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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China



**ADVANCED COMMUNICATIONS & SENSING**

# SX1511B/SX1512B

## World's Lowest Voltage Level Shifting GPIO with LED Driver and Keypad Engine

### GENERAL DESCRIPTION

The SX1511B and SX1512B are complete ultra low voltage General Purpose parallel Input/Output (GPIO) expanders ideal for low power handheld battery powered equipment. This family of GPIOs comes in 8-, 16-channel configuration and allows easy serial expansion of I/O through a standard SPI interface. GPIO devices can provide additional control and monitoring when the microcontroller or chipset has insufficient I/O ports, or in systems where serial communication and control from a remote location is advantageous.

These devices can also act as a level shifter to connect a microcontroller running at one voltage level to a component running at a different voltage level, thus eliminating the need for extra level translating circuits. The core is operating as low as 1.425V while the dual I/O banks can operate between 1.2V and 3.6V independent of the core voltage and each other (5.5V tolerant).

The SX1511B and SX1512B feature a fully programmable LED Driver with internal oscillator for enhanced lighting control such as intensity (via 256-step PWM), blinking and breathing (fade in/out) make them highly versatile for a wide range of LED applications.

In addition, keypad applications are also supported with an on-chip scanning engine that enables continuous keypad monitoring up to 64 keys without any additional host interaction reducing the bus activity.

The SX1511B and SX1512B have the ability to generate mask-programmable interrupts based on a falling/rising edge of any of its GPIO lines. A dedicated pin (NINT) indicates to a host controller that a state change occurred on one or more of the lines. Each GPIO is programmable via a bank of 8-bit configuration registers that include data, direction, pull-up/pull-down, interrupt mask and interrupt registers. These I/O expanders feature small footprint packages and are rated from -40°C to +85°C temperature range.

### ORDERING INFORMATION

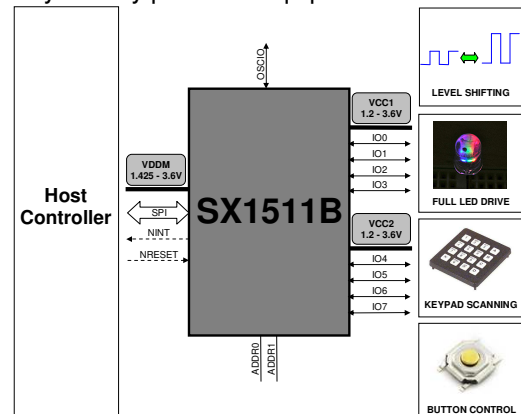
Part Number	I/Os	Package	Marking
SX1511BIULTRT	8	QFN-UT-20	JKA5
SX1512BIULTRT	16	QFN-UT-28	KA25
SX1512BEVK	16	Evaluation Kit	-

### KEY PRODUCT FEATURES

- 1.2V to 3.6V Low Operating Voltage with Dual Independent I/O Rails (VCC1, VCC2)
  - Enable Direct Level Shifting Between I/O Banks and Host Controller
- 5.5V Tolerant I/Os, Up to 15mA Output Sink on all I/Os (No Total Sink Current Limit)
- Integrated LED Driver for Enhanced Lighting
  - Intensity Control (256-step PWM)
  - Blink Control (224 On/Off values)
  - Breathing Control (224 Fade In/Out values)
- On-Chip Keypad Scanning Engine
  - Support Up to 8x8 Matrix (64 Keys)
  - Configurable Input Debouncer
- 8/16 Channels of True Bi-directional Style I/O
  - Programmable Pull-up/Pull-down
  - Push/Pull or Open-drain outputs
  - Programmable Polarity
- Open Drain Active Low Interrupt Output (NINT)
  - Bit Maskable
  - Programmable Edge Sensitivity
- Built-in Clock Management (Internal 2MHz Oscillator/External Clock Input, 7 clock values)
  - OSCIO can be Configured as GPO
- SPI Compatible Slave Interface (up to 20MHz)
- Power-On Reset and Reset Input (NRESET)
- Ultra Low Current Consumption: 1uA Typ
- -40°C to +85°C Operating Temperature Range
- Up to 2kV HBM ESD Protection
- Small Footprint Packages
- Pb & Halogen Free, RoHS/WEEE compliant

### TYPICAL APPLICATIONS

- Cell phones, PDAs, MP3 players
- Digital camera, Notebooks, GPS Units
- Any battery powered equipment



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**ADVANCED COMMUNICATIONS & SENSING**

**1 PIN DESCRIPTION**

**1.1 SX1511B 8-channel SPI GPIO with LED Driver and Keypad Engine**

Pin	Symbol	Type	Description
1	NRESET	DI	Active low reset input
2	SO	DO	SPI data output (HZ when not used)
3	SCK	DI	SPI clock input
4	SI	DI	SPI data input
5	I/O[0]	DIO (*)	I/O[0], at power-on configured as an input LED driver : Intensity control (PWM)
6	I/O[1]	DIO (*)	I/O[1], at power-on configured as an input LED driver : Intensity control (PWM)
7	VCC1	P	Supply voltage for Bank A I/O[3-0]
8	GND	P	Ground Pin
9	I/O[2]	DIO (*)	I/O[2], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
10	I/O[3]	DIO (*)	I/O[3], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
11	NINT	DO	Active low interrupt output
12	NSS	DI	SPI slave select input (active low)
13	OSCIO	DIO (*)	Oscillator input/output, can also be used as GPO
14	VDDM	P	Main supply voltage
15	I/O[4]	DIO (*)	I/O[4], at power-on configured as an input LED driver : Intensity control (PWM)
16	I/O[5]	DIO (*)	I/O[5], at power-on configured as an input LED driver : Intensity control (PWM)
17	VCC2	P	Supply voltage for Bank B I/O[7-4]
18	GND	P	Ground Pin
19	I/O[6]	DIO (*)	I/O[6], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
20	I/O[7]	DIO (*)	I/O[7], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)

D/I/O/P: Digital/Input/Output/Power

(\*) This pin is programmable through the SPI interface

Table 1 – SX1511B Pin Description

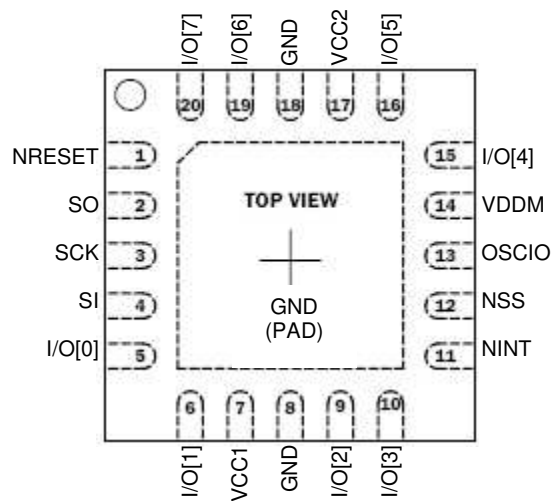


Figure 1 – SX1511B QFN-UT-20 Pinout

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**1.2 SX1512B 16-channel SPI GPIO with LED Driver and Keypad Engine**

Pin	Symbol	Type	Description
1	I/O[2]	DIO (*)	I/O[2], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
2	I/O[3]	DIO (*)	I/O[3], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
3	GND	P	Ground Pin
4	VCC1	P	Supply voltage for Bank A I/O[7-0]
5	I/O[4]	DIO (*)	I/O[4], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
6	I/O[5]	DIO (*)	I/O[5], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
7	I/O[6]	DIO (*)	I/O[6], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
8	I/O[7]	DIO (*)	I/O[7], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
9	NINT	DO	Active low interrupt output
10	NSS	DI	SPI slave select input (active low)
11	OSCIO	DIO (*)	Oscillator input/output, can also be used as GPO
12	VDDM	P	Main supply voltage
13	I/O[8]	DIO (*)	I/O[8], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
14	I/O[9]	DIO (*)	I/O[9], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
15	I/O[10]	DIO (*)	I/O[10], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
16	I/O[11]	DIO (*)	I/O[11], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
17	GND	P	Ground Pin
18	VCC2	P	Supply voltage for Bank B I/O[15-8]
19	I/O[12]	DIO (*)	I/O[12], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
20	I/O[13]	DIO (*)	I/O[13], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
21	I/O[14]	DIO (*)	I/O[14], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
22	I/O[15]	DIO (*)	I/O[15], at power-on configured as an input LED driver : Intensity control (PWM), Blinking, Breathing (Fade In/Out)
23	NRESET	DI	Active low reset input
24	SO	DO	SPI data output (HZ when not used)
25	SCK	DI	SPI clock input
26	SI	DI	SPI data input
27	I/O[0]	DIO (*)	I/O[0], at power-on configured as an input LED driver : Intensity control (PWM), Blinking
28	I/O[1]	DIO (*)	I/O[1], at power-on configured as an input LED driver : Intensity control (PWM), Blinking

D/I/O/P: Digital/Input/Output/Power

(\*) This pin is programmable through the SPI interface

Table 2 – SX1512B Pin Description

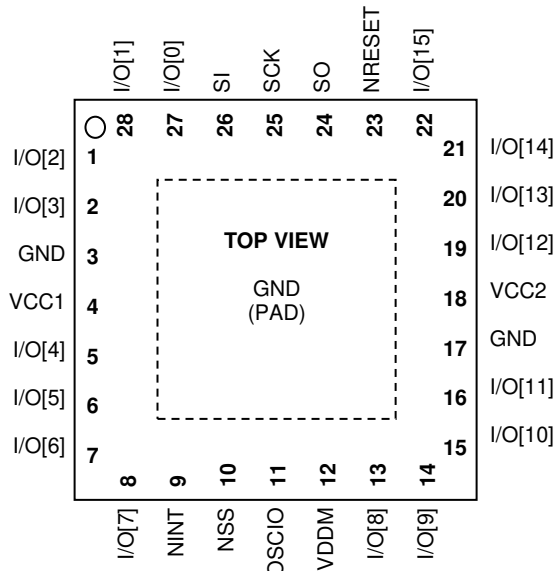


Figure 2 – SX1512B QFN-UT-28 Pinout

**ADVANCED COMMUNICATIONS & SENSING**
**1.3 I/Os Feature Summary**

I/O	SX1511B					SX1512B				
	LED Driver			Keypad		LED Driver			Keypad	
	PWM	Blink	Breathe	Row	Col.	PWM	Blink	Breathe	Row	Col.
0	√			√		√	√		√	
1	√			√		√	√		√	
2	√	√		√		√	√		√	
3	√	√	√	√		√	√		√	
4	√				√	√	√	√	√	
5	√				√	√	√	√	√	
6	√	√			√	√	√	√	√	
7	√	√	√		√	√	√	√	√	
8						√	√			√
9						√	√			√
10						√	√			√
11						√	√			√
12						√	√	√		√
13						√	√	√		√
14						√	√	√		√
15						√	√	√		√

*Table 3 – I/Os Feature Summary*

Please note that in addition to table above, all I/Os feature bank-to-bank and bank-to-host level shifting.

**ADVANCED COMMUNICATIONS & SENSING**
**2 ELECTRICAL CHARACTERISTICS**
**2.1 Absolute Maximum Ratings**

Stress above the limits listed in the following table may cause permanent failure. Exposure to absolute ratings for extended time periods may affect device reliability. The limiting values are in accordance with the Absolute Maximum Rating System (IEC 134). All voltages are referenced to ground (GND).

Symbol	Description	Min	Max	Unit
$V_{\max\_VDDM}$	Main supply voltage	- 0.4	3.7	V
$V_{\max\_VCC1-2}$	Digital I/O pin supply voltage (SX1511/12B)	- 0.4	3.7	V
$V_{ES\_HBM}$	Electrostatic handling HBM model <sup>(1)</sup> (SX1511B)	-	2000	V
	Electrostatic handling HBM model <sup>(1)</sup> (SX1512B)	-	1500	
$V_{ES\_CDM}$	Electrostatic handling CDM model	-	1000	V
$V_{ES\_MM}$	Electrostatic handling MM model (SX1511B)	-	200	V
	Electrostatic handling MM model (SX1512B)	-	150	
$T_A$	Operating ambient temperature range	-40	+85	°C
$T_C$	Junction temperature range	-40	+125	°C
$T_{STG}$	Storage temperature range	-55	+150	°C
$I_{lat}$	Latchup-free input pin current <sup>(2)</sup>	+/-100	-	mA

(1) Tested according to JESD22-A114A

(2) Static latch-up values are valid at maximum temperature according to JEDEC 78 specification

Table 4 - Absolute Maximum Ratings

**2.2 Electrical Specifications**

Table below assumes default registers values, unless otherwise specified. Typical values are given for  $T_A = +25^\circ\text{C}$ ,  $VDDM=VCC1=VCC2=3.3\text{V}$ .

Symbol	Description	Conditions	Min	Typ	Max	Unit
<b>Supply</b>						
VDDM	Main supply voltage		1.425	-	3.6	V
VCC1,2	I/O banks supply voltage		1.2	-	3.6	V
IDDm	Main supply current (SX1511B, SPI inactive)	Oscillator OFF	-	1	5	µA
		Internal osc. (2MHz)	-	175	235	
		External osc. (32kHz)	-	10	-	
	Main supply current (SX1512B, SPI inactive)	Oscillator OFF	-	1	5	µA
		Internal osc. (2MHz)	-	365	460	
		External osc. (32kHz)	-	10	-	
ICC1,2	I/O banks supply current <sup>(1)</sup>		-	1	2	µA
<b>I/Os set as Input</b>						
VIH	High level input voltage	$VCC1,2 \geq 2\text{V}$	0.7* $VCC1,2$	-	5.5 <sup>(3)</sup>	V
		$VCC1,2 < 2\text{V}$	0.8* $VCC1,2$	-	5.5 <sup>(3)</sup>	
VIL	Low level input voltage	$VCC1,2 \geq 2\text{V}$	-0.4	-	0.3* $VCC1,2$	V
		$VCC1,2 < 2\text{V}$	-0.4	-	0.2* $VCC1,2$	
ILEAK	Input leakage current	Assuming no active pull-up/down	-1	-	1	µA
CI	Input capacitance	-	-	-	10	pF
<b>I/Os set as Output</b>						
VOH	High level output voltage	-	$VCC1,2$ -0.3	-	$VCC1,2$	V
VOL	Low level output voltage	-	-0.4	-	0.3	V
IOH	High level output source current	$VCC1,2 \geq 2\text{V}$	-	-	8 <sup>(2)</sup>	mA
		$VCC1,2 < 2\text{V}$	-	-	2 <sup>(2)</sup>	



**ADVANCED COMMUNICATIONS & SENSING**

Symbol	Description	Conditions	Min	Typ	Max	Unit
IOL	Low level output sink current	VCC1,2 >= 2V	-	-	15 <sup>(2)</sup>	mA
		VCC1,2 < 2V	-	-	8 <sup>(2)</sup>	
t <sub>PV</sub>	Output data valid timing	After 8 <sup>th</sup> SCK falling edge	-	-	200	ns
<b>NINT (Output)</b>						
VOL	Low level output voltage	-	-0.4	-	0.3	V
IOL <sub>M</sub>	Low level output sink current	VDDM >= 2V	-	-	8	mA
		VDDM < 2V	-	-	4	
t <sub>IV</sub>	Interrupt valid timing	From input data change	-	-	4	μs
t <sub>IR</sub>	Interrupt reset timing	From RegInterruptSource clearing	-	-	4	μs
<b>NRESET (Input)</b>						
VIH <sub>MR</sub>	High level input voltage	VDDM >= 2V	0.7*VDDM	-	VDDM <sub>max</sub>	V
		VDDM < 2V	0.8*VDDM	-	VDDM <sub>max</sub>	
VIL <sub>M</sub>	Low level input voltage	VDDM >= 2V	-0.4	-	0.3*VDDM	V
		VDDM < 2V	-0.4	-	0.2*VDDM	
ILEAK	Input leakage current	-	-1	-	1	μA
CI	Input capacitance	-	-	-	10	pF
VPOR	Power-On-Reset voltage	Cf. Figure 6	-	0.8	-	V
VDROPH	High brown-out voltage	Cf. Figure 6	-	VDDM-1	-	V
VDROPL	Low brown-out voltage	Cf. Figure 6	-	0.2	-	V
t <sub>RESET</sub>	Reset time	Cf. Figure 6	0.6	-	2.5	ms
t <sub>PULSE</sub>	Reset pulse from host uC	Cf. Figure 6	200	-	-	ns
<b>OSCIO (Input/Output)</b>						
VIH <sub>MO</sub>	High level input voltage	VDDM >= 2V	0.7*VDDM	-	VDDM+0.3	V
		1.425V =< VDDM < 2V	0.8*VDDM	-	VDDM+0.3	
		VDDM < 1.425V	0.9*VDDM	-	VDDM+0.3	
VIL <sub>MO</sub>	Low level input voltage	VDDM >= 2V	-0.4	-	0.3*VDDM	V
		1.425V =< VDDM < 2V	-0.4	-	0.2*VDDM	
		VDDM < 1.425V	-0.4	-	0.1*VDDM	
ILEAK	Input leakage current	-	-1	-	1	μA
CI	Input capacitance	-	-	-	10	pF
VOH <sub>M</sub>	High level output voltage	-	VDDM-0.3	-	VDDM	V
VOL	Low level output voltage	-	-0.4	-	0.3	V
IOH <sub>M</sub>	High level output source current	VDDM >= 2V	-	-	8	mA
		VDDM < 2V	-	-	2	
IOL <sub>M</sub>	Low level output sink current	VDDM >= 2V	-	-	8	mA
		VDDM < 2V	-	-	4	
<b>SPI Interface : NSS(Input), SCK(Input), SI(Input), SO(Output)</b>						
VIH <sub>MA</sub>	High level input voltage	VDDM >= 2V	0.7* VDDM	-	VDDM +0.3	V
		VDDM < 2V	0.8* VDDM	-	VDDM +0.3	
VIL <sub>M</sub>	Low level input voltage	VDDM >= 2V	-0.4	-	0.3* VDDM	V
		VDDM < 2V	-0.4	-	0.2* VDDM	
ILEAK	Input leakage current	-	-1	-	1	μA
CI	Input capacitance	-	-	-	10	pF
VOH <sub>M</sub>	High level output voltage	-	VDDM – 0.3	-	VDDM	V
VOL	Low level output voltage	-	-0.4	-	0.3	V
IOH <sub>M</sub>	High level output source current	VDDM >= 2V	-	-	8	mA
		VDDM < 2V	-	-	2	
IOL <sub>M</sub>	Low level output sink current	VDDM >= 2V	-	-	8	mA
		VDDM < 2V	-	-	4	
f <sub>SCK</sub>	SCK max clock frequency	-	-	20 <sup>(4)</sup>	-	MHz
t <sub>SCK,LOW</sub>	SCK low time (% of SCK cycle)	-	45	-	55	%
t <sub>SCK,HIGH</sub>	SCK high time (% of SCK cycle)	-	45	-	55	%
t <sub>SI,SETUP</sub>	SI setup time	-	9	-	-	ns
t <sub>SI,HOLD</sub>	SI hold time	-	9	-	-	ns

**ADVANCED COMMUNICATIONS & SENSING**

Symbol	Description	Conditions	Min	Typ	Max	Unit
$t_{SO,VALID}$	SO valid time (% of SCK cycle)	After SCK falling edge	-	-	33 <sup>(4)</sup>	%
$t_{NSS,SCK}$	NSS low to SCK rising edge	-	25	-	-	ns
$t_{SCK,NSS}$	SCK falling edge to NSS high	-	25	-	-	ns
$t_{NSS,HIGH}$	NSS rising to falling edge	-	25	-	-	ns
<b>Miscellaneous</b>						
RPULL	Programmable pull-up/down resistors for IO[0-7]	-	-	42	-	k $\Omega$
$f_{OSC}$	Oscillator frequency	Internal	1.3	2	2.6	MHz
		External from OSCIN (40-60% duty cycle)	-	-	2.6	

(1) Assuming no load connected to outputs and inputs fixed to VCC1,2 or GND.

(2) Can be increased by tying together and driving simultaneously several I/Os.

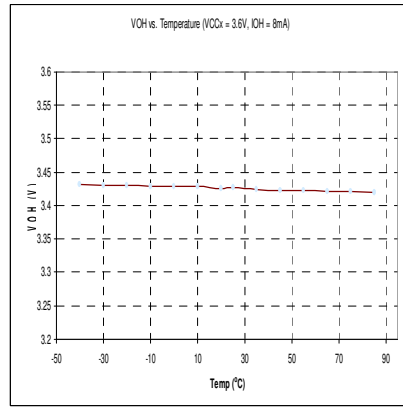
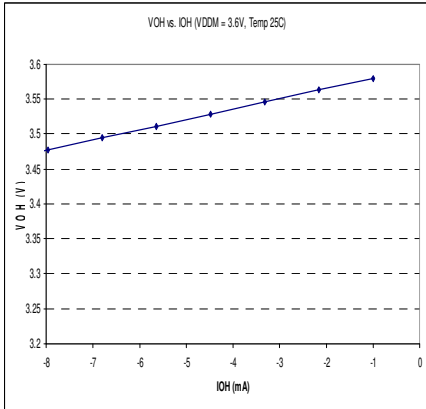
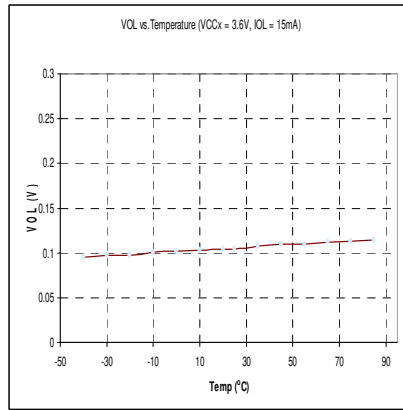
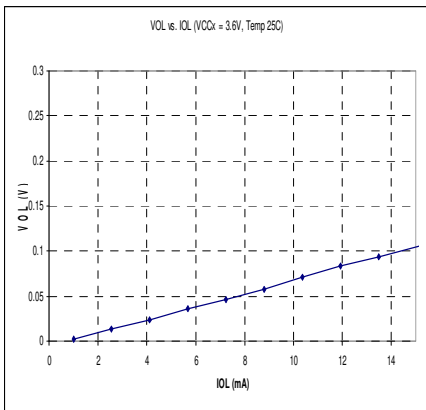
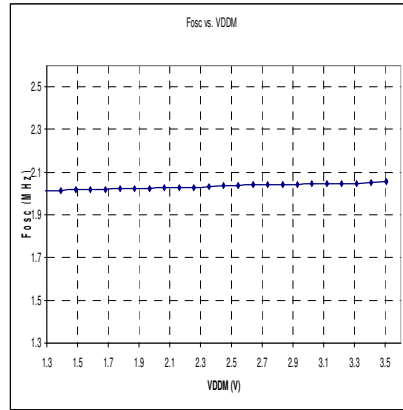
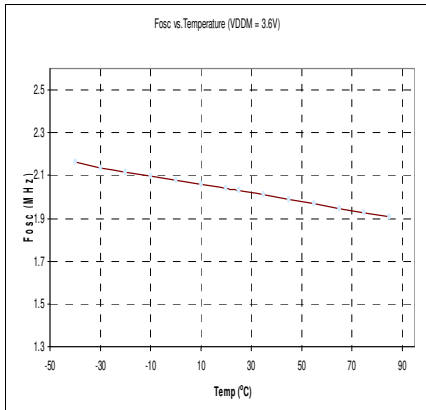
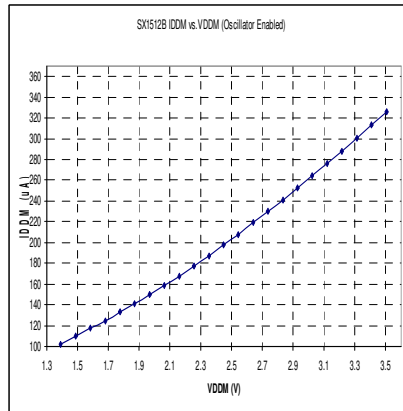
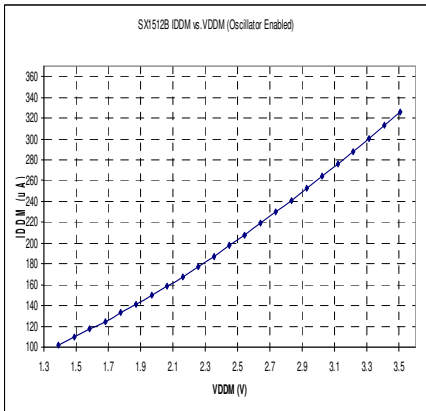
(3) With RegHighInput bit enabled (VCCx min = 1.65V), else 3.6V (VCCx min = 1.2V)

(4)  $f_{SCK}$  is calculated assuming a  $t_{SO,VALID}$  of maximum 1/3 of SCK cycle. This gives 1/6 of SCK cycle as setup time to the host controller. For systems where the setup time can be relaxed,  $t_{SO,VALID}$  is also shown in §3 to allow the user to calculate the maximum SPI frequency for individual systems.

*Table 5 – Electrical Specifications*

**ADVANCED COMMUNICATIONS & SENSING**

**3 TYPICAL OPERATING CHARACTERISTICS**



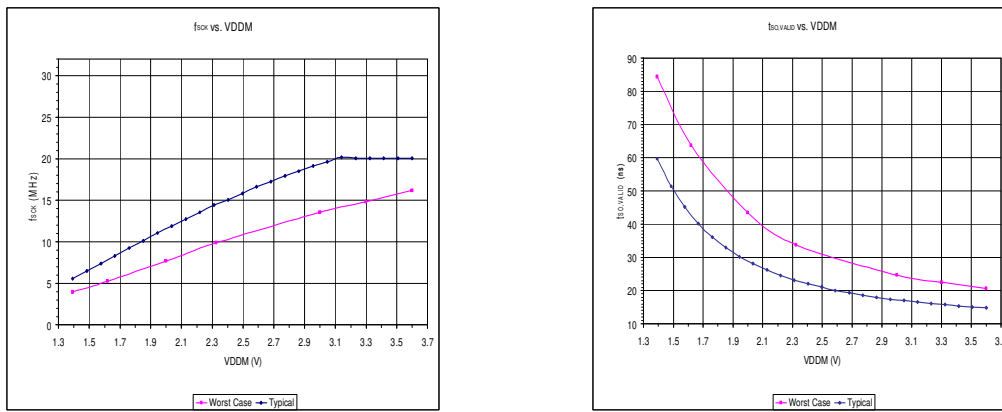
**ADVANCED COMMUNICATIONS & SENSING**


Figure 3 – Typical Operating Characteristics

**ADVANCED COMMUNICATIONS & SENSING**

**4 BLOCK DETAILED DESCRIPTION**

**4.1 SX1511B 8-channel SPI GPIO with LED Driver and Keypad Engine**

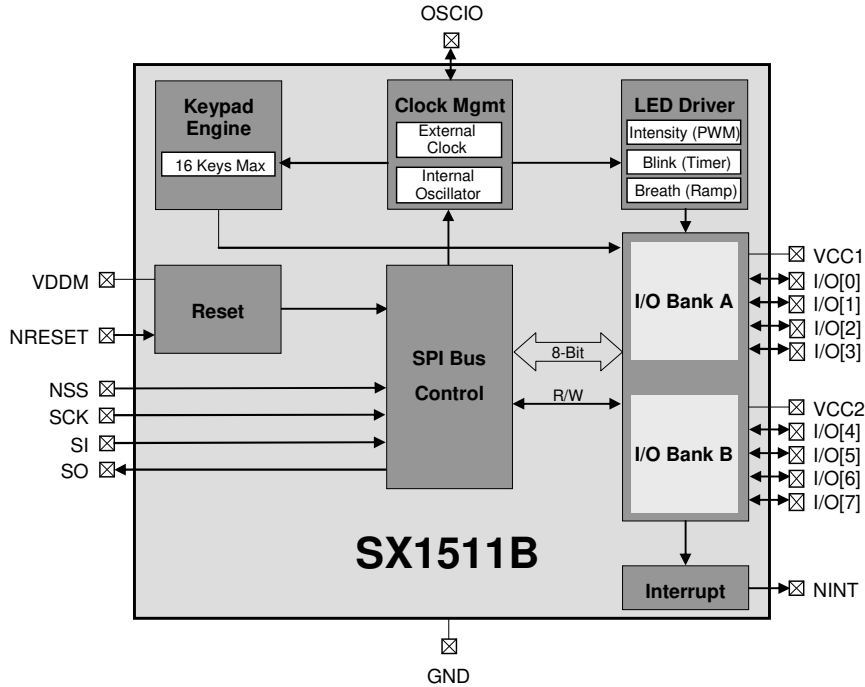


Figure 4 – 8-channel Low Voltage GPIO with LED Driver and Keypad Engine

**4.2 SX1512B 16-channel SPI GPIO with LED Driver and Keypad Engine**

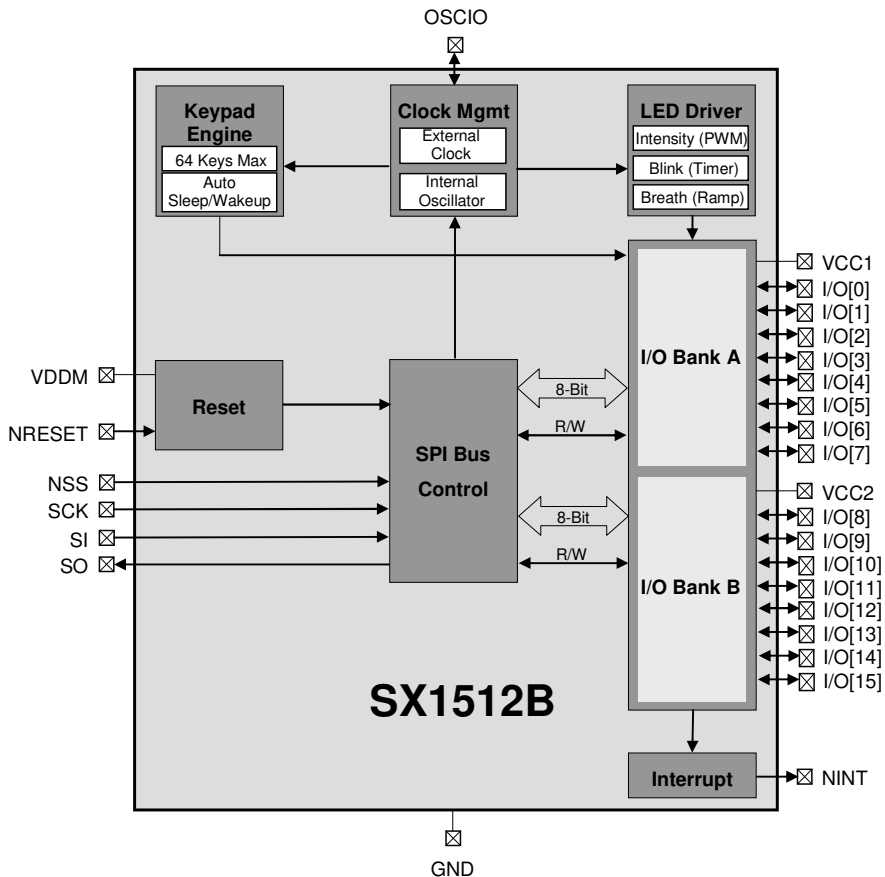


Figure 5 – 16-channel Low Voltage GPIO with LED Driver and Keypad Engine

## ADVANCED COMMUNICATIONS & SENSING

### 4.3 Reset

#### 4.3.1 Hardware (NRESET)

The SX1511B and SX1512B generate their own power on reset signal after a power supply is connected to the VDDM pin. NRESET input pin can be used to reset the chip anytime, it must be connected to VDDM (or greater) either directly (if not used), or via a resistor.

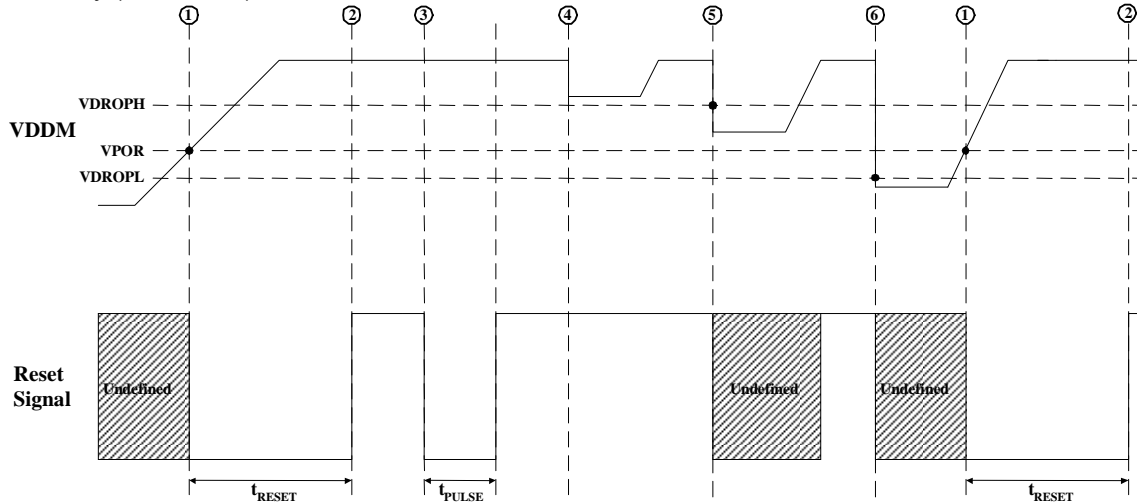


Figure 6 – Power-On / Brown-out Reset Conditions

1. Device behavior is undefined until VDDM rises above VPOR, at which point internal reset procedure is started.
2. After  $t_{\text{RESET}}$ , the reset procedure is completed.
3. In operation, the SX1511B and SX1512B may be reset (POR like or LED driver counters only depending on RegMisc setting) at anytime by an external device driving NRESET low for  $t_{\text{PULSE}}$  or longer. Chip can be accessed normally again after NRESET rising edge.
4. During a brown-out event, if VDDM drops above VDROPH a reset will not occur.
5. During a brown-out event, if VDDM drops between VDROPH and VDROPL a reset may occur.
6. During a brown-out event, if VDDM drops below VDROPL a reset will occur next time VPOR is crossed.

Please note that a brown-out event is defined as a transient event on VDDM. If VDDM is attached to a battery, then the gradual decay of the battery voltage will not be interpreted as a brown-out event. Please also note that a sharp rise in VDDM ( $> 1\text{V}/\mu\text{s}$ ) may induce a circuit reset.

#### 4.3.2 Software (RegReset)

Writing consecutively 0x12 and 0x34 to RegReset register will reset all registers to their default values.

### 4.4 SPI Interface

The SX1511B and SX1512B SPI interface operates only in slave mode. 4 lines are used to exchange data between an external master host and the slave device:

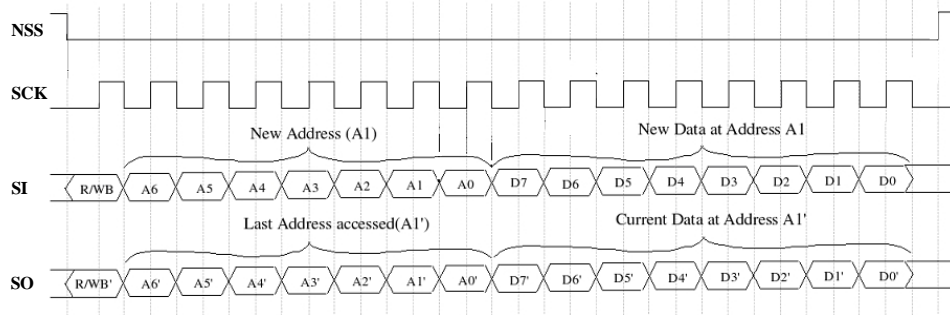
- **NSS** : Slave select input (active low)
- **SCK** : Clock input
- **SI** : Data input
- **SO** : Data output

The SX1511B and SX1512B have a few user-accessible internal 8-bits registers to set the various parameters of operation (Cf. §5 for detailed configuration registers description). The SPI interface has been designed for program flexibility, in that any register can be written or read independently of each other.

## ADVANCED COMMUNICATIONS & SENSING

### 4.4.1 WRITE

To write a value into a configuration register the timing diagram below should be carefully followed by the uC.

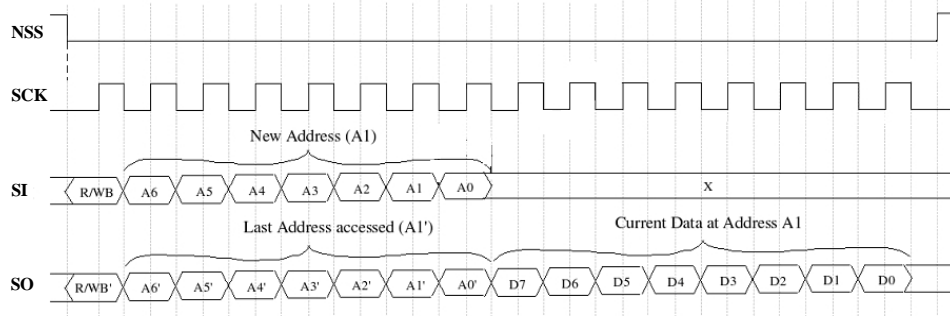


*Figure 7 - SPI Write Operation*

Successive register data can be written by the master without repeating the address byte, the register address can be automatically incremented or kept fixed depending on the setting programmed in RegMisc.

### 4.4.2 READ

To read a value from a configuration register the timing diagram below should be carefully followed by the uC.



*Figure 8 – SPI Read Operation*

Successive register data can be read by the master without repeating the address byte, the register address will be automatically incremented or kept fixed depending on the setting programmed in RegMisc.

## 4.5 I/O Banks

### 4.5.1 Input Debouncer

Each input can be individually debounced by setting corresponding bits in RegDebounce register. At power up the debounce function is disabled. After enabling the debouncer, the change of the input value is accepted only if the input value is identical at two consecutive sampling times.

The debounce time common to all IOs can be set in RegDebounceConfig register from 0.5 to 64ms. ( $f_{OSC} = 2\text{MHz}$ )

### 4.5.2 Keypad Scanning Engine

SX1511B, and SX1512B integrate a fully programmable keypad scanning engine to implement keypad applications up to 8x8 matrix (i.e. 64 keys).

Please note that SX1512B also implements an Auto Sleep/Wakeup feature to save power consumption when no key has been pressed for a programmed time.

**ADVANCED COMMUNICATIONS & SENSING**

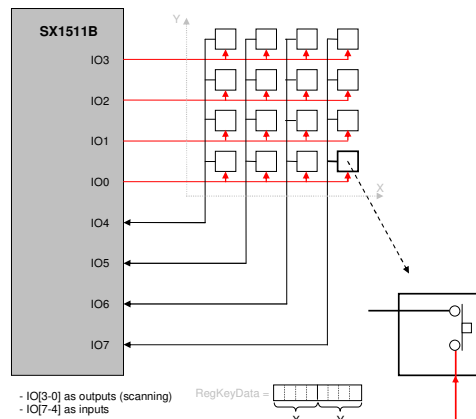


Figure 9 – 4x4 Keypad Connection to SX1511B

Following procedure should be implemented on the host controller for a 4x4 keypad:

1. Set *RegDir* to *0xF0* (*IO[3-0]* as outputs, *IO[7-4]* as inputs) , set *RegOpenDrain* to *0x0F* (*IO[3-0]* as open-drain outputs), set *RegPullup* to *0xF0* (pull-ups enabled on inputs *IO[7-4]*).
2. Enable and configure debouncing on *IO[7-4]* (*RegDebounceEnable* = *0xF0*, Ex : *RegDebounceConfig* = *0x05*)
3. Enable and configure keypad scanning engine (Ex : *RegKeyConfig* = *0x7D*) This will start an infinite loop with the following sequence to *IO[3:0]*: *ZZZ0*, *ZZ0Z*, *Z0ZZ*, *0ZZZ*. Make sure that scan interval is set to higher value than the debounce time.
4. When a key is pressed, *NINT* goes low, key scan is halted and the key coordinates are stored in *RegKeyData*:
  - The column data will be stored in *RegKeyData[7:4]* (Note: column indication is active low)
  - The row data will be stored in *RegKeyData[3:0]* (Note: row indication is active low)
  - When *RegKeyData* is read, this data along with the interrupt is automatically cleared (same behavior as reading *RegData*) and the key scan continues to the next row.
5. Restart from point 4.

This implementation allows the host to handle both single and multi-touches easily (fast AAAAAA sequence is a long press of key A, fast ABABABAB sequence is key A and key B pressed together, etc)

**4.5.3 Level Shifter**

Because of their 5.5V tolerant I/O banks with independent supply voltages between 1.2V and 3.6V, the SX1511B and SX1512B can perform level shifting of signals from one I/O bank to another **without uC activity** by programming the corresponding configuration register bits accordingly in *RegLevelShifter* (and *RegDir*). This can save significant BOM cost in a final application where only a few signals need to be level-shifted (no need for an additional external level shifter IC).

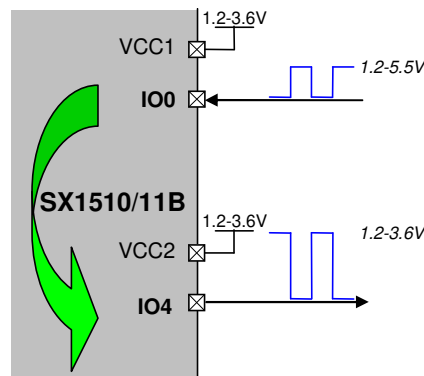


Figure 10 – Level Shifting Example



**ADVANCED COMMUNICATIONS & SENSING**

The minimum pulse width  $t_{LevelShiftMin}$  which can be level shifted properly depends on  $V_{CCx}$  and  $V_{DDM}$ :

$$t_{LevelShiftMin} = Input\ Delay + Core\ Delay + Output\ Delay$$

Input/Core/Output delays vs  $V_{CCx}/V_{DDM}$  are given in figures below.

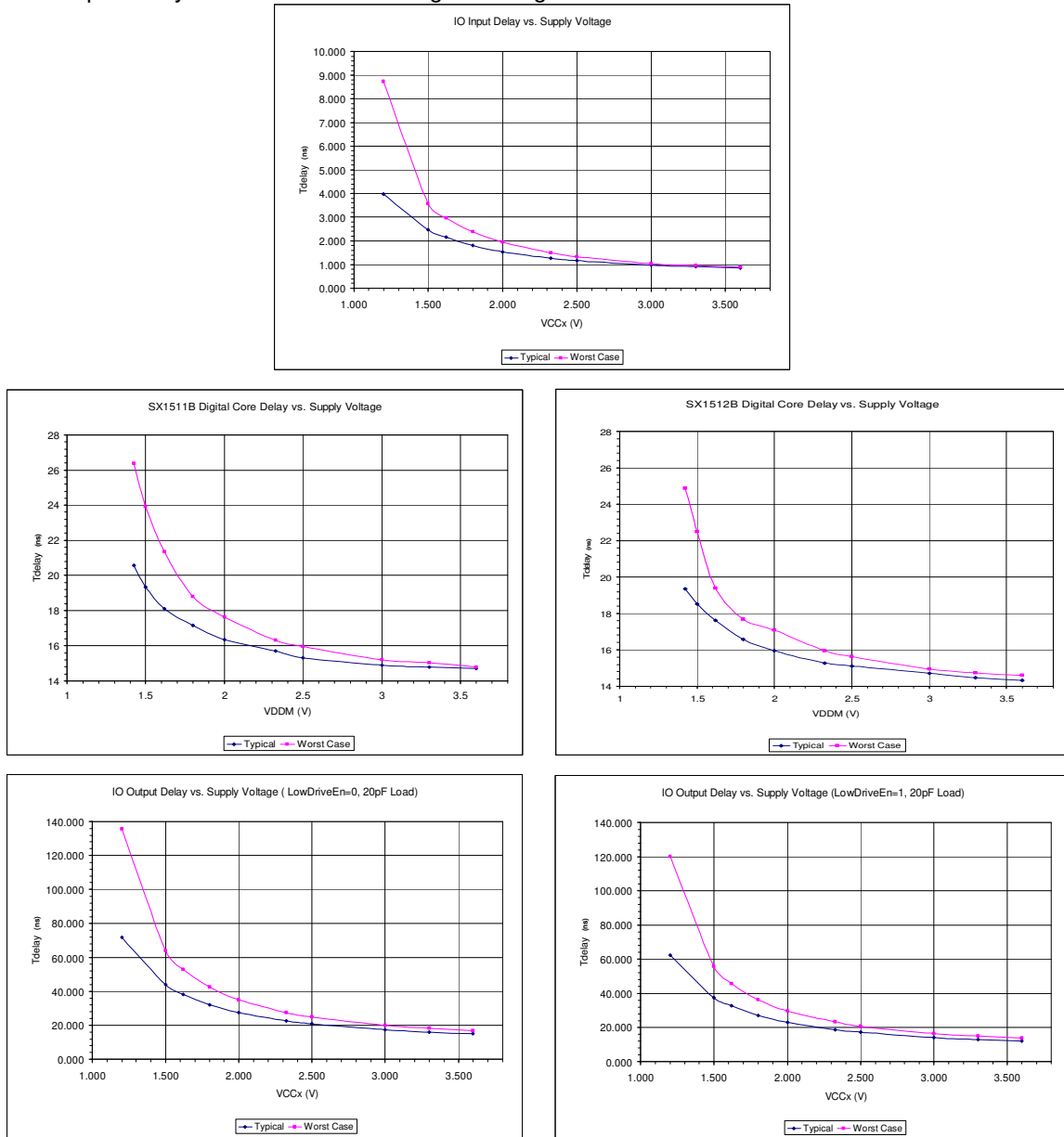


Figure 11 – Level Shifter Max Frequency Calculation Data

**4.5.4 Polarity Inverter**

Each IO's polarity can be individually inverted by setting corresponding bit in RegPolarity register. Please note that polarity inversion can also be combined with level shifting feature.

**4.6 Interrupt (NINT)**

At start-up, the transition detection logic is reset, and NINT is released to a high-impedance state. The interrupt mask register is set to 0xFF, disabling the interrupt output for transitions on all I/O ports. The transition flags are cleared to indicate no data changes.

An interrupt NINT can be generated on any programmed combination of I/Os rising and/or falling edges through the RegInterruptMask and RegSense registers. If needed, the I/Os which triggered the interrupt can then be identified by reading RegInterruptSource register.

## ADVANCED COMMUNICATIONS & SENSING

When NINT is low (i.e. interrupt occurred), it can be reset back high (i.e. cleared) by writing 0xFF in RegInterruptSource (this will also clear corresponding bits in RegEventStatus register). The interrupt can also be cleared automatically when reading RegData register (Cf. RegMisc)

*Example: We want to detect rising edge of I/O[1] on SX1511B (NINT will go low).*

1. We enable interrupt on I/O[1] in RegInterruptMask  
 ⇒ RegInterruptMask = "XXXXXX0X"
2. We set edge sense for I/O[1] in RegSense  
 ⇒ RegSenseLow = "XXXX01XX"

Please note that independently from the "user defined" process described above the keypad engine, when enabled, also uses NINT to indicate a key press.

Hence we have NINT = "user defined condition occurred" OR "keypad engine condition occurred"

### 4.7 Clock Management

A main oscillator clock fOSC is needed by the LED driver, keypad engine and debounce features.

Clock management block is illustrated in figure below.

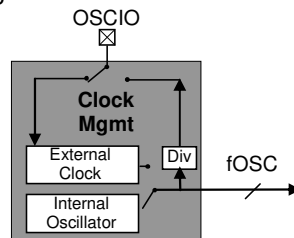


Figure 12 – Clock Management Overview

The block is configured in register RegClock (Cf §5 for more detailed information):

- Selection of internal clock source: none (OFF) or internal oscillator or external clock input from OSCIN.
- Definition of OSCIO pin function (OSCIN or OSCOUT)
- OSCOUT frequency setting (sub-multiple of fOSC)

Please note that if needed the OSCOUT feature can be used as an additional GPO (Cf. RegClock)

### 4.8 LED Driver

#### 4.8.1 Overview

Every IO has its own independent LED driver (Cf §6.2 for typical LED connection), all IOs can perform intensity control (PWM) while some of them additionally include blinking and breathing features (Cf pin description §1.3)

The LED drivers of all I/Os share the same clock ClkX configurable in RegMisc[6:4]. Please note that for power consumption reasons ClkX is OFF by default.

Assuming ClkX is not OFF, LED driver for IO[X] is enabled when RegLEDDriverEnable[X] = 1 in which case it can operate in one of the three modes below:

- Static mode (all I/Os, with or without fade in/out)
- Single shot mode (blinking capable I/Os only, with or without fade in/out)
- Blink mode (blinking capable I/Os only, with or without fade in/out)

**ADVANCED COMMUNICATIONS & SENSING**

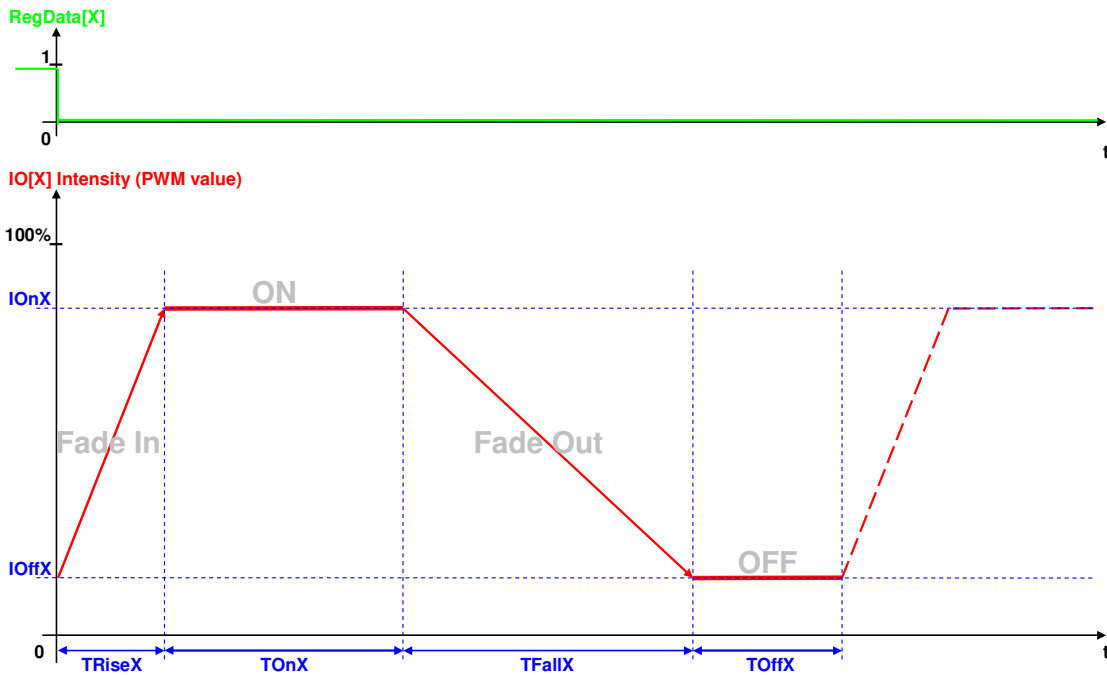


Figure 13 – LED Driver Overview

Each IO[X] has its own set of programmable registers (Cf §5 for more detailed information):

- **RegTOnX** (blinking capable I/Os only): TOnX, ON time of IO[X]
- **RegIOonX** (all I/Os): IOonX, ON intensity of IO[X]
- **RegOffX** (blinking capable I/Os only): TOffX and IOoffX, OFF time and intensity of IO[X]
- **RegTRiseX**(breathing capable I/Os only): TRiseX, fade in time of IO[X]
- **RegTFallX**(breathing capable I/Os only): TFallX, fade out time of IO[X]

Please note that the LED Driver mode is selectable for each IO bank between linear and logarithmic. (Cf 4.8.5)

All the figures assume normal IO polarity, for inverse polarity RegData control must be inverted (does not invert the polarity of the IO signal itself).

**4.8.2 Static Mode**

Only mode available for non blinking capable IOs (with Off intensity = 0), else invoked when TOnX = 0. If the I/O doesn't support fading the LED intensity will step directly to the IOonX/IOoffX value.

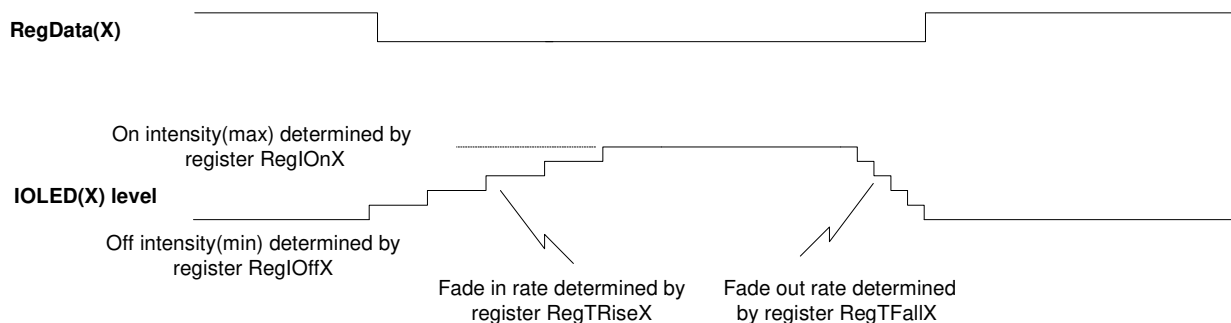


Figure 14 – LED Driver Static Mode

**4.8.3 Single Shot Mode**

Invoked when TOnX != 0 and TOffX = 0.

If the I/O doesn't support fading the LED intensity will step directly to the IOonX/IOoffX value.

**ADVANCED COMMUNICATIONS & SENSING**

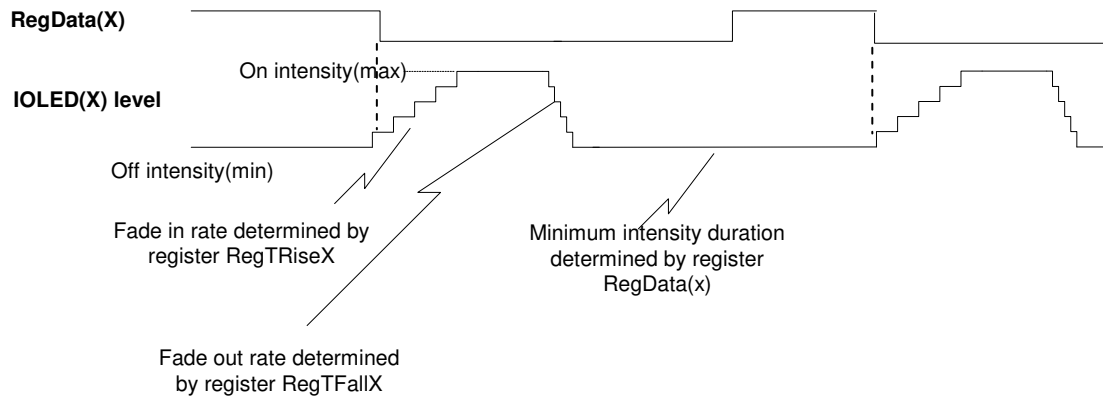


Figure 15 – LED Driver Single Shot Mode

**4.8.4 Blink Mode**

Invoked when TOnX != 0 and TOffX != 0.

If the I/O doesn't support fading the LED intensity will step directly to the IOnX/IOffX value.

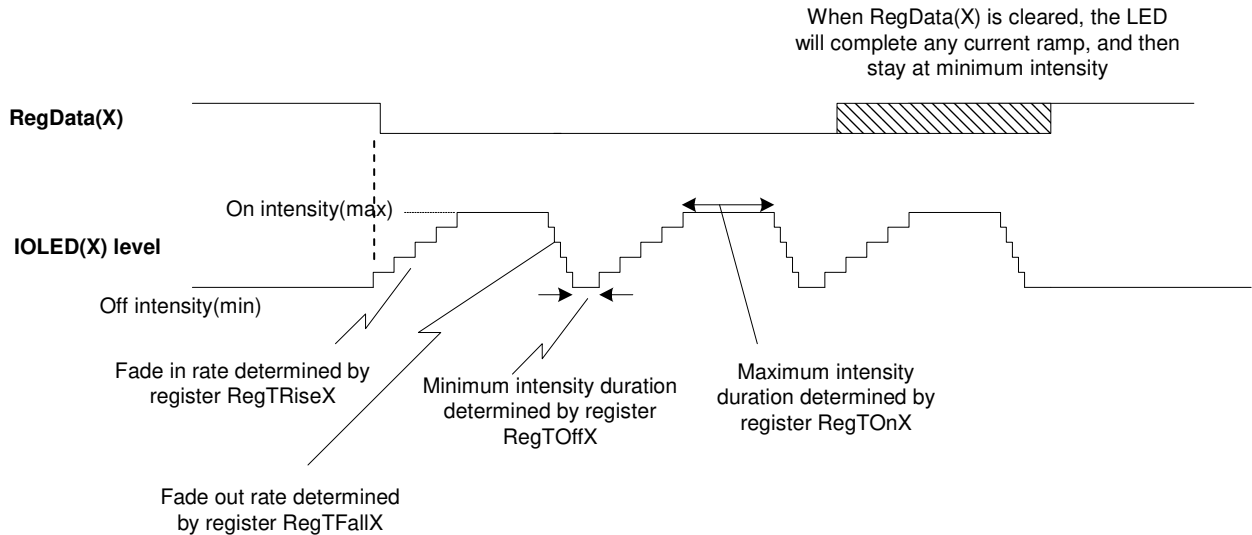


Figure 16 – LED Driver Blink Mode

**4.8.5 LED Driver Modes**

For each IO bank, the LED driver mode of fading capable IOs can be selected between linear or logarithmic in RegMisc.

Lin.	Log.	Lin.	Log.	Lin.	Log.	Lin.	Log.	Lin.	Log.	Lin.	Log.	Lin.	Log.	Lin.	Log.
0	0	32	4	64	13	96	28	128	53	160	88	192	135	224	198
1	0	33	4	65	13	97	28	129	53	161	88	193	135	225	198
2	0	34	4	66	13	98	30	130	53	162	88	194	135	226	198
3	0	35	4	67	13	99	30	131	53	163	88	195	135	227	198
4	0	36	5	68	14	100	31	132	56	164	93	196	142	228	207
5	0	37	5	69	14	101	31	133	56	165	93	197	142	229	207
6	0	38	5	70	14	102	32	134	56	166	93	198	142	230	207
7	0	39	5	71	14	103	32	135	56	167	93	199	142	231	207
8	1	40	6	72	16	104	34	136	60	168	98	200	150	232	216
9	1	41	6	73	16	105	34	137	60	169	98	201	150	233	216
10	1	42	6	74	17	106	35	138	60	170	98	202	150	234	216
11	1	43	6	75	17	107	35	139	60	171	98	203	150	235	216
12	1	44	7	76	18	108	36	140	65	172	104	204	157	236	225
13	1	45	7	77	18	109	36	141	65	173	104	205	157	237	225

**ADVANCED COMMUNICATIONS & SENSING**

14	1	46	7	78	19	110	38	142	65	174	104	206	157	238	225
15	1	47	7	79	19	111	38	143	65	175	104	207	157	239	225
16	2	48	8	80	20	112	39	144	69	176	110	208	165	240	235
17	2	49	8	81	20	113	39	145	69	177	110	209	165	241	235
18	2	50	8	82	21	114	41	146	69	178	110	210	165	242	235
19	2	51	8	83	21	115	41	147	69	179	110	211	165	243	235
20	2	52	9	84	22	116	42	148	73	180	116	212	172	244	245
21	2	53	9	85	22	117	42	149	73	181	116	213	172	245	245
22	2	54	9	86	23	118	44	150	73	182	116	214	172	246	245
23	2	55	9	87	23	119	44	151	73	183	116	215	172	247	245
24	3	56	10	88	24	120	46	152	78	184	122	216	181	248	255
25	3	57	10	89	24	121	46	153	78	185	122	217	181	249	255
26	3	58	10	90	25	122	46	154	78	186	122	218	181	250	255
27	3	59	10	91	25	123	46	155	78	187	122	219	181	251	255
28	3	60	11	92	26	124	49	156	83	188	129	220	189	252	255
29	3	61	11	93	26	125	49	157	83	189	129	221	189	253	255
30	3	62	12	94	27	126	49	158	83	190	129	222	189	254	255
31	3	63	12	95	27	127	49	159	83	191	129	223	189	255	255

Table 6 – LED Driver Linear vs Logarithmic Function (I)

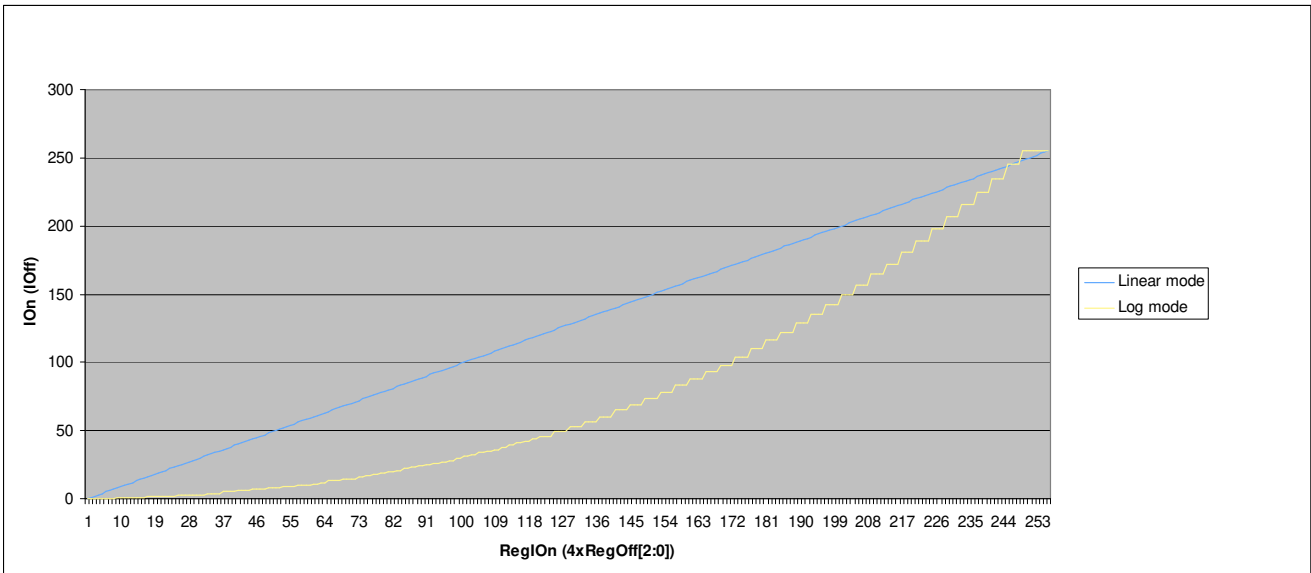


Figure 17 – LED Driver Linear vs Logarithmic Function (II)

**4.8.6 Synchronization of LED Drivers across several ICs**

When several GPIO expanders are used in the same application it may be useful that their LEDs drivers are synchronous for coherent global operation.

In this case all ICs should share their fOSC through their OSCIO pins and have their reset connected together.

When RegMisc of each IC is set accordingly, NRESET signal can then be used to reset all devices' internal counters (but not the register settings) and allow synchronous LED operation (blinking, fading) across multiple devices.

**4.8.7 Tutorial**

Below are the steps required to use the LED driver with the typical LED connection described §6.2:

- Disable input buffer (RegInputDisable)
- Disable pull-up (RegPullUp)
- Enable open drain (RegOpenDrain)

**ADVANCED COMMUNICATIONS & SENSING**

- Set direction to output (RegDir) – by default RegData is set high => LED OFF
- Enable oscillator (RegClock)
- Configure LED driver clock and mode if relevant (RegMisc)
- Enable LED driver operation (RegLEDDriverEnable)
- Configure LED driver parameters (RegTOn, RegIOn, RegOff, RegTRise, RegTFall)
- Set RegData bit low => LED driver started

## ADVANCED COMMUNICATIONS & SENSING

### 5 CONFIGURATION REGISTERS

#### 5.1 SX1511B 8-channel GPIO with LED Driver and Keypad Engine

Address	Name	Description	Default
<b>Device and IO Banks</b>			
0x00	RegInputDisable	Input buffer disable register	0000 0000
0x01	RegLongSlew	Output buffer long slew register	0000 0000
0x02	RegLowDrive	Output buffer low drive register	0000 0000
0x03	RegPullUp	Pull-up register	0000 0000
0x04	RegPullDown	Pull-down register	0000 0000
0x05	RegOpenDrain	Open drain register	0000 0000
0x06	RegPolarity	Polarity register	0000 0000
0x07	RegDir	Direction register	1111 1111
0x08	RegData	Data register	1111 1111
0x09	RegInterruptMask	Interrupt mask register	1111 1111
0x0A	RegSenseHigh	Sense register for I/O[7:4]	0000 0000
0x0B	RegSenseLow	Sense register for I/O[3:0]	0000 0000
0x0C	RegInterruptSource	Interrupt source register	0000 0000
0x0D	RegEventStatus	Event status register	0000 0000
0x0E	RegLevelShifter	Level shifter register	0000 0000
0x0F	RegClock	Clock management register	0000 0000
0x10	RegMisc	Miscellaneous device settings register	0000 0000
0x11	RegLEDDriverEnable	LED driver enable register	0000 0000
<b>Debounce and Keypad Engine</b>			
0x12	RegDebounceConfig	Debounce configuration register	0000 0000
0x13	RegDebounceEnable	Debounce enable register	0000 0000
0x14	RegKeyConfig	Key scan configuration register	0000 0000
0x15	RegKeyData	Key value	1111 1111
<b>LED Driver (PWM, blinking, breathing)</b>			
0x16	RegIOn0	ON intensity register for I/O[0]	1111 1111
0x17	RegIOn1	ON intensity register for I/O[1]	1111 1111
0x18	RegTOn2	ON time register for I/O[2]	0000 0000
0x19	RegIOn2	ON intensity register for I/O[2]	1111 1111
0x1A	RegOff2	OFF time/intensity register for I/O[2]	0000 0000
0x1B	RegTOn3	ON time register for I/O[3]	0000 0000
0x1C	RegIOn3	ON intensity register for I/O[3]	1111 1111
0x1D	RegOff3	OFF time/intensity register for I/O[3]	0000 0000
0x1E	RegTRise3	Fade in register for I/O[3]	0000 0000
0x1F	RegTFall3	Fade out register for I/O[3]	0000 0000
0x20	RegIOn4	ON intensity register for I/O[4]	1111 1111
0x21	RegIOn5	ON intensity register for I/O[5]	1111 1111
0x22	RegTOn6	ON time register for I/O[6]	0000 0000
0x23	RegIOn6	ON intensity register for I/O[6]	1111 1111
0x24	RegOff6	OFF time/intensity register for I/O[6]	0000 0000
0x25	RegTOn7	ON time register for I/O[7]	0000 0000
0x26	RegIOn7	ON intensity register for I/O[7]	1111 1111
0x27	RegOff7	OFF time/intensity register for I/O[7]	0000 0000
0x28	RegTRise7	Fade in register for I/O[7]	0000 0000
0x29	RegTFall7	Fade out register for I/O[7]	0000 0000
<b>Miscellaneous</b>			
0x2A	RegHighInput	High input enable register	0000 0000
<b>Software Reset</b>			
0x7D	RegReset	Software reset register	0000 0000
<b>Test (not to be written)</b>			
0x7E	RegTest1	Test register	0000 0000
0x7F	RegTest2	Test register	0000 0000

Bits set as output take "1" as default value.

*Table 7 – SX1511B Configuration Registers Overview*

**ADVANCED COMMUNICATIONS & SENSING**

Addr	Name	Default	Bits	Description	
0x00	<b>RegInputDisable</b>	0x00	7:0	Disables the input buffer of each [input-configured] IO 0 : Input buffer is enabled (input actually being used) 1 : Input buffer is disabled (input actually not being used or LED connection)	
0x01	<b>RegLongSlew</b>	0x00	7:0	Enables increased slew rate of the output buffer of each [output-configured] IO 0 : Increased slew rate is disabled 1 : Increased slew rate is enabled	
0x02	<b>RegLowDrive</b>	0x00	7:0	Enables reduced drive of the output buffer of each [output-configured] IO 0 : Reduced drive is disabled 1 : Reduced drive is enabled, IOL specifications are divided by 2.	
0x03	<b>RegPullUp</b>	0x00	7:0	Enables the pull-up for each IO 0 : Pull-up is disabled 1 : Pull-up is enabled	
0x04	<b>RegPullDown</b>	0x00	7:0	Enables the pull-down for each IO 0 : Pull-down is disabled 1 : Pull-down is enabled	
0x05	<b>RegOpenDrain</b>	0x00	7:0	Enables open drain operation for each [output-configured] IO 0 : Regular push-pull operation 1 : Open drain operation	
0x06	<b>RegPolarity</b>	0x00	7:0	Enables polarity inversion for each IO 0 : Normal polarity : RegData[x] = IO[x] 1 : Inverted polarity : RegData[x] = !IO[x] (for both input and output configured IOs)	
0x07	<b>RegDir</b>	0xFF	7:0	Configures direction for each IO. 0 : IO is configured as an output 1 : IO is configured as an input	
0x08	<b>RegData</b>	0xFF	7:0	Write: Data to be output to the output-configured IOs Read: Data seen at the IOs, independent of the direction configured.	
0x09	<b>RegInterruptMask</b>	0xFF	7:0	Configures which [input-configured] IO will trigger an interrupt on NINT pin 0 : An event on this IO will trigger an interrupt 1 : An event on this IO will NOT trigger an interrupt	
0x0A	<b>RegSenseHigh</b>	0x00	7:6	Edge sensitivity of RegData[7]	00 : None 01 : Rising 10 : Falling 11 : Both
			5:4	Edge sensitivity of RegData[6]	
			3:2	Edge sensitivity of RegData[5]	
			1:0	Edge sensitivity of RegData[4]	
0x0B	<b>RegSenseLow</b>	0x00	7:6	Edge sensitivity of RegData[3]	00 : None 01 : Rising 10 : Falling 11 : Both
			5:4	Edge sensitivity of RegData[2]	
			3:2	Edge sensitivity of RegData[1]	
			1:0	Edge sensitivity of RegData[0]	
0x0C	<b>RegInterruptSource</b>	0x00	7:0	Interrupt source (from IOs set in RegInterruptMask) 0 : No interrupt has been triggered by this IO 1 : An interrupt has been triggered by this IO (an event as configured in relevant RegSense register occurred).  Writing '1' clears the bit in RegInterruptSource and in RegEventStatus When all bits are cleared, NINT signal goes back high.	
0x0D	<b>RegEventStatus</b>	0x00	7:0	Event status of all IOs. 0 : No event has occurred on this IO 1 : An event has occurred on this IO (an edge as configured in relevant RegSense register occurred).  Writing '1' clears the bit in RegEventStatus and in RegInterruptSource if relevant. If the edge sensitivity of the IO is changed, the bit(s) will be cleared automatically	
0x0E	<b>RegLevelShifter</b>	0x00	7:6	Level shifter mode for IO[3] (Bank A) and IO[7] (Bank B)	00 : OFF 01 : A->B 10 : B->A 11 : Reserved
			5:4	Level shifter mode for IO[2] (Bank A) and IO[6] (Bank B)	
			3:2	Level shifter mode for IO[1] (Bank A) and IO[5] (Bank B)	
			1:0	Level shifter mode for IO[0] (Bank A) and IO[4] (Bank B)	
0x0F	<b>RegClock</b>	0x00	7	Unused	Oscillator frequency (fOSC) source 00 : OFF. LED driver, keypad engine and debounce features are disabled. 01 : External clock input (OSCIN) 10 : Internal 2MHz oscillator 11 : Reserved  OSCIO pin function (Cf. §4.7) 0 : OSCIO is an input (OSCIN) 1 : OSCIO is an output (OSCOUT)  Frequency of the signal output on OSCOUT pin: 0x0 : 0Hz, permanent "0" logical level (GPO) 0xF : 0Hz, permanent "1" logical level (GPO) Else : fOSCOUT = fOSC/(2^(RegClock[3:0]-1))
			6:5		
			4		
			3:0		



**ADVANCED COMMUNICATIONS & SENSING**

0x10	RegMisc	0x00	7	LED Driver mode for Bank B's fading capable IOs (IO7) 0: Linear 1: Logarithmic
			6:4	Frequency of the LED Driver clock ClkX of all IOs: 0 : OFF. LED driver functionality is disabled for all IOs. Else : $ClkX = fOSC / (2^{(RegMisc[6:4]-1)})$
			3	LED Driver mode for Bank A's fading capable IOs (IO3) 0: Linear 1: Logarithmic
			2	NRESET pin function when externally forced low (Cf. §4.3.1 and §4.8.5) 0: Equivalent to POR 1: Reset PWM/Blink/Fade counters (not user programmed values) This bit can only be reset manually or by POR, not by NRESET.
			1	Auto-increment register address (Cf. §4.4) 0: ON. When several consecutive data are read/written, register address is incremented. 1: OFF. When several consecutive data are read/written, register address is kept fixed.
			0	Autoclear NINT on RegData read (Cf. §4.6) 0: ON. RegInterruptSource is also automatically cleared when RegData is read. 1: OFF. RegInterruptSource must be manually cleared, either directly or via RegEventStatus.
0x11	RegLEDDriverEnable	0x00	7:0	Enables LED Driver for each [output-configured] IO 0 : LED Driver is disabled 1 : LED Driver is enabled
0x12	RegDebounceConfig	0x00	7:3	Unused
			2:0	Debounce time (Cf. §4.5.1) 000: 0.5ms x 2MHz/fOSC 001: 1ms x 2MHz/fOSC 010: 2ms x 2MHz/fOSC 011: 4ms x 2MHz/fOSC 100: 8ms x 2MHz/fOSC 101: 16ms x 2MHz/fOSC 110: 32ms x 2MHz/fOSC 111: 64ms x 2MHz/fOSC
0x13	RegDebounceEnable	0x00	7:0	Enables debouncing for each [input-configured] IO 0 : Debouncing is disabled 1 : Debouncing is enabled
0x14	RegKeyConfig	0x00	7	Unused
			6:5	Number of rows (outputs) + key scan enable 00 : Key scan OFF 01 : 2 rows – IO[0:1] 10 : 3 rows – IO[0:2] 11 : 4 rows – IO[0:3]
			4:3	Number of columns (inputs) 00 : 1 column – IO[4] 01 : 2 columns – IO[4:5] 10 : 3 columns – IO[4:6] 11 : 4 columns – IO[4:7]
			2:0	Scan time per row (must be set above debounce time). 000 : 1ms x 2MHz/fOSC 001 : 2ms x 2MHz/fOSC 010 : 4ms x 2MHz/fOSC 011 : 8ms x 2MHz/fOSC 100 : 16ms x 2MHz/fOSC 101 : 32ms x 2MHz/fOSC 110 : 64ms x 2MHz/fOSC 111 : 128ms x 2MHz/fOSC
0x15	RegKeyData	0xFF	7:0	Key which generated NINT (active low) Ex: RegKeyData=11011110 => key [IO5;IO0] has been pressed and generated NINT When read it is automatically cleared together with NINT and key scan continues.
0xXX	RegTOnX	0x00	7:5	Unused
			4:0	ON Time of IO[X]: 0 : Infinite (Static mode, TOn directly controlled by RegData, Cf §4.8.2) 1 - 15 : $TOnX = 64 * RegTOnX * (255/ClkX)$ 16 - 31 : $TOnX = 512 * RegTOnX * (255/ClkX)$
0xXX	RegIOnX	0xFF	7:0	ON Intensity of IO[X] - Linear mode : $IOnX = RegIOnX$ - Logarithmic mode (fading capable IOs only) : $IOnX = f(RegIOnX)$ , Cf §4.8.5
0xXX	RegOffX	0x00	7:3	OFF Time of IO[X]: 0 : Infinite (Single shot mode, TOff directly controlled by RegData, Cf §4.8.3) 1 - 15 : $TOffX = 64 * RegOffX[7:3] * (255/ClkX)$ 16 - 31 : $TOffX = 512 * RegOffX[7:3] * (255/ClkX)$
			2:0	OFF Intensity of IO[X] - Linear mode : $IOffX = 4 * RegOff[2:0]$ - Logarithmic mode (fading capable IOs only) : $IOffX = f(4 * RegOffX[2:0])$ , Cf §4.8.5
0xXX	RegTRiseX	0x00	7:5	Unused

**ADVANCED COMMUNICATIONS & SENSING**

			4:0	Fade In setting of IO[X] 0 : OFF 1 - 15 : $TRiseX = (RegOnX - (4xRegOffX[2:0])) * RegTRiseX * (255/ClkX)$ 16 - 31 : $TRiseX = 16 * (RegOnX - (4xRegOffX[2:0])) * RegTRiseX * (255/ClkX)$
0xXX	<b>RegTFallX</b>	0x00	7:5	Unused
			4:0	Fade Out setting of IO[X] 0 : OFF 1 - 15 : $TFallX = (RegOnX - (4xRegOffX[2:0])) * RegTFallX * (255/ClkX)$ 16 - 31 : $TFallX = 16 * (RegOnX - (4xRegOffX[2:0])) * RegTFallX * (255/ClkX)$
0x2A	<b>RegHighInput</b>	0x00	7:0	Enables high input mode for each [input-configured] IO 0 : OFF. VIH max = 3.6V and VCCx min = 1.2V 1 : ON. VIH max = 5.5V and VCCx min = 1.65V
0x7D	<b>RegReset</b>	0x00	7:0	Software reset register Writing consecutively 0x12 and 0x34 will reset the device (same as POR) Always reads 0.

*Table 8 – SX1511B Configuration Registers Description*