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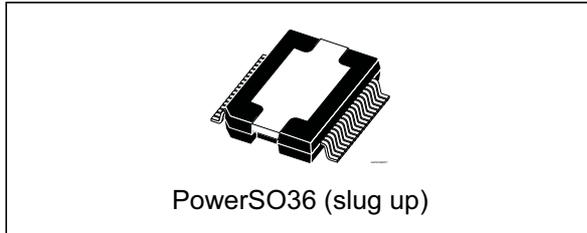
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## 4 x 50 W differential power amplifier with full I<sup>2</sup>C diagnostics, high efficiency and low voltage operation

Datasheet - production data



### Features

- Multipower BCD technology
- MOSFET output power stage
- DMOS power output
- Differential input
- Class SB high efficiency
- High output power capability:
  - 4x28 W/4 Ω @ 14.4 V, f = 1 kHz, 10% THD
  - 4x50 W/2 Ω @ 14.4 V, f = 1 kHz, 10% THD
- Max power 4 x 75 W / 2 Ω
- Full I<sup>2</sup>C bus driving:
  - Standby
  - Independent front/rear soft play/mute
  - Selectable gain 26 dB /16 dB (for low noise line output function)
  - High efficiency enable/disable
  - I<sup>2</sup>C bus digital diagnostics (including DC bus AC load detection)
- Fault detection through integrated diagnostics
- DC offset detection
- Four independent short circuit protection

- Clipping detector pin with selectable threshold (2 %/10 %)
- Standby/mute pin
- Linear thermal shutdown with multiple thermal warning
- ESD protection
- Very robust against any kind of misconnection
- Improved SVR suppression during battery transients
- Capable to play down to 6 V (e.g. “Start-stop”)

### Description

The TDA7569BDLVPD is the most advanced BCD technology quad bridge car radio amplifier, including a wide range of innovative features.

The TDA7569BDLVPD is equipped with the most complete diagnostics array that communicates the status of each speaker through the I<sup>2</sup>C bus. The differential input stage improves the disturbance rejection.

The dissipated output power under average listening condition is significantly reduced when compared to the conventional class AB solutions, thanks to the innovative internal design. Moreover it has been designed to be very robust against several kinds of misconnections.

It is moreover compliant to the most recent OEM specifications for low voltage operation (so called 'start-stop' battery profile during engine stop), helping car manufacturers to reduce the overall emissions and thus contributing to environment protection.

**Table 1. Device summary**

Order code	Package	Packing
TDA7569BDLVPD	PowerSO36	Tube
TDA7569BDLVPDTR	PowerSO36	Tape and reel

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# 1 Block diagram and application circuit

Figure 1. Block diagram

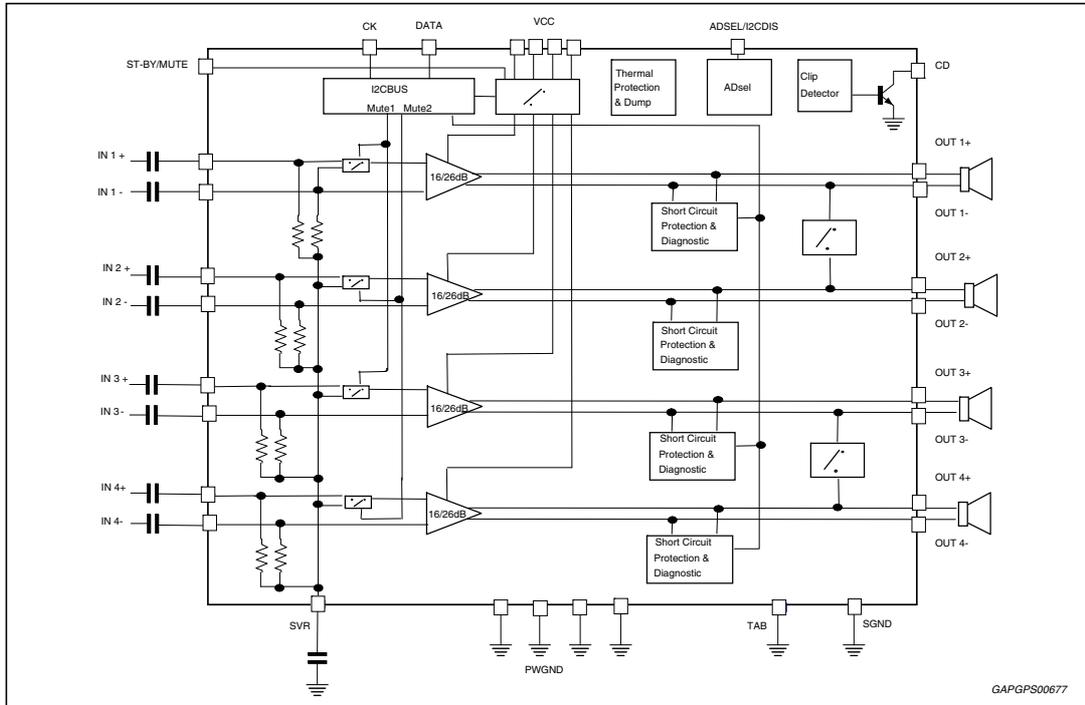
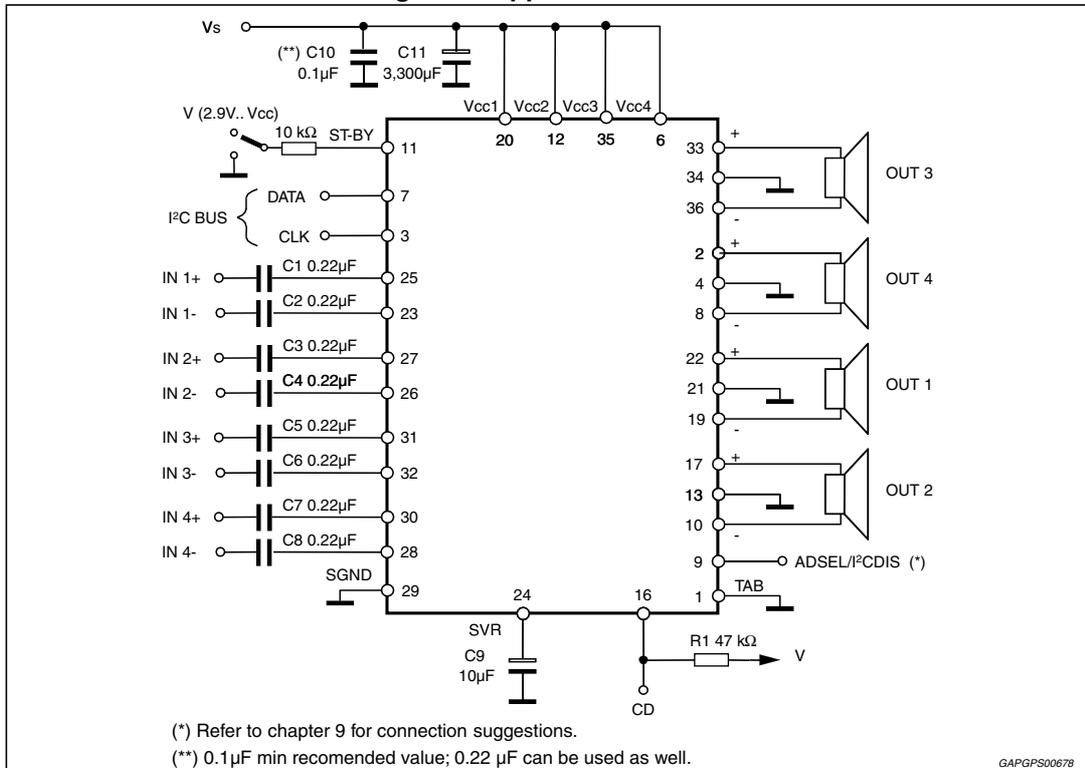
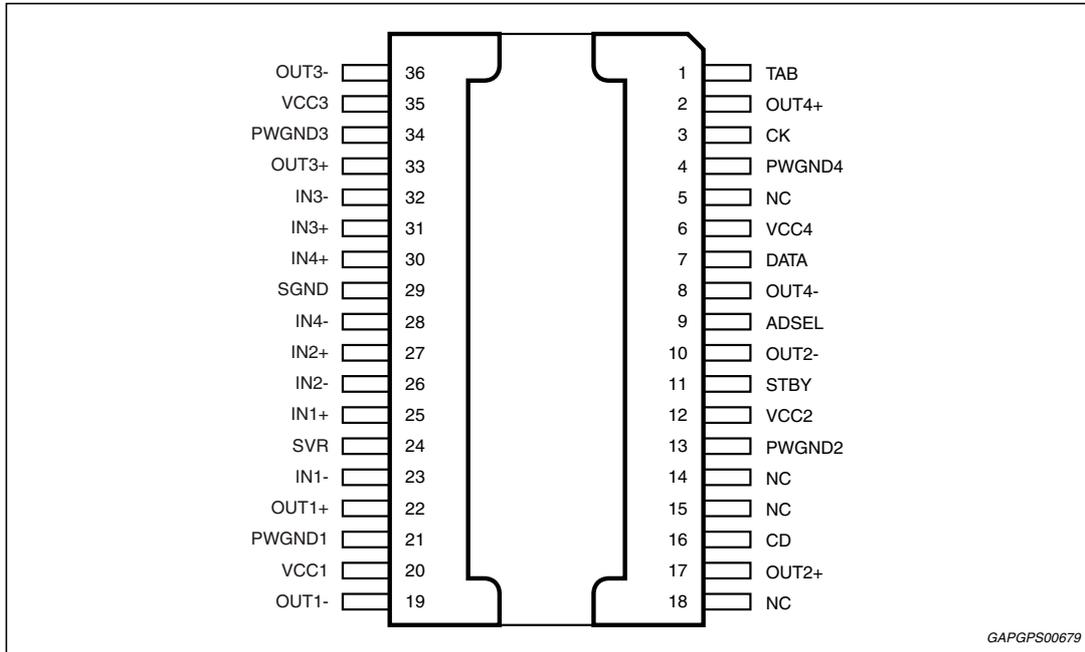


Figure 2. Application circuit



## 2 Pin description

Figure 3. Pin connection diagram (top of view)



For channel name reference: CH1 = LF, CH2 = LR, CH3 = RF, CH4 = RR.

Table 2. Pin list description

Pin #	Pin name	Function
1	TAB	-
2	OUT4+	Channel 4, + output
3	CK	I <sup>2</sup> C bus clock/HE selector
4	PWGND4	Channel 4 output power ground
5	NC	Not connected
6	VCC4	Supply voltage pin 4
7	DATA	I <sup>2</sup> C bus data pin/gain selector
8	OUT4-	Channel 4, - output
9	ADSEL	Address selector pin/ I <sup>2</sup> C bus disable (legacy select)
10	OUT2-	Channel 2, - output
11	STBY	Standby pin
12	VCC2	Supply voltage pin 2
13	PWGND2	Channel 2 output power ground
14	NC	Not connected
15	NC	Not connected
16	CD	Clip detector output pin

Table 2. Pin list description (continued)

Pin #	Pin name	Function
17	OUT2+	Channel 2, + output
18	NC	Not connected
19	OUT1-	Channel 1, - output
20	VCC1	Supply voltage pin1
21	PWGND1	Channel 1 output power ground
22	OUT1+	Channel 1, + output
23	IN1-	Channel 1, -input
24	SVR	SVR pin
25	IN1+	Channel 1, +input
26	IN2-	Channel 2, -input
27	IN2+	Channel 2, +input
28	IN4-	Channel 4, -input
29	SGND	Signal ground pin
30	IN4+	Channel 4, +input
31	IN3+	Channel 3, +input
32	IN3-	Channel 3, -input
33	OUT3+	Channel 3, + output
34	PWGND3	Channel 3 output power ground
35	VCC3	Supply voltage pin 3
36	OUT3-	Channel 3, - output

## 3 Electrical specifications

### 3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit
$V_{op}$	Operating supply voltage <sup>(1)</sup>	18	V
$V_S$	DC supply voltage	28	V
$V_{peak}$	Peak supply voltage (for $t_{max} = 50$ ms)	50	V
GNDmax	Ground pins voltage	-0.3 to 0.3	V
$V_{CK}, V_{DATA}, V_{CD}$	CK, CD and DATA pin voltage	-0.3 to 5.5	V
$V_{stby}$	STBY pin voltage	-0.3 to $V_{op}$	V
$I_O$	Output peak current (not repetitive $t_{max} = 100$ ms)	8	A
	Output peak current (repetitive $f > 10$ kHz)	6	
$P_{tot}$	Power dissipation $T_{case} = 70^\circ\text{C}$ <sup>(2)</sup>	80	W
$T_{stg}, T_j$	Storage and junction temperature <sup>(3)</sup>	-55 to 150	$^\circ\text{C}$
$T_{amb}$	Operative temperature range	-40 to 105	$^\circ\text{C}$

- For  $R_L = 2 \Omega$ , the output current limit can be reached at  $V_{op} > 16$  V (internal self-protections can be triggered).
- This is max theoretical value, for power dissipation in real application conditions please refer to curves reported in [Section 3.4: Electrical characteristics curves](#).
- A suitable heatsink/dissipation system should be used to keep  $T_j$  inside the specified limits.

### 3.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Value	Unit
$R_{th\ j-case}$	Thermal resistance junction-to-case	Max. 1	$^\circ\text{C}/\text{W}$

### 3.3 Electrical characteristics

Refer to the test circuit,  $V_S = 14.4\text{ V}$ ;  $R_L = 4\ \Omega$ ;  $f = 1\text{ kHz}$ ;  $G_V = 26\text{ dB}$ ;  $T_{\text{amb}} = 25\text{ }^\circ\text{C}$ ; unless otherwise specified.

Tested at  $T_{\text{amb}} = 25\text{ }^\circ\text{C}$  and  $T_{\text{hot}} = 105\text{ }^\circ\text{C}$ ; functionality guaranteed for  $T_J = -40\text{ }^\circ\text{C}$  to  $150\text{ }^\circ\text{C}$ .

**Table 5. Electrical characteristics**

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
<b>General characteristics</b>						
$V_S$	Supply voltage range	$R_L = 4\ \Omega$	6	-	18	V
		$R_L = 2\ \Omega$	6	-	16 <sup>(1)</sup>	V
$I_d$	Total quiescent drain current	-	-	160	250	mA
$R_{IN}$	Input impedance (differential)	-	90	115	140	K $\Omega$
$V_{AM}$	Min. supply mute threshold	IB1(D7) = 1; Signal attenuation -6 dB	7	-	8	V
		IB1(D7) = 0 (default); <sup>(2)</sup> Signal attenuation -6 dB	5	-	5.8	
$V_{OS}$	Offset voltage	Mute & play	-80	-	80	mV
$V_{dth}$	Dump threshold	-	18.5	-	20.5	V
$I_{SB}$	Standby current	$V_{\text{standby}} = 0$	-	1	5	$\mu\text{A}$
SVR	Supply voltage rejection	$f = 100\text{ Hz to }10\text{ kHz}$ ; $V_r = 1\text{ Vpk}$ ; $R_g = 600\ \Omega$	60	70	-	dB
$T_{ON}$	Turn on timing (Mute play transition)	D2/D1 (IB1) 0 to 1	-	25	40	ms
$T_{OFF}$	Turn off timing (Play mute transition)	D2/D1 (IB1) 1 to 0	-	25	40	ms
$TH_{\text{WARN1}}$	Average junction temperature for TH warning 1	DB1 (D7) = 1	-	160	-	$^\circ\text{C}$
$TH_{\text{WARN2}}$	Average junction temperature for TH warning 2	DB4 (D7) = 1	-	145	-	
$TH_{\text{WARN3}}$	Average junction temperature for TH warning 3	DB4 (D6) = 1	-	125	-	
<b>Audio performances</b>						
$P_O$	Output power	Max. power <sup>(3)</sup> $V_S = 15.2\text{ V}$ , $R_L = 4\ \Omega$	-	50	-	W
		THD = 10 %, $R_L = 4\ \Omega$	25	28	-	W
		THD = 1 %, $R_L = 4\ \Omega$	20	22	-	W
		$R_L = 2\ \Omega$ ; THD 10 %	40	50	-	W
		$R_L = 2\ \Omega$ ; THD 1 %	32	40	-	W
		$R_L = 2\ \Omega$ ; Max. power <sup>(3)</sup> $V_S = 14.4\text{ V}$	60	75	-	W
	Max power@ $V_S = 6\text{ V}$ , $R_L = 4\ \Omega$	-	6	-	W	

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
THD	Total harmonic distortion	$P_O = 1 \text{ W to } 10 \text{ W}$ ; STD mode	-	0.015	0.1	%
		HE MODE; $P_O = 1.5 \text{ W}$	-	0.05	0.1	%
		HE MODE; $P_O = 8 \text{ W}$	-	0.1	0.5	%
		$P_O = 1\text{-}10 \text{ W}$ , $f = 10 \text{ kHz}$	-	0.15	0.5	%
		$G_V = 16 \text{ dB}$ ; STD Mode $V_O = 0.1 \text{ to } 5 \text{ VRMS}$	-	0.02	0.05	%
$C_T$	Cross talk	$f = 1 \text{ kHz to } 10 \text{ kHz}$ , $R_g = 600 \Omega$	50	70	-	dB
$G_{V1}$	Voltage gain 1	-	25	26	27	dB
$\Delta G_{V1}$	Voltage gain match 1	-	-1	-	1	dB
$G_{V2}$	Voltage gain 2	-	15	16	17	dB
$\Delta G_{V2}$	Voltage gain match 2	-	-1	-	1	dB
$E_{IN1}$	Output noise voltage 1	$R_g = 600 \Omega$ 20 Hz to 22 kHz	-	45	60	$\mu\text{V}$
$E_{IN2}$	Output noise voltage 2	$R_g = 600 \Omega$ ; $G_V = 16 \text{ dB}$ 20 Hz to 22 kHz	-	20	30	$\mu\text{V}$
BW	Power bandwidth	-	100	-	-	kHz
CMRR	Input CMRR	$V_{CM} = 1 \text{ Vpk-pk}$ ; $R_g = 0 \Omega$	-	70	-	dB
$\Delta V_{OITU}$	ITU Pop filter output voltage	<b>Standby to Mute and Mute to Standby transition</b> $T_{amb} = 25 \text{ }^\circ\text{C}$ , ITU-R 2K, $C_{svr} = 10 \mu\text{F}$ $V_s = 14.4 \text{ V}$	-7.5	-	+7.5	mV
		<b>Mute to Play transition</b> $T_{amb} = 25 \text{ }^\circ\text{C}$ , ITU-R 2K, $V_s = 14.4 \text{ V}^{(4)}$	-7.5	-	+7.5	mV
		<b>Play to Mute transition</b> $T_{amb} = 25 \text{ }^\circ\text{C}$ , ITU-R 2K, $V_s = 14.4 \text{ V}^{(5)}$	-7.5	-	+7.5	mV
<b>Clip detector</b>						
$CD_{LK}$	Clip det. high leakage current	CD off / $V_{CD} = 5.5 \text{ V}$	-	0	5	$\mu\text{A}$
$CD_{SAT}$	Clip det sat. voltage	CD on; $I_{CD} = 1 \text{ mA}$	-	-	300	mV
$CD_{THD}$	Clip det THD level	D0 (IB1) = 1	5	10	15	%
		D0 (IB1) = 0	1	2	3	%
<b>Control pin characteristics</b>						
$V_{SBY}$	Standby/mute pin for standby	-	0	-	1.2	V
$V_{MU}$	Standby/mute pin for mute	-	2.9	-	3.5	V
$V_{OP}$	Standby/mute pin for operating	-	4.5	-	18	V

Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
I <sub>MU</sub>	Standby/mute pin current	V <sub>st-by/mute</sub> = 4.5 V	-	1	5	μA
		V <sub>st-by/mute</sub> < 1.2 V	-	0	5	μA
A <sub>SB</sub>	Standby attenuation	-	90	110	-	dB
A <sub>M</sub>	Mute attenuation	-	80	100	-	dB
<b>Turn on diagnostics 1 (Power amplifier mode)</b>						
Pgnd	Short to GND det. (below this limit, the Output is considered in short circuit to GND)	Power amplifier in standby	-	-	1.2	V
Pvs	Short to Vs det. (above this limit, the output is considered in short circuit to Vs)		Vs -1.2	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults).		1.8	-	Vs -1.8	V
Lsc	Shorted load det.		-	-	0.5	Ω
Lop	Open load det.		85	-	-	Ω
Lnop	Normal load det.		1.5	-	45	Ω
<b>Turn on diagnostics 2 (Line driver mode)</b>						
Pgnd	Short to GND det. (below this limit, the output is considered in short circuit to GND)	Power amplifier in standby	-	-	1.2	V
Pvs	Short to Vs det. (above this limit, the output is considered in short circuit to Vs)	-	Vs -1.2	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults).	-	1.8	-	Vs -1.8	V
Lsc	Shorted load det.	-	-	-	1.5	Ω
Lop	Open load det.	-	330	-	-	Ω
Lnop	Normal load det.	-	7	-	180	Ω
<b>Permanent diagnostics 2 (Power amplifier mode or line driver mode)</b>						
Pgnd	Short to GND det. (below this limit, the Output is considered in short circuit to GND)	Power amplifier in mute or play, one or more short circuits protection activated	-	-	1.2	V
Pvs	Short to Vs det. (above this limit, the output is considered in short circuit to Vs)		Vs -1.2	-	-	V
Pnop	Normal operation thresholds. (Within these limits, the output is considered without faults).		1.8	-	Vs -1.8	V

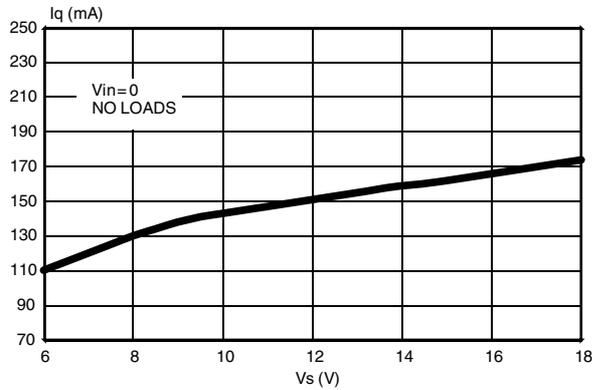
Table 5. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
L <sub>SC</sub>	Shorted load det.	Power amplifier mode	-	-	0.5	Ω
		Line driver mode	-	-	1.5	Ω
V <sub>O</sub>	Offset detection	Power amplifier in play, AC input signals = 0	±1.5	±2	±2.5	V
I <sub>NLH</sub>	Normal load current detection	V <sub>O</sub> < (V <sub>S</sub> -5)pk, IB2 (D7) = 0	500	-	-	mA
I <sub>OLH</sub>	Open load current detection		-	-	250	mA
I <sub>NLL</sub>	Normal load current detection	V <sub>O</sub> < (V <sub>S</sub> -5)pk, IB2 (D7) = 1	250	-	-	mA
I <sub>OLL</sub>	Open load current detection		-	-	125	mA
<b>I<sup>2</sup>C bus interface</b>						
S <sub>CL</sub>	Clock frequency	-	-	-	400	kHz
V <sub>IL</sub>	Input low voltage	-	-	-	1.5	V
V <sub>IH</sub>	Input high voltage	-	2.3	-	-	V

- When V<sub>S</sub> > 16 V the output current limit is reached (triggering embedded internal protections).
- In legacy mode only low threshold option is available.
- Saturated square wave output.
- Voltage ramp on STBY pin:  
from 3.3 V to 4.2 V in t ≥ 40 ms.  
In case of I<sup>2</sup>C mode command IB1(D1) = 1 (Mute → Unmute rear channels) and/or IB1(D2) = 1 (Mute → Unmute front channels) must be transmitted before to start the voltage ramp on STBY pin.
- Voltage ramp on STBY pin:  
from 4.05 V to 3.55 V in t ≥ 40 ms.  
In case of I<sup>2</sup>C mode command IB1(D1) = 0 (Unmute → Mute rear channels) and/or IB1(D2) = 0 (Unmute → Mute front channels) must be NOT transmitted before to start the voltage ramp on STBY pin.

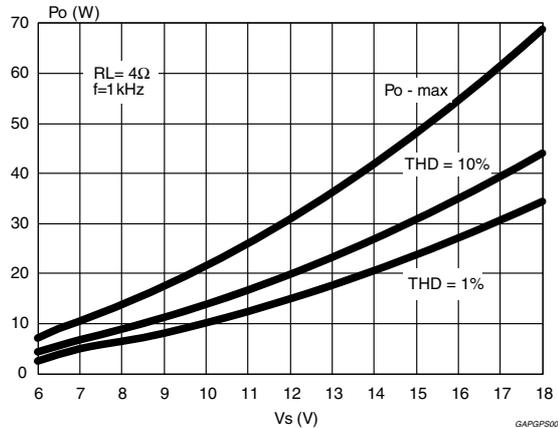
### 3.4 Electrical characteristics curves

Figure 4. Quiescent current vs. supply voltage



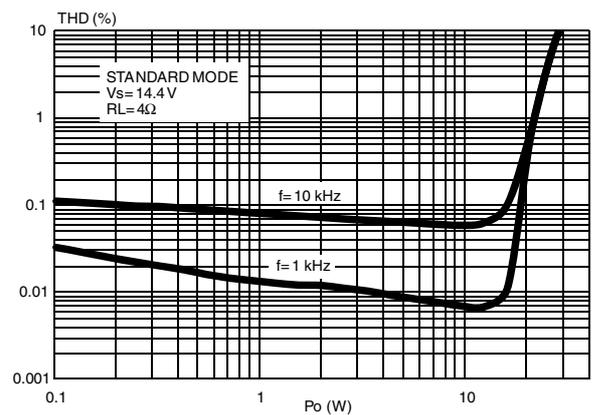
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Figure 5. Output power vs. supply voltage (4 Ω)



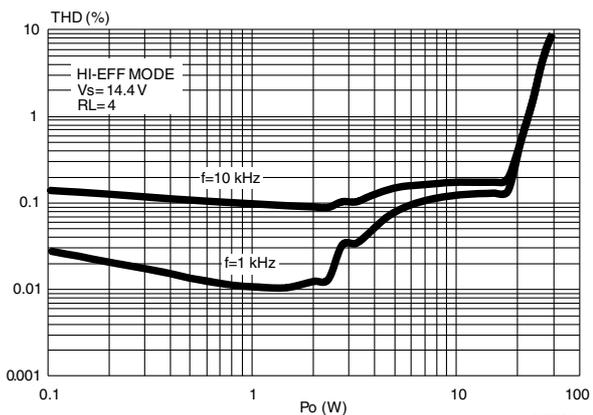
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Figure 6. Distortion vs. output power (4 Ω, STD)



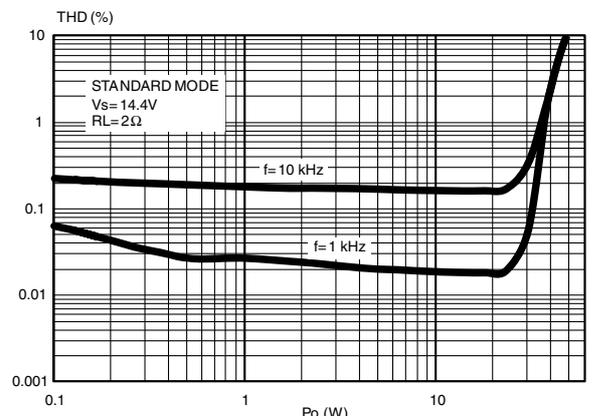
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Figure 7. Distortion vs. output power (4 Ω, HI-EFF)



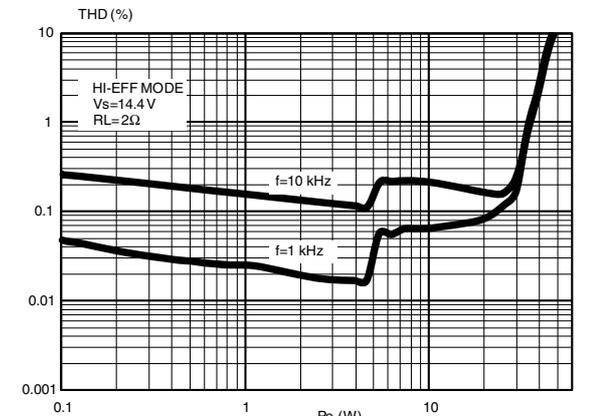
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Figure 8. Distortion vs. output power (2 Ω, STD)



GAPGPS00209

Figure 9. Distortion vs. output power (2 Ω, HI-EFF)



GAPGPS00208

Figure 10. Distortion vs. frequency (2 Ω)

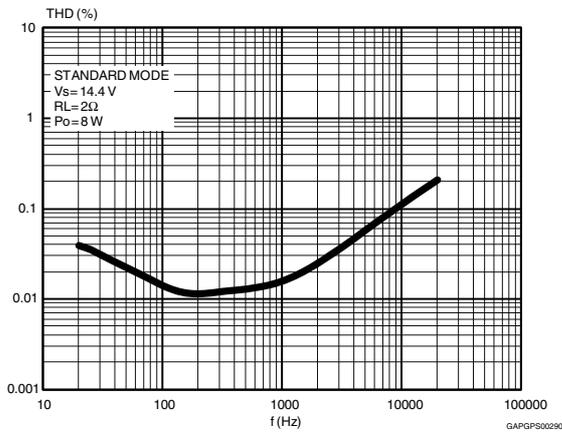


Figure 11. Distortion vs. output power  $V_s = 6\text{ V}$  (4 Ω, STD)

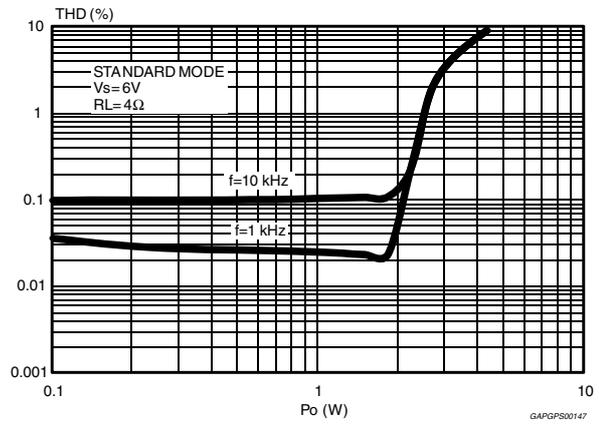


Figure 12. Distortion vs. frequency (4 Ω)

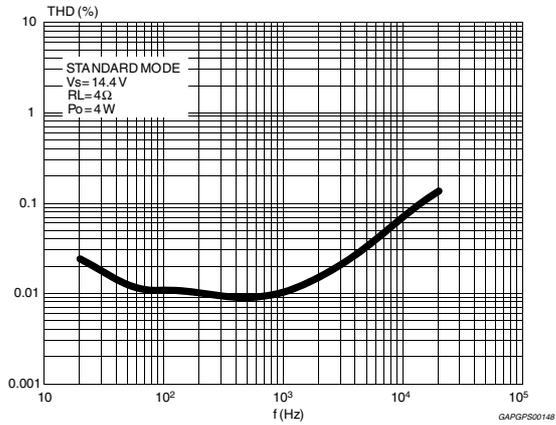


Figure 13. Crosstalk vs. frequency

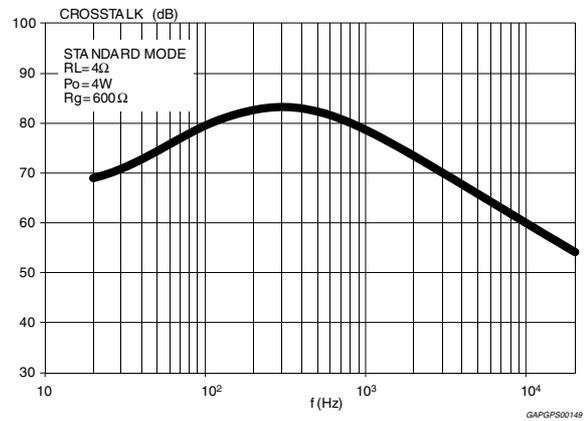


Figure 14. Supply voltage rejection vs. frequency

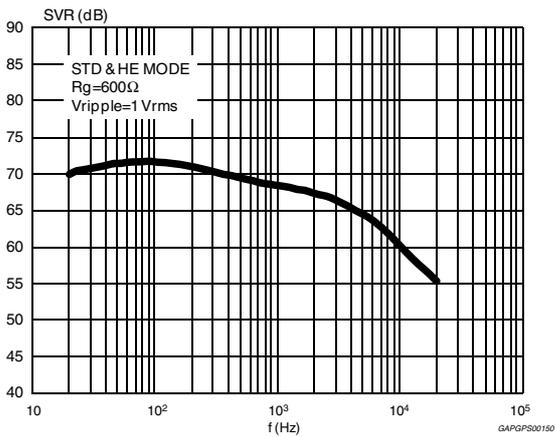
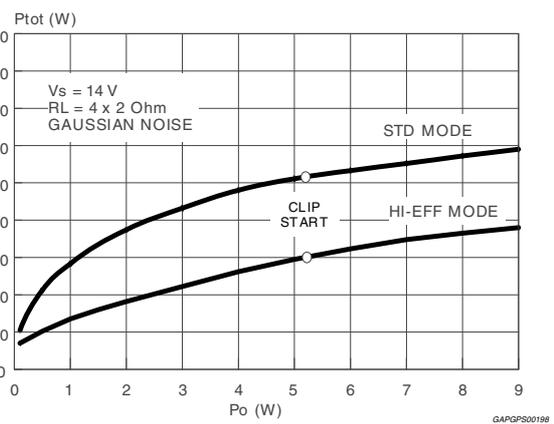
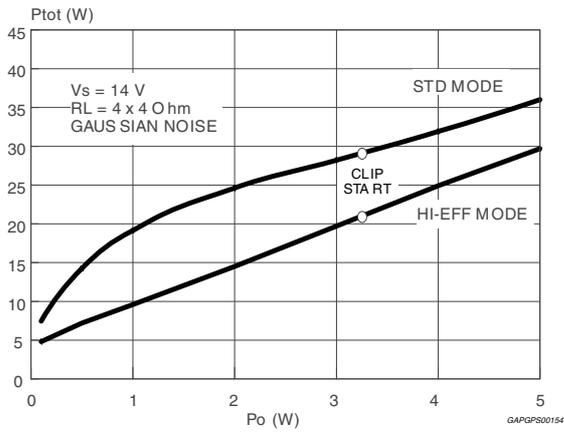


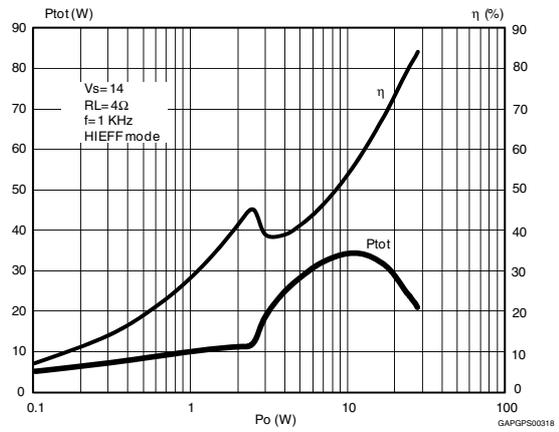
Figure 15. Power dissipation vs. average output power (audio program simulation, 2 Ω)



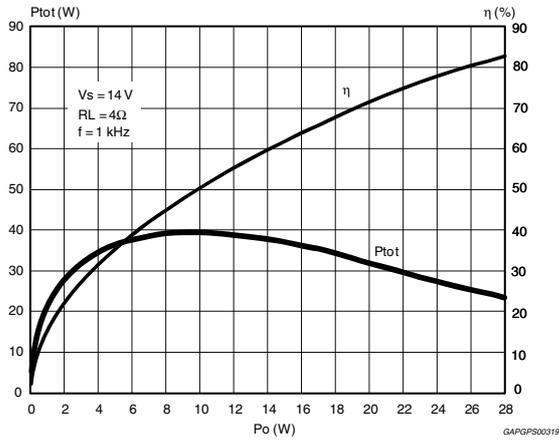
**Figure 16. Power dissipation vs. average output power (audio program simulation, 4 Ω)**



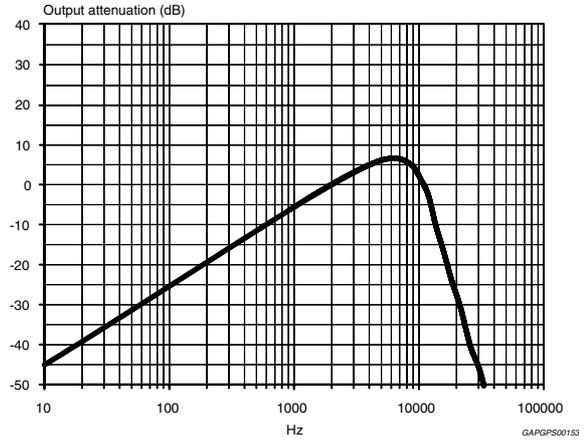
**Figure 17. Total power dissipation and efficiency vs. output power (4 Ω, HI-EFF, Sine)**



**Figure 18. Total power dissipation and efficiency vs. output power (4 Ω, STD, Sine)**



**Figure 19. ITU R-ARM frequency response, weighting filter for transient pop**



## 4 Diagnostics functional description

### 4.1 Turn-on diagnostic

It is strongly recommended to activate this feature at turn-on (standby out) with I<sup>2</sup>C bus request. Detectable output faults are:

- SHORT TO GND
- SHORT TO V<sub>s</sub>
- SHORT ACROSS THE SPEAKER
- OPEN SPEAKER

To verify if any of the above misconnections are in place, a subsonic (inaudible) current pulse (Figure 20) is internally generated, sent through the speaker(s) and sunk back. The Turn On diagnostic status is internally stored until a successive diagnostic pulse is requested (after a I<sup>2</sup>C reading).

If the "standby out" and "diag. enable" commands are both given through a single programming step, the pulse takes place first (the power stage stays 'off' during the pulses, showing high impedance at the outputs).

Afterwards, when the Amplifier is biased, the PERMANENT diagnostic takes place. The previous turn-on state is kept until a short appears at the outputs.

Figure 20. Turn - on diagnostic: working principle

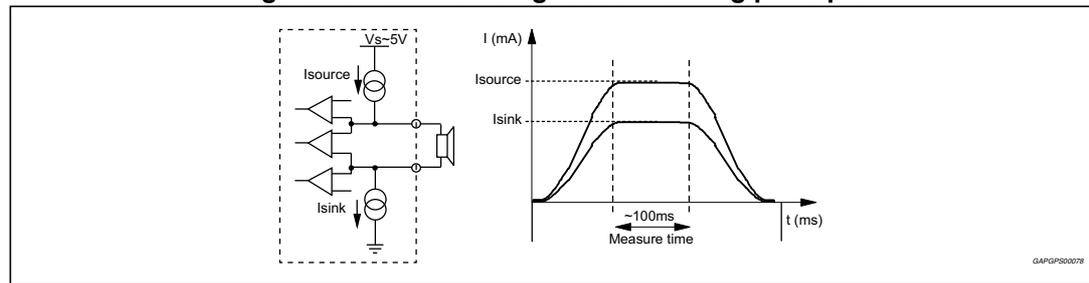


Figure 21 and 22 show SVR and OUTPUT waveforms at the turn-on (standby out) with and without turn-on diagnostic.

Figure 21. SVR and output behavior (Case 1: without turn-on diagnostic)

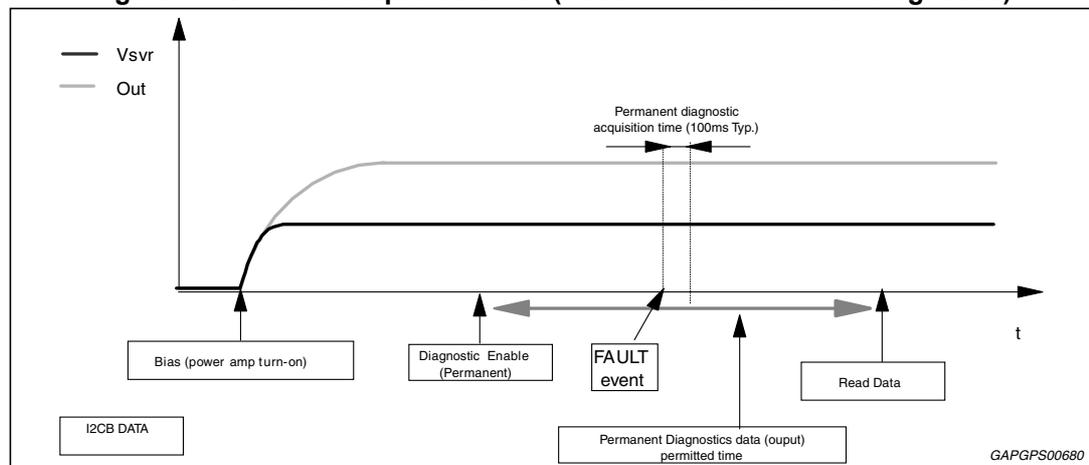
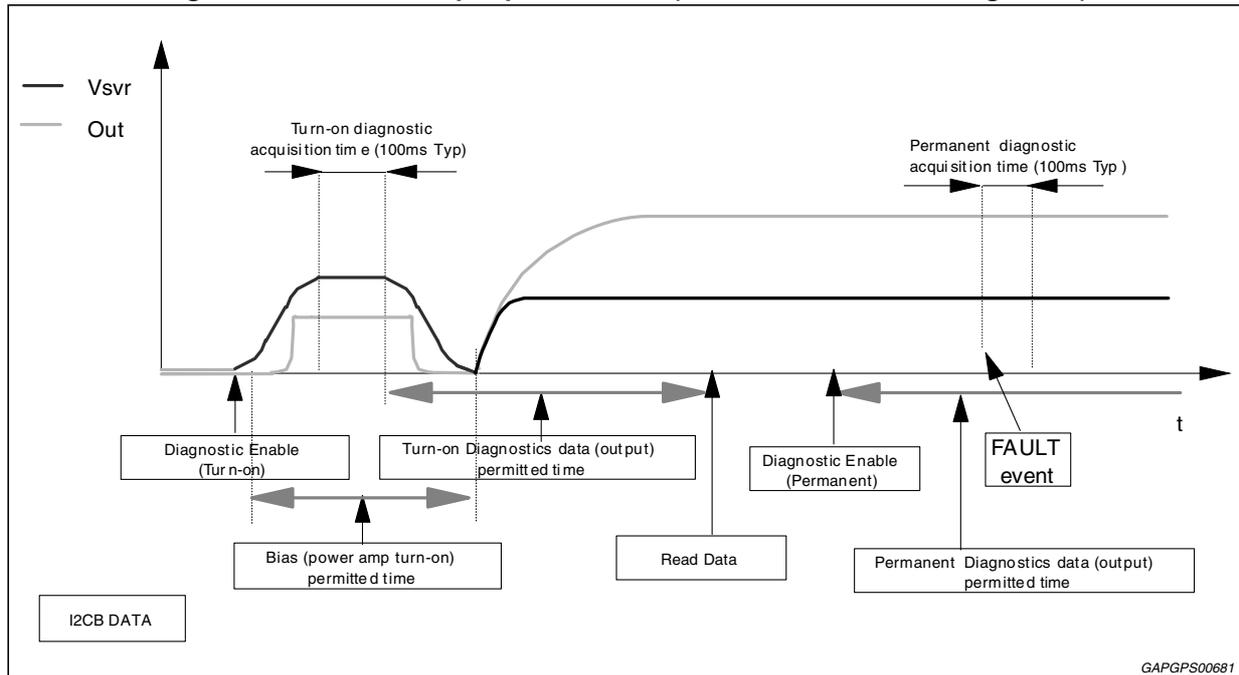
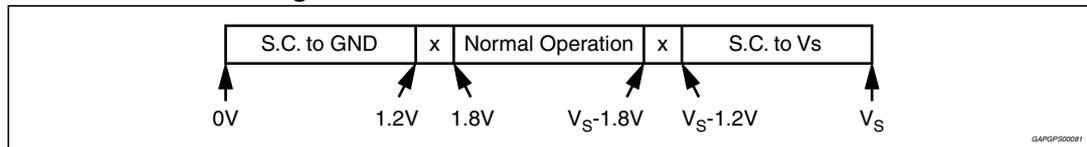


Figure 22. SVR and output pin behavior (Case 2: with turn-on diagnostic)



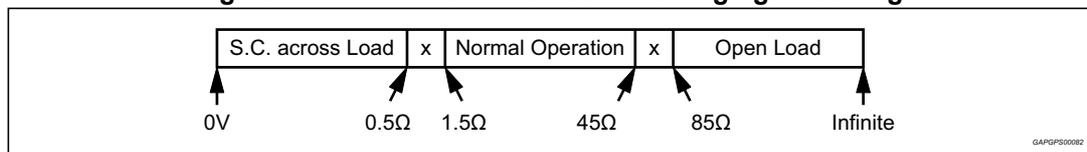
The information related to the outputs status is read and memorized at the end of the current pulse plateau. The acquisition time is 100 ms (typ.). No audible noise is generated in the process. As for SHORT TO GND / Vs the fault-detection thresholds remain unchanged from 26 dB to 16 dB gain setting. They are as follows:

Figure 23. Short circuit detection thresholds



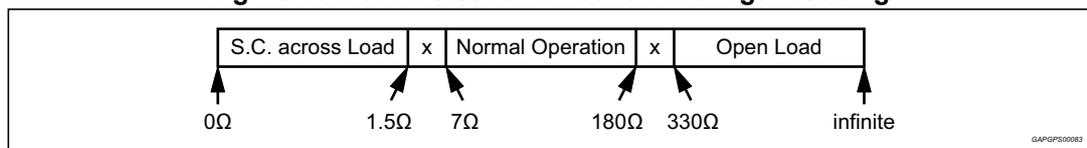
Concerning SHORT ACROSS THE SPEAKER / OPEN SPEAKER, the threshold varies from 26 dB to 16 dB gain setting, since different loads are expected (either normal speaker's impedance or high impedance). The values in case of 26 dB gain are as follows:

Figure 24. Load detection thresholds - high gain setting



If the Line-Driver mode ( $G_v = 16$  dB and Line Driver Mode diagnostic = 1) is selected, the same thresholds will change as follows:

Figure 25. Load detection threshold - low gain setting



## 4.2 Permanent diagnostics

Detectable conventional faults are:

- Short to GND
- Short to Vs
- Short across the speaker

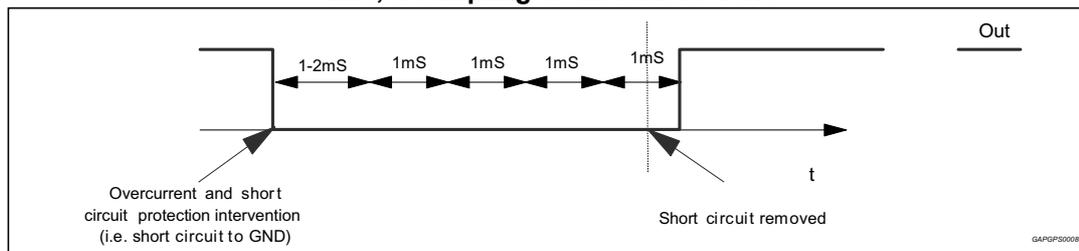
The following additional feature is provided:

- Output offset detection

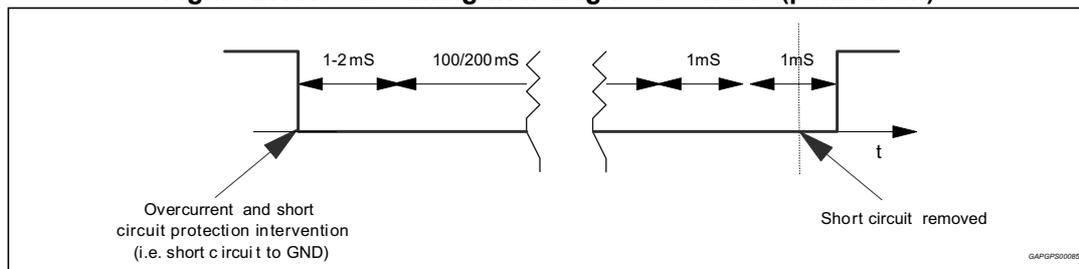
The TDA7569BDLVPD has 2 operating status:

1. **RESTART mode.** The diagnostic is not enabled. Each audio channel operates independently of each other. If any of the a.m. faults occurs, only the channel(s) interested is shut down. A check of the output status is made every 1 ms (*Figure 26*). Restart takes place when the overload is removed.
2. **DIAGNOSTIC mode.** It is enabled via I<sup>2</sup>C bus and it self activates if an output overload (such as to cause the intervention of the short-circuit protection) occurs to the speakers outputs. Once activated, the diagnostics procedure develops as follows (*Figure 27*):
  - To avoid momentary re-circulation spikes from giving erroneous diagnostics, a check of the output status is made after 1ms: if normal situation (no overloads) is detected, the diagnostic is not performed and the channel returns active.
  - Instead, if an overload is detected during the check after 1 ms, then a diagnostic cycle having a duration of about 100 ms is started.
  - After a diagnostic cycle, the audio channel interested by the fault is switched to RESTART mode. The relevant data are stored inside the device and can be read by the microprocessor. When one cycle has terminated, the next one is activated by an I<sup>2</sup>C reading. This is to ensure continuous diagnostics throughout the car-radio operating time.
  - To check the status of the device a sampling system is needed. The timing is chosen at microprocessor level (over half a second is recommended).

**Figure 26. Restart timing without diagnostic enable (permanent) - Each 1 mS time, a sampling of the fault is done**



**Figure 27. Restart timing with diagnostic enable (permanent)**



### 4.3 Output DC offset detection

Any DC output offset exceeding  $\pm 2$  V are signalled out. This inconvenient might occur as a consequence of initially defective or aged and worn-out input capacitors feeding a DC component to the inputs, so putting the speakers at risk of overheating.

This diagnostic has to be performed with low-level output AC signal (or  $V_{in} = 0$ ).

The test is run with selectable time duration by microprocessor (from a "start" to a "stop" command):

- START = Last reading operation or setting IB1 - D5 - (OFFSET enable) to 1
- STOP = Actual reading operation

Excess offset is signalled out if it is persistent for all the assigned testing time. This feature is disabled if any overloads leading to activation of the short-circuit protection occurs in the process.

### 4.4 AC diagnostic

It is targeted at detecting accidental disconnection of tweeters in 2-way speaker and, more in general, presence of capacitive (AC) coupled loads.

This diagnostic is based on the notion that the overall speaker's impedance (woofer + parallel tweeter) will tend to increase towards high frequencies if the tweeter gets disconnected, because the remaining speaker (woofer) would be out of its operating range (high impedance). The diagnostic decision is made according to peak output current thresholds, and it is enabled by setting (IB2-D2) = 1. Two different detection levels are available:

- High current threshold IB2 (D7) = 0  
   $I_{out} > 500$  mA<sub>pk</sub> = normal status  
   $I_{out} < 250$  mA<sub>pk</sub> = open tweeter
- Low current threshold IB2 (D7) = 1  
   $I_{out} > 250$  mA<sub>pk</sub> = normal status  
   $I_{out} < 125$  mA<sub>pk</sub> = open tweeter

To correctly implement this feature, it is necessary to briefly provide a signal tone (with the amplifier in "play") whose frequency and magnitude are such as to produce an output current higher than 500 mA<sub>pk</sub> with IB2(D7) = 0 (higher than 250 mA<sub>pk</sub> with IB2(D7) = 1) in normal conditions and lower than 250 mA<sub>pk</sub> with IB2(D7) = 0 (lower than 125 mA<sub>pk</sub> with IB2(D7) = 1) when the parallel tweeter is missing/disconnected.

The test has to last for a minimum number of 3 sine cycles starting from the activation of the AC diagnostic function IB2<D2> up to the I<sup>2</sup>C reading of the results (measuring period). To confirm the presence of tweeter, it is necessary to find at least 3 current pulses over the above threshold during the measuring period, else an "open tweeter" message will be issued.

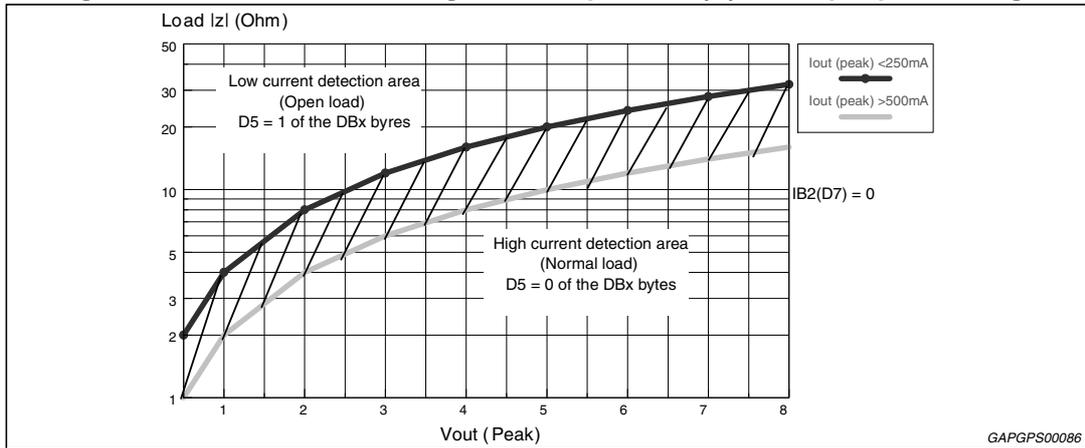
The frequency / magnitude setting of the test tone depends on the impedance characteristics of each specific speaker being used, with or without the tweeter connected (to be calculated case by case). High-frequency tones (> 10 kHz) or even ultrasonic signals are recommended for their negligible acoustic impact and also to maximize the impedance module's ratio between with tweeter-on and tweeter-off.

Figure 28 and 29 shows the load impedance as a function of the peak output voltage and the relevant diagnostic fields.

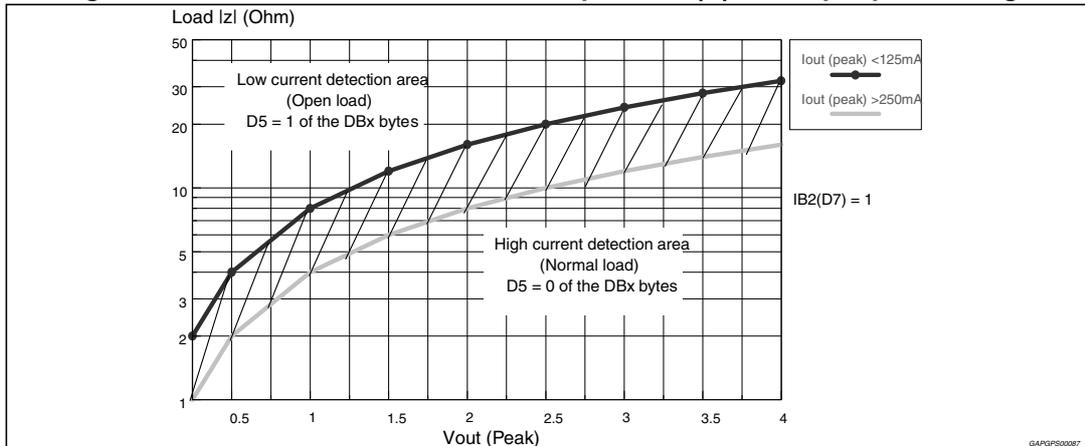
It is recommended to keep the output voltage always below 8 V (high threshold case) or 4 V (low threshold case), to avoid the circuit to saturate (causing wrong detection cases).

This feature is disabled if any overloads leading to activation of the short-circuit protection occurs in the process.

**Figure 28. Current detection high: load impedance |Z| vs. output peak voltage**



**Figure 29. Current detection low: load impedance |Z| vs. output peak voltage**



## 5 Multiple faults

When more misconnections are simultaneously in place at the audio outputs, it is guaranteed that at least one of them is initially read out. The others are notified after successive cycles of I<sup>2</sup>C reading and faults removal, provided that the diagnostic is enabled. This is true for both kinds of diagnostic (Turn on and Permanent).

The table below shows all the couples of double-fault possible. It should be taken into account that a short circuit with the 4 ohm speaker unconnected is considered as double fault.

**Table 6. Double fault table for turn on diagnostic**

	<b>S. GND</b>	<b>S. Vs</b>	<b>S. Across L.</b>	<b>Open L.</b>
<b>S. GND</b>	S. GND	S. Vs + S. GND	S. GND	S. GND
<b>S. Vs</b>	/	S. Vs	S. Vs	S. Vs
<b>S. Across L.</b>	/	/	S. Across L.	N.A.
<b>Open L.</b>	/	/	/	Open L. (*)

In Permanent Diagnostic the table is the same, with only a difference concerning Open Load(\*), which is not among the recognizable faults. Should an Open Load be present during the device's normal working, it would be detected at a subsequent Turn on Diagnostic cycle (i.e. at the successive Car Radio Turn on).

### 5.1 Faults availability

All the results coming from I<sup>2</sup>C bus, by read operations, are the consequence of measurements inside a defined period of time. If the fault is stable throughout the whole period, it will be sent out.

To guarantee always resident functions, every kind of diagnostic cycles (Turn-on, Permanent, Offset) will be reactivate after any I<sup>2</sup>C reading operation. So, when the micro reads the I<sup>2</sup>C, a new cycle will be able to start, but the read data will come from the previous diag. cycle (i.e. The device is in Turn-on state, with a short to GND, then the short is removed and micro reads I<sup>2</sup>C. The short to GND is still present in bytes, because it is the result of the previous cycle. If another I<sup>2</sup>C reading operation occurs, the bytes do not show the short). In general to observe a change in Diagnostic bytes, two I<sup>2</sup>C reading operations are necessary.

## 6 Thermal protection

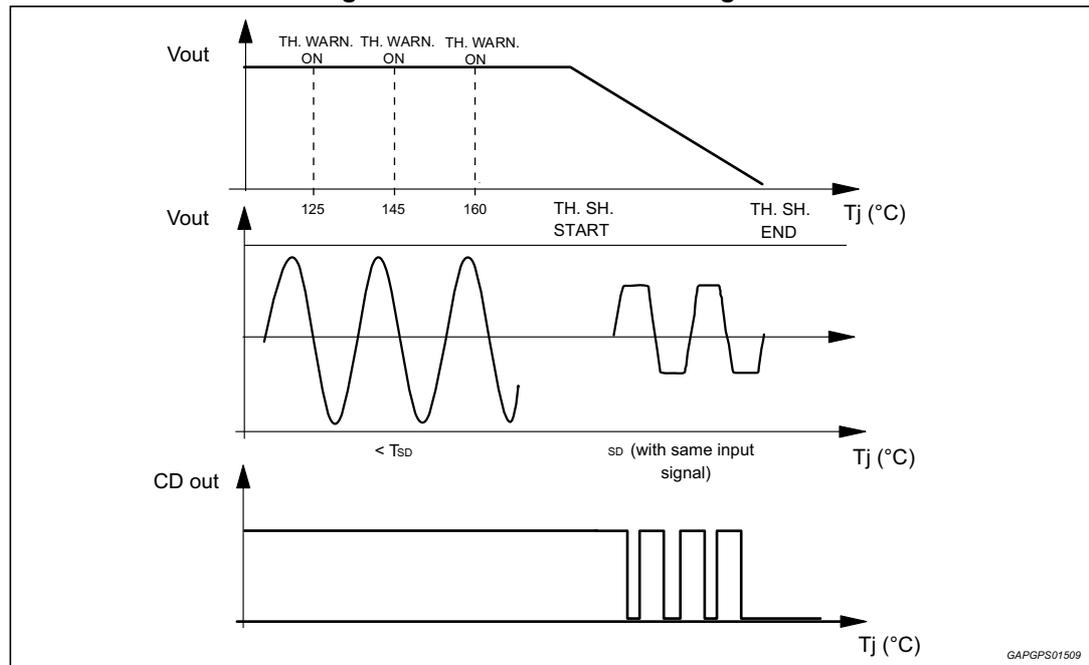
Thermal protection is implemented through thermal foldback (*Figure 30*).

Thermal foldback begins limiting the audio input to the amplifier stage as the junction temperatures rise above the normal operating range. This effectively limits the output power capability of the device thus reducing the temperature to acceptable levels without totally interrupting the operation of the device.

The output power will decrease to the point at which thermal equilibrium is reached. Thermal equilibrium will be reached when the reduction in output power reduces the dissipated power such that the die temperature falls below the thermal foldback threshold. Should the device cool, the audio level will increase until a new thermal equilibrium is reached or the amplifier reaches full power. Thermal foldback will reduce the audio output level in a linear manner.

Three Thermal warning are available through the I<sup>2</sup>C bus data. After thermal shut down threshold is reached, the CD could toggle (as shown in *Figure 30*) or stay low, depending on signal level.

**Figure 30. Thermal foldback diagram**



### 6.1 Fast muting

The muting time can be shortened to less than 1.5ms by setting (IB2) D5 = 1. This option can be useful in transient battery situations (i.e. during car engine cranking) to quickly turnoff the amplifier to avoid any audible effects caused by noise/transients being injected by preamp stages. The bit must be set back to “0” shortly after the mute transition.

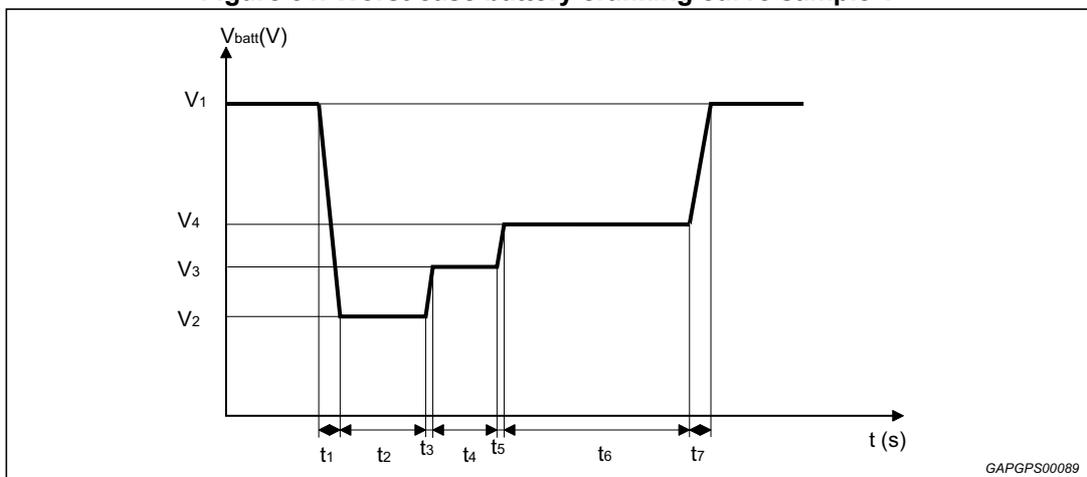
## 7 Battery transition management

### 7.1 Low voltage (“start stop”) operation

The most recent OEM specifications are requiring automatic stop of car engine at traffic light, in order to reduce emissions of polluting substances. The TDA7569BDLVPD, thanks to its innovating design, is able to play music when battery falls down to 6/7V during such conditions, without producing audible pop noise. The maximum system power will be reduced accordingly.

Worst case battery cranking curves are shown below, indicating the shape and durations of allowed battery transitions

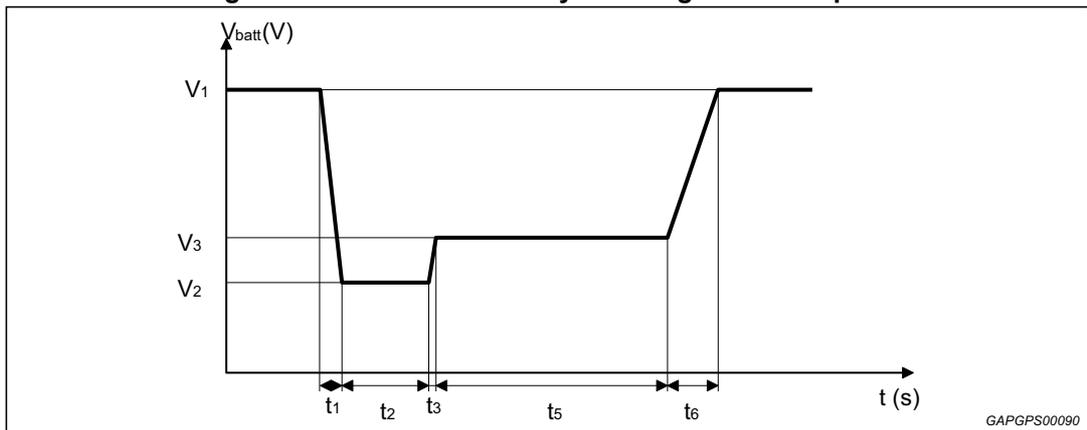
**Figure 31. Worst case battery cranking curve sample 1**



V1 = 12 V; V2 = 6 V; V3 = 7 V; V4 = 8 V

t1 = 2 ms; t2 = 50 ms; t3 = 5 ms; t4 = 300 ms; t5 = 10 ms; t6 = 1 s; t7 = 2 ms

**Figure 32. Worst case battery cranking curve sample 2**



V1 = 12 V; V2 = 6 V; V3 = 7 V

t1 = 2 ms; t2 = 5 ms; t3 = 15 ms; t5 = 1 s; t6 = 50 ms

## 7.2 Advanced battery management

In addition to compatibility with low  $V_{batt}$ , the TDA7569BDLVPD is able to sustain upwards fast battery transitions (like the one showed in *Figure 33*) without causing unwanted audible effect, thanks to the innovative circuit topology.

**Figure 33. Upwards fast battery transitions diagram**

