +25\text{ °C}$ , all voltages are referenced to GND.

Table 20: Electrical characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DD(SRC)}$	Current consumption	Device Idle as SOURCE (not connected, no communication)				
		$V_{SYS}$ @ 3.3 V	–	158	–	$\mu\text{A}$
		$V_{DD}$ @ 5.0 V	–	188	–	$\mu\text{A}$
$I_{STDBY}$	Standby current consumption	Device standby (not connected, low power)				
		$V_{SYS}$ @ 3.3 V	–	33	–	$\mu\text{A}$
		$V_{DD}$ @ 5.0 V	–	53	–	$\mu\text{A}$
CC1 and CC2 pins						
$I_{P-USB}$	CC current sources	CC pin voltage $V_{CC} = -0.3$ to 2.6 V $-40^\circ < T_A < +105^\circ$	-20%	80	+20%	$\mu\text{A}$
$I_{P-1.5}$			-8%	180	+8%	$\mu\text{A}$
$I_{P-3.0}$			-8%	330	+8%	$\mu\text{A}$
$V_{CCO}$	CC open pin voltage	CC unconnected, $V_{DD}=3.0$ to 5.5 V	2.75	–	–	V
$R_d$	CC pull-down resistors	$-40^\circ < T_A < +105^\circ$	-10%	5.1	+10%	k $\Omega$
$V_{CCDB-1.5}$ $V_{CCDB-3.0}$	CC pin voltage in dead battery condition	External $I_P=180\text{ }\mu\text{A}$ applied into CC	–	–	1.2	V
		External $I_P=330\text{ }\mu\text{A}$ applied into CC ( $V_{DD} = 0$ , dead battery function enabled)	–	–	2	V
$R_{INCC}$	CC input impedance	Pull-up and pull-down resistors off	200	–	–	k $\Omega$
$V_{TH0.2}$	Detection threshold 1	Max $R_a$ detection by DFP at $I_P = I_{P-USB}$ , min $I_{P-USB}$ detection by UFP on $R_d$ , min CC voltage for connected UFP	0.15	0.2	0.25	V
$V_{TH0.4}$	Detection threshold 2	Max $R_a$ detection by DFP at $I_P = I_{P-1.5}$	0.35	0.4	0.45	V
$V_{TH0.66}$	Detection threshold 3	Min $I_{P-1.5}$ detection by UFP on $R_d$	0.61	0.66	0.7	V
$V_{TH0.8}$	Detection threshold 4	Max $R_a$ detection by DFP at $I_P = I_{P-3.0}$	0.75	0.8	0.85	V
$V_{TH1.23}$	Detection threshold 5	Min $I_{P-3.0}$ detection by UFP on $R_d$	1.16	1.23	1.31	V

**STUSB4700**
**Electrical characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{TH1.6}$	Detection threshold 6	Max $R_d$ detection by DFP at $I_P = I_{P-USB}$ and $I_P = I_{P-1.5}$	1.5	1.6	1.65	V
$V_{TH2.6}$	Detection threshold 7	Max $R_d$ detection by DFP at $I_{P-3.0}$ , max CC voltage for connected UFP	2.45	2.6	2.75	V
<b><math>V_{CONN}</math> protection</b>						
$R_{VCONN}$	$V_{CONN}$ path resistance	$I_{VCONN} = 0.2$ A $-40^{\circ}\text{C} < T_A < +105^{\circ}\text{C}$	0.25	0.5	0.975	$\Omega$
$I_{OCP}$	Over current protection	Programmable current limit threshold (from 100 mA to 600 mA by step of 50 mA).	85	100	125	mA
			300	350	400	
			550	600	650	
$V_{OVP}$	Output over voltage protection		5.9	6	6.1	V
$V_{UVP}$	Input under voltage protection	Low UVLO threshold	2.6	–	2.7	V
		High UVLO threshold (default)	4.6	–	4.8	
<b><math>V_{BUS}</math> monitoring and driving</b>						
$V_{THUSB}$	$V_{BUS}$ presence threshold	$V_{SYS}=3.0$ to $5.5$ V	3.8	3.9	4	V
$V_{THOV}$	$V_{BUS}$ safe 0V threshold (vSafe0V)	$V_{SYS}=3.0$ to $5.5$ V Programmable threshold (from 0.6 to 1.8 V) Default $V_{THOV} = 0.6$ V	0.5	0.6	0.7	V
			0.8	0.9	1	
			1.1	1.2	1.3	
			1.7	1.8	1.9	
$R_{DISUSB}$	$V_{BUS}$ discharge resistor		600	700	800	$\Omega$
$T_{DISUSB}$	$V_{BUS}$ discharge time to 0 V	Default $T_{DISUSB} = 840$ ms . The coefficient $T_{DISPARAM}$ is programmable by NVM.	70 * $T_{DISPARAM}$	84 * $T_{DISPARAM}$	100 * $T_{DISPARAM}$	ms
$T_{DISUSB}$	$V_{BUS}$ discharge time to PDO	Default $T_{DISUSB} = 200$ ms The coefficient $T_{DISPARAM}$ is programmable by NVM	20 * $T_{DISPARAM}$	24 * $T_{DISPARAM}$	28 * $T_{DISPARAM}$	ms
$V_{MONUSBH}$	$V_{BUS}$ monitoring high voltage threshold	$V_{BUS} =$ nominal target value Default $V_{MONUSBH} = V_{BUS} + 10\%$ The threshold limit is programmable by NVM from $V_{BUS} + 5\%$ to $V_{BUS} + 20\%$	–	$V_{BUS} + 10\%$	–	V