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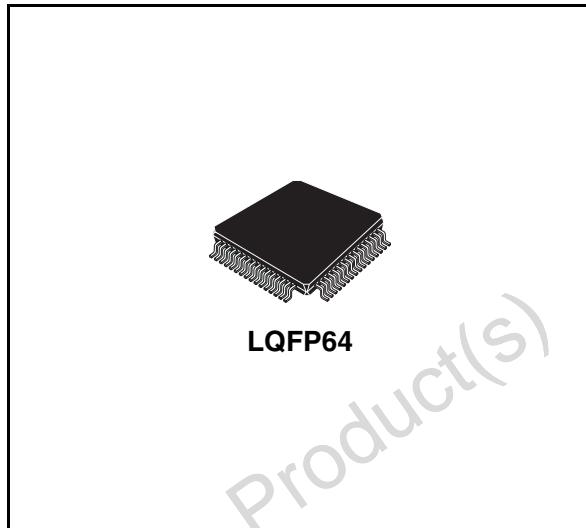
## FM/AM digital IF sampling processor

## Features

- FM/AM IF sampling DSP
- ON-CHIP analogue to digital converter for 10.7MHz IF signal conversion
- FM channel equalization
- FM adjacent channel suppression
- Reception enhancement in multipath condition
- Stereo decoder and weak signal processing
- 2 Channel serial audio interface (SAI) with sample rate converter
- I<sup>2</sup>C and buffer SPI control interfaces
- RDS filter, demodulator & decoder
- Inter processor transport interface for antenna and tuner diversity
- Front-end AGC feedback

## Description

The TDA7580 is an integrated circuit implementing an advanced mixed analogue and digital solution, to perform the signal processing



of an AM/FM channel. The HW & SW architecture has been devised to perform a digital equalization of the FM/AM channel, and a real rejection of adjacent channels and any other signals, interfering with the listening of the desired station. In severe multiple path conditions, the reception is improved to get high quality audio.

**Table 1. Device summary**

Part number	Package	Packing
TDA7580	LQFP64	Tube
TDA758013TR	LQFP64	Tape and reel

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## 1 Overview

The algorithm is self-adaptive, thus it requires no “on-the-field” adjustments after the parameters optimization.

The chip embeds a *Band Pass Sigma Delta Analogue to Digital Converter* for 10.7MHz IF conversion from a “tuner device” (the TDA7515 is highly recommended).

The 24bit DSP allows flexibility in the algorithms implementation, thus giving some freedom for customer required features. The total processing power offers a significant headroom for customer's software requirement, even when the channel equalization and the decoding software is running. the program and data memory space can be loaded from an external non volatile memory via I<sup>2</sup>C or SPI.

The oscillator module works with an external 74.1MHz quartz crystal. It has very low electro magnetic interference, as it introduces very low distortion, and in any case harmonics fall outside the radio bandwidth.

The companion tuner device receives the reference clock through a differential ended interface, which works off the oscillator module by properly dividing down the master clock frequency. That allows the overall system saving an additional crystal for the tuner.

After the IF conversion, the digitized baseband signal passes through the base band processing section, either FM or AM, depending on the listener selection. The FM base band processing comprises of stereo decoder, spike detection and noise blanking. The AM noise blanking is fully software implemented.

The internal RDS filter, demodulator and decoder features complete functions to have the output data available through either I<sup>2</sup>C or SPI interface. No DSP support is needed but at start-up, so that RDS can work in background and in parallel with other DSP processing. This mode (RDS only) allows current consumption saving for low power application modes.

An I<sup>2</sup>C/SPI interface is available for any control and communication with the main micro, as well as RDS data interface. The DSP SPI block embeds a 10 words FIFO for both transmit and receive channels, to lighten the DSP task and frequently respond to the interrupt from the control interface.

Serial audio interface (SAI) is the ideal solution for the audio data transfer, both transmit and receive: either master or slave. The flexibility of this module gives a wide choice of different protocols, including I<sup>2</sup>S. Two fully independent bidirectional data channels, with separate clocks allows the use of TDA7580 as general purpose digital audio processor.

A fully asynchronous sample rate converter (ASRC) is available as a peripheral prior to sending audio data out via the SAI, so that internal audio sampling rate (~36kHz and FM/AM mode) can be adapted by upconversion to any external rate.

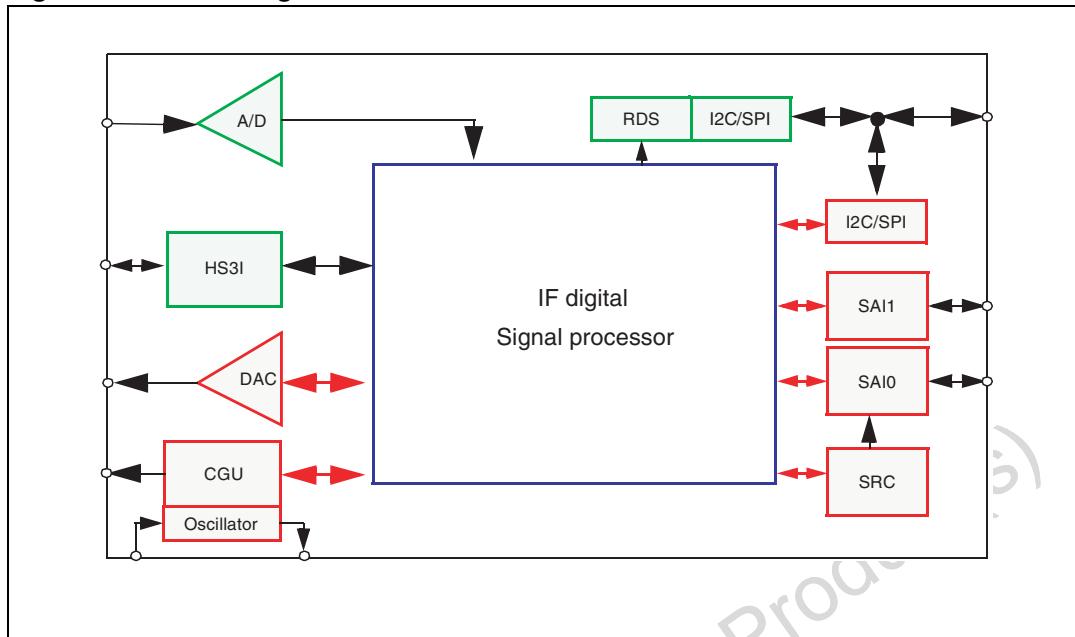
An inter processor transport interface (HS<sup>3</sup>I, high speed synchronous serial interface) is also available for a modular system which implements *Dual Tuner Diversity*, thus enhancing the overall system performance. It is about a synchronous serial interface which exchanges data up to the MPX rate. It has been designed to reduce the electro magnetic interference toward the sensitive analogue signal from the tuner.

General purpose I/O registers are connected to and controlled by the DSP, by means of memory map.

A debug and test interface is available for on chip software debug as well as for internal registers read/write operation.

## 2

## Block diagram and electrical specifications

**Figure 1.** Block diagram**Table 2.** Absolute maximum ratings

Symbol	Parameter	Value	Unit
$V_{DD}$ $V_{DD3}$	Power supplies <sup>(1)</sup>	Nom. 1.8V Nom. 3.3V	-0.5 to 2.5 -0.5 to 4.0
	Analog input or output voltage belonging to 3.3V IO ring ( $V_{DDSD}$ , $V_{DDOSC}$ )	-0.5 to 4.0	V
	Digital input or output voltage, 5V tolerant	Normal <sup>(2)</sup> Failsafe <sup>(3)</sup>	-0.5 to 6.50 -0.5 to 3.80
	All remaining digital input or output voltage	Nom. 1.8V Nom. 3.3V	-0.5 to ( $V_{DD}+0.5$ ) -0.5 to ( $V_{DD3}+0.5$ )
$T_j$	Operating junction temperature range	-40 to 125	°C
$T_{stg}$	Storage temperature	-55 to 150	°C

1.  $V_{DD3}$  refers to all of the nominal 3.3V power supplies ( $V_{DDH}$ ,  $V_{OSC}$ ,  $V_{DDSD}$ ).  $V_{DD}$  refers to all of the nominal 1.8V power supplies ( $V_{DD}$ ,  $V_{MTR}$ ).

2. During Normal Mode operation  $V_{DD3}$  is always available as specified.
3. During Fail-safe Mode operation  $V_{DD3}$  may be not available.

---

**Warning:** Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

---

**Table 3. Recommended DC operating conditions ( $T_j = -40^{\circ}\text{C}$  to  $125^{\circ}\text{C}$ )**

Symbol	Parameter	Comment	Min.	Typ.	Max.	Unit
$V_{DD}$	1.8V Power supply voltage	Core power supply	1.7	1.80	1.9	V
$V_{DDH}$	3.3V Power supply voltage <sup>(1)</sup>	IO Rings power supply (with $G_{NDH}$ )	3.15	3.30	3.45	V
$V_{OSC}$	3.3V Power supply voltage <sup>(1)</sup>	Oscillator power supply ( $G_{NDosc}$ )	3.15	3.30	3.45	V
$V_{DDSD}$	3.3V Power supply voltage <sup>(1)</sup>	IF ADC power supply (with $G_{NDSD}$ )	3.15	3.30	3.45	V
$V_{MTR}$	1.8V Power supply voltage	DAC keying and tuner clock power supply (with $G_{NDMTR}$ )	1.7	1.80	1.9	V

1.  $V_{DDH}$ ,  $V_{OSC}$ ,  $V_{DDSD}$  are also indicated in this document as  $V_{DD3}$ . All others as  $V_{DD}$ .

**Table 4. Thermal data**

Symbol	Parameter	Value	Unit
$R_{th\ j-amb}$	Thermal resistance junction to ambient	68	°C/W

## 2.1 Pin description

Figure 2. PIN connection (top view)

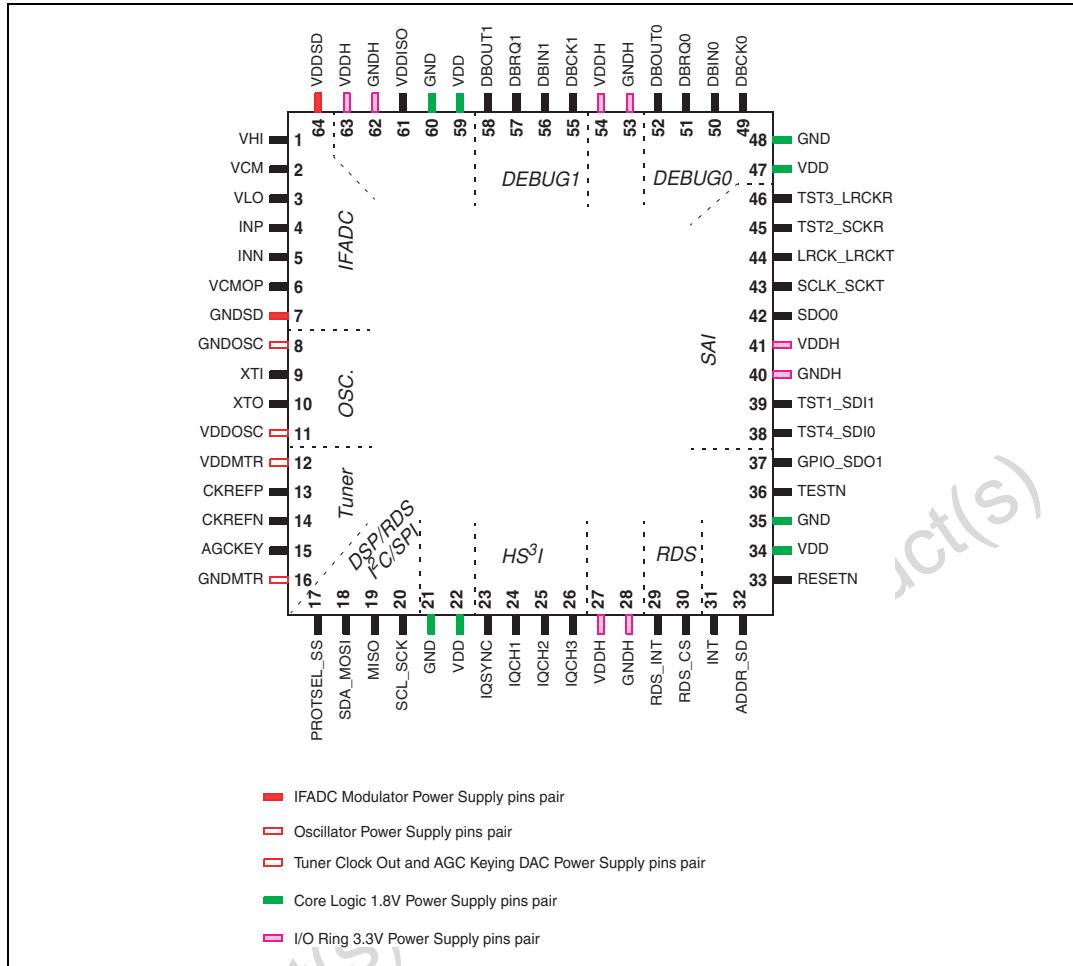


Table 5. Pin description

N°	Name	Type	Description	Notes	After Reset
1	VHI	A	Internally generated IFADC Opamps 2.65V (@V <sub>DD</sub> =3.3V) reference voltage pin for external filtering	It needs external minimum 4.7µF ceramic capacitor	
2	VCM	A	Internally generated common mode 1.65V (@V <sub>DD</sub> =3.3V) reference voltage pin for external filtering	It needs external minimum 10µF ceramic capacitor	
3	VLO	A	Internally generated IFADC opamps 0.65V (@V <sub>DD</sub> =3.3V) reference voltage pin for external filtering	It needs external minimum 4.7µF ceramic capacitor	
4	INP	A	Positive IF signal input from tuner	2.0Vpp @VDD=3.3V	
5	INN	A	Negative IF signal input from tuner	2.0Vpp @VDD=3.3V	
6	VCMOP	-	Not connected.		

**Table 5. Pin description (continued)**

N°	Name	Type	Description	Notes	After Reset
7	GNDSD	G	IFADC modulator analogue ground	Clean ground, to be star connected to voltage regulator ground	
8	GNDOSC	G	Oscillator ground	Clean ground, to be star connected to voltage regulator ground	
9	XTI	I	High impedance oscillator input (quartz connection) or clock input when in Antenna Diversity slave mode	Maximum voltage swing is VDD=3.3V	
10	XTO	O	Low impedance oscillator output (quartz connection)		
11	VDDOSC	P	Oscillator power supply	3.3V	
12	VDDMTR	P	Tuner reference clock and AGC keying DAC power supply	1.8V	
13	CKREFP	B	Tuner reference clock positive output.	FM 100kHz AM <sub>EU</sub> 18kHz With internal pull-up, on at reset [PP]	Output
14	CKREFN	B	Tuner reference clock negative output.	FM 100kHz AM <sub>EU</sub> 18kHz With internal pull-up, on at reset [PP]	Output
15	AGCKEY	A	DAC output for Tuner AGC keying	1.5kohm ±30% output impedance. 1Vpp ±1% output dynamic range	
16	GNDMTR	G	Ground of the tuner reference clock buffer and the AGC keying DAC		
17	PROTSEL_SS	B	DSP0 GPIO for control serial interface (low: SPI or high: I <sup>2</sup> C) selection at device Bootstrap. In SPI protocol mode, after boot procedure, SPI slave select, otherwise DSP0 GPIO0	DSP0 GPIO0 5V tolerant With internal pull-up, on at reset [PP]	Input
18	SDA_MOSI	B	Control serial interface and RDS IO: - SPI mode: slave data in or master data out for main SPI & RDS SPI data in - I <sup>2</sup> C mode: data for main I <sup>2</sup> C or RDS I <sup>2</sup> C	5V tolerant With internal pull-up, on at reset [PP]	Input
19	MISO	B	SPI slave data out or master data in for main SPI and RDS SPI data out	DSP0 GPIO1 5V tolerant. With internal pull-up, on at reset [PP]	Input
20	SCL_SCK	B	Bit clock for Control Serial Interface and RDS	5V tolerant. With internal pull-up, on at reset [PP]	Input

**Table 5.** Pin description (continued)

N°	Name	Type	Description	Notes	After Reset
21	GND	G	Digital core power ground		
22	VDD	P	Digital core power supply	1.8V	
23	IQSYNC	B	High speed synchronous serial interface (HS <sup>3</sup> I) clock if HS <sup>3</sup> I master mode, else DSP1 GPIO or DSP1 debug port clock (DBOUT1)	DSP1 GPIO0 5V tolerant. With internal pull-up, on at reset	Input
24	IQCH1	B	High speed synchronous serial interface (HS <sup>3</sup> I) channel 1 data if HS <sup>3</sup> I master mode, else DSP1 GPIO or DSP1 debug port request (DBRQ1)	DSP1 GPIO1 5V tolerant. With internal pull-up, on at reset [PP]	Input
25	IQCH2	B	High speed synchronous serial interface (HS <sup>3</sup> I) channel 2 data if HS <sup>3</sup> I master mode, else DSP1 GPIO or DSP1 debug port data In (DBIN1)	DSP1 GPIO2 5V tolerant. With internal pull-down, on at reset [PP]	Input
26	IQCH3	B	High speed synchronous serial interface (HS <sup>3</sup> I) channel 3 data if HS <sup>3</sup> I master mode, else DSP1 GPIO or DSP1 debug port data out (DBCK1)	DSP1 GPIO3 5V tolerant With internal pull-down, on at reset [PP]	Input
27	VDDH	P	3.3V IO ring power supply (HS <sup>3</sup> I, I <sup>2</sup> C/SPI, RDS, INT)		
28	GNDH	G	3.3V IO ring power ground (HS <sup>3</sup> I, I <sup>2</sup> C/SPI, RDS, INT)		
29	RDS_INT	B	RDS interrupt to external main microprocessor in case of traffic information	DSP1 GPIO4. 5V tolerant, open drain With internal pull-up, on at reset [OD]	Input
30	RDS_CS	B	RDS chip select. When RESETN rising, If RDS_CS 0, the RDS's SPI is selected; else RDS's I <sup>2</sup> C	DSP1 GPIO5. 5V tolerant. With internal pull-up, on at reset [PP]	Input
31	INT	I	DSP0 external interrupt	5V tolerant. With internal pull-up, on at reset	
32	ADDR_SD	B	IFS chip master (Low) or slave (High) mode selection, latched in upon RESETN release. It selects the LSB of the I <sup>2</sup> C addresses. Station detector output	DSP0 GPIO2 5V tolerant With internal pull-down, on at reset [PP]	Input
33	RESETN	I	Chip hardware reset, active low	5V tolerant With internal pull-up	
34	VDD	P	Digital power supply	1.8V	
35	GND	G	Digital power ground		
36	TESTN	I	Test enable pin, active low	With internal pull-up	

**Table 5. Pin description (continued)**

N°	Name	Type	Description	Notes	After Reset
37	GPIO_SDO1	B	DSP0 GPIO for boot selection or audio SAI0 output.	5V tolerant. DSP0 GPIO3. With internal pull-up, on at reset [PP]	Input
38	TST4_SDIO	B	Audio SAI0 data input or test selection pin in test mode	5V tolerant. DSP0 GPIO5. With internal pull-up, on at reset [PP]	Input
39	TST1_SD1	B	DSP0 GPIO for boot selection or audio SAI1 input. Test selection pin in test mode.	5V tolerant. DSP0 GPIO4. With internal pull-up, on at reset [PP]	Input
40	GNDH	G	3.3V IO ring power ground (audio SAI, ResetN, test pins)		
41	VDDH	P	3.3V IO ring power supply (audio SAI, ResetN, test pins)		
42	SDO0	B	Radio or audio SAI0 data output	5V tolerant. With internal pull up, @0V at reset [PP]	Output
43	SCLK_SCKT	B	SAI0 receive and transmit bit clock (master or slave with ASRC); SAI1 transmit bit clock	5V tolerant With internal pull up, on at reset [PP]	Input
44	LRCK_LRCKT	B	SAI0 receive and transmit left/right clock (master or slave with ASRC); SAI1 transmit left/right clock	5V tolerant With internal pull up, on at reset [PP]	Input
45	TST2_SCKR	B	SAI0 Transmit bit clock; SAI1 receive and transmit bit clock. Or test selection pin in test mode	5V tolerant. DSP0 GPIO6. With internal pull up, on at reset [PP]	Input
46	TST3_LRCKR	B	SAI0 Transmit LeftRight clock; SAI1 Receive and Transmit bit clock. Or Test selection pin in Test Mode	DSP0 GPIO7. 5V tolerant. With internal pull up, on at reset [PP]	Input
47	VDD	P	Digital core power supply	1.8V	
48	GND	G	Digital core power ground		
49	DBCK0	B	Debug port clock of DSP0 (DBCK0)	DSP0 GPIO. 9. 5V tolerant. With internal pull down, on at reset [PP]	Input
50	DBIN0	B	Debug port data input of DSP0 (DBIN0)	DSP0 GPIO. 11. 5V tolerant. With internal pull down, on at reset [PP]	Input
51	DBRQ0	B	Debug port request of DSP0 (DBRQ0)	DSP0 GPIO. 5V tolerant With internal pull up, on at reset [PP]	Input
52	DBOUT0	B	Debug port data output of DSP0 (DBOUT0)	DSP0 GPIO10. 5V tolerant. With internal pull up, on at reset [PP]	Input

**Table 5.** Pin description (continued)

N°	Name	Type	Description	Notes	After Reset
53	GNDH	G	3.3V IO ring power ground (debug interface, GPIO)		
54	VDDH	P	3.3V IO ring power supply (Debug interface, GPIO)		
55	DBCK1	B	DSP1 debug port clock (DBCK1) if HS <sup>3</sup> I master mode, else high speed synchronous serial interface (HS <sup>3</sup> I) channel3 data	DSP1 GPIO9. 5V tolerant. With internal pull down, on at reset [PP]	Input
56	DBIN1	B	DSP1 GPIO or DSP1 debug port data in (DBIN1) if HS <sup>3</sup> I master mode, else high speed synchronous serial interface (HS <sup>3</sup> I) channel2 data i	DSP1 GPIO11 5V tolerant With internal pull down, on at reset [PP]	Input
57	DBRQ1	B	DSP1 GPIO or DSP1 debug port request (DBRQ1) if HS <sup>3</sup> I master mode, else high speed synchronous serial interface (HS <sup>3</sup> I) channel1 data	5V tolerant. With internal pull up, on at reset [PP]	Input
58	DBOUT1	B	DSP1 GPIO or DSP1 debug port data out (DBOUT1) if HS <sup>3</sup> I master mode, else high speed synchronous serial interface (HS <sup>3</sup> I) clock	DSP1 GPIO10 5V tolerant With internal pull up, on at reset [PP]	Input
59	VDD	P	Digital core power supply	1.8V	
60	GND	G	Digital core power ground		
61	VDDISO	P	3.3V N-isolation biasing supply	Clean 3.3V supply to be star connected to voltage regulator	
62	GNDH	G	3.3V IO ring power ground (modulator digital section)		
63	VDDH	P	3.3V IO ring power supply (modulator digital section)		
64	VDDSD	P	3.3V IFADC modulator analogue power supply	Clean power supply, to be star connected to 3.3V voltage regulator	

**I/O Type**

P: Power supply from voltage regulator  
 G: Power ground from voltage regulator  
 A: Analogue I/O  
 I: Digital input  
 O: Digital output  
 B: Bidirectional I/O

**I/O Definition and status**

Z: high impedance (input)  
 O: logic low output  
 X: undefined output  
 1: logic high output  
 Output **PP**: Push pull / **OD**: Open drain

## 2.2 Electrical characteristics

**Table 6. General interface electrical characteristics**  
 $(T_j = -40^\circ\text{C} \text{ to } 125^\circ\text{C}; V_{DD} = 1.8\text{V}, V_{DD3} = 3.3\text{V})$

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$I_{ilh}$	Low level input current $I_{Os} @ V_{DD3}$ (absolute value)	$V_i = 0\text{V}$ (1) (2) without pull-up-down device			1	$\mu\text{A}$
$I_{ihh}$	High level input current $I_{Os} @ V_{DD3}$ (absolute value)	$V_i = V_{DD3}$ (1) (2) without pull-up-down device			1	$\mu\text{A}$
$I_{il}$	Low level input current $I_{Os} @ V_{DD}$ (absolute value)	$V_i = 0\text{V}$ (1) (3) (4) without pull-up-down device			1	$\mu\text{A}$
$I_{ih}$	High level input current $I_{Os} @ V_{DD}$ (absolute value)	$V_i = V_{DD}$ (1) (3) (4) without pull-up device			1	$\mu\text{A}$
$I_{ipdh}$	Pull-down current $I_{Os} @ V_{DD3}$	$V_i = V_{DD3}$ (5) with pull-down device	35	60	85	$\mu\text{A}$
$I_{opuh}$	Pull-up current $I_{Os} @ V_{DD3}$	$V_i = 0\text{V}$ (6) with pull-up device	-100	-70	-40	$\mu\text{A}$
$I_{opul}$	Pull-up current $I_{Os} @ V_{DD}$	$V_i = 0\text{V}$ (3) with pull-up device	-40	-30	-20	$\mu\text{A}$
$I_{aihop}$	Analogue pin sunk / drawn current on pin1	$V_i = V_{DD3}$	0.95	1.25	1.55	$\text{mA}$
		$V_i = 0\text{V}$	-6.25	-5.0	-3.75	$\text{mA}$
$I_{acm}$	Analogue pin sunk / drawn current on pin 2	$V_i = V_{DD3}$	6.0	8.0	10.0	$\text{mA}$
		$V_i = 0\text{V}$	-10.0	-8.0	-6.0	$\text{mA}$
$I_{ail}$	Analogue pin sunk / drawn current on pin 3	$V_i = V_{DD3}$	3.75	5.0	6.25	$\text{mA}$
		$V_i = 0\text{V}$	-1.55	-1.25	-0.95	$\text{mA}$
$I_{ain}$	Analogue pin sunk / drawn current on pin 4 and pin 5	$V_i = V_{DD3}$	24	32	40	$\mu\text{A}$
		$V_i = 0\text{V}$	-40	-32	-24	$\mu\text{A}$
$I_{aih6}$	Analogue pin current on pin 6	$V_o = 0\text{V}$ or $V_{DD3}$			5	$\mu\text{A}$
$I_{aik}$	Analogue pin sunk / drawn current on pin 15	$V_i = V_{DD}$	0.8	1.2	1.6	$\text{mA}$
		$V_i = 0\text{V}$ (spec absolute value)			1	$\mu\text{A}$
$I_{oz}$	Tri-state output leakage	$V_o = 0\text{V}$ or $V_{DD3}$ without pull up / down device (1)			1	$\mu\text{A}$
$I_{ozFT}$	5V tolerant tri-state output leakage	$V_o = 0\text{V}$ or $V_{DD}$ (1)			1	$\mu\text{A}$
		$V_o = 5\text{V}$			80	$\mu\text{A}$
$I_{latchup}$	I/O latch up current	$V < 0\text{V}, V > V_{DD}$	200			$\text{mA}$
$V_{esd}$	Electrostatic protection	Leakage, $1\mu\text{A}$	2000			$\text{V}$

1. The leakage currents are generally very small,  $<1\text{nA}$ . The value given here,  $1\text{mA}$ , is the maximum that can occur after an electrostatic stress on the pin.

2. On pins: 17 to 20, 23 to 26, 29 to 33, 36 to 39, 42 to 46, 49 to 52, 55 to 58.
3. On pins: 13 and 14.
4. Same check on the analogue pin 15 (physically without pull-up-down)
5. On pins: 25, 26, 32, 49, 50, 55, 56
6. On pins: 17 to 20, 23 to 24, 29 to 31, 33, 36 to 39, 42 to 46, 51, 52, 57, 58

**Table 7. Low voltage interface CMOS DC electrical characteristics**  
 $(T_j = -40^\circ\text{C} \text{ to } 125^\circ\text{C}; V_{DD3} = 3.3\text{V})$

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$V_{il}$	Low level input voltage	$1.70\text{V} \leq V_{DD} \leq 1.90\text{V}$			$0.2*V_{DD}$	V
$V_{ih}$	High level input voltage	$1.70\text{V} \leq V_{DD} \leq 1.90\text{V}$	$0.8*V_{DD}$			V
$V_{ol}$	Low level output voltage	$I_{ol} = 4\text{mA}$ (1)			0.15	V
$V_{oh}$	High level output voltage	$I_{ol} = -4\text{mA}$ (1)	$V_{DD}-0.15$			V

1. It is the source/sink current under worst case conditions and reflects the name of the I/O cell according to the drive capability.

**Table 8. High voltage CMOS interface DC electrical characteristics**  
 $(T_j = -40^\circ\text{C} \text{ to } 125^\circ\text{C}; V_{DD}=1.8\text{V})$

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$V_{il}$	Low level input voltage	$3.15\text{V} \leq V_{DD3} \leq 3.45\text{V}$			0.8	V
$V_{ih}$	High level input voltage	$3.15\text{V} \leq V_{DD3} \leq 3.45\text{V}$	2.0			V
$V_{ol}$	Low level output voltage	$I_{ol} = X\text{mA}$ (1) (2)			0.15	V
$V_{oh}$	High level output voltage	$I_{ol} = -X\text{mA}$ (1) (2)	$V_{DD3}-0.15$			V

1. It is the source/sink current under worst case conditions & reflects the name of the I/O cell according to the drive capability

2. X=4mA for pins 17 to 20, 29, 30, 32, 37 to 39, 42 to 46; X=8mA for pins 23 to 26, 49 to 52, 55 to 58.

**Table 9. Current consumption ( $T_j = -40^\circ\text{C} \text{ to } 125^\circ\text{C}$ )**

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$I_{DD}$	Current through $V_{DD}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$ All digital blocks working		120	150	mA
$I_{DDHdc}$	Static current through $V_{DDH}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$	10	13	16	mA
$I_{DDHac}$	Current through $V_{DDH}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$ I/Os working with 5pF load			50	mA
$I_{SD}$	Current through $V_{SD}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$	25	35	45	mA
$I_{OSCdc}$	Current through $V_{OSC}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$ without quartz	5.5	8	10.5	mA
$I_{OSCac}$	Current through $V_{OSC}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$ with quartz	6.5	9	11.5	mA
$I_{MTR}$	Current through $V_{MTR}$ power supply	$V_{DD}=1.8\text{V}, V_{DD3}=3.3\text{V}$	0.5	1.3	2.0	mA

Note: 74.1MHz internal DSP clock, at  $T_{amb} = 25^\circ\text{C}$ . Current due to external loads not included.

**Table 10. Oscillator characteristics**(T<sub>j</sub> = -40°C to 125°C; V<sub>DD</sub> = 1.7V to 1.9V, V<sub>DD3</sub> = 3.15V to 3.45V)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
F <sub>OSCFM</sub>	Oscillator frequency (XTI/XTO)			74.1		MHz

Note: The accuracy depends on the quartz frequency precision: high stability oscillator

**Table 11. Crystal characteristics for 1 and 2 chip load**

Parameter name	Parameter value	
	1 chip load	2 chips load
Temperature range	-55°C÷125°C	-55°C÷125°C
Adjustment tolerance (@ 25°C ± 3°C)	± 30 ppm	± 30 ppm
Frequency stability (-20°C÷+70°C)	± 50 ppm	± 50 ppm
Aging @ 25°C	5 ppm/year	5 ppm/year
Shunt (static) capacitance [Co]	<5pF	<5pF
Motional capacitance	1fF ± 30%	1fF ± 30%
Mode of oscillation	AT-3rd	AT-3rd
Resonance resistance	< 75 ohm	< 45 ohm
Capacitive load for oscillation frequency = 74.1MHz	10pF	12pF

**Table 12. External clock signal on XTI** (In case the device is driven by an external clock through the XTI pin, the characteristics reported in this table have to be met)

Parameter name	Parameter value			
	Min	Typ	Max	Unit
Clock frequency		74.10		MHz
Frequency stability (-20°C÷+70°C)	-50		50	ppm
Clock jitter			10	ps rms
Start up time			5	ms
Clock level (sine wave) <sup>(1)</sup>	220		640	mV rms
Clock level (square wave) <sup>(1)</sup>	0.50		1.80	V p-p
Clock duty cycle (square wave)	45		55	%
Clock rise / fall time (square wave) <sup>(1)</sup>			500	ps

1. specified @ XTI pin of TDA7580

**Table 13. DSP core ( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ )**

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
$F_{\text{dspMax}}$	Maximum DSP clock frequency	$V_{\text{DD}}=1.7\text{V}$ , $V_{\text{DD3}}=3.3\text{V}$	81.5			MHz

**Table 14. FM stereo decoder characteristics**

( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ;  $V_{\text{DD}} = 1.7\text{V}$  to  $1.9\text{V}$ ,  $V_{\text{DD3}} = 3.15\text{V}$  to  $3.45\text{V}$ ; BW for measurements 20Hz to 15KHz)

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
a_ch	Channel separation	(Adjustable by SW from 0 to -45dB)	-45		0	dB
THD	Total harmonic distortion	1KHz; mono; $\Delta f=75\text{KHz}$ ;		0.02	0.04	%
(S+N)/N	Signal plus noise to noise ratio	1KHz; mono; $\Delta f=40\text{KHz}$ ;	78	80	82	dB

$$\text{MCK} = 18.525\text{MHz}, F_{\text{sin}}/F_{\text{sout}} = 0.820445366$$

**Table 15. Sample rate converter**

( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ;  $V_{\text{DD}} = 1.7\text{V}$  to  $1.9\text{V}$ ,  $V_{\text{DD3}} = 3.15\text{V}$  to  $3.45\text{V}$ );  
BW for measurements 20Hz to 20KHz

Symbol	Parameter	Test condition	Min.	Typ.	Max.	Unit
THD+N	Total harmonic distortion + noise	20Hz to 20kHz, full scale, 16 bit inp.		-95	-92	dB
		20Hz to 20kHz, full scale, 20 bit inp.		-98	-95	dB
		1 kHz full scale, 16 bit inp.		-98	-95	dB
		2 kHz full scale, 16 bit inp.		-98	-95	dB
		5 kHz full scale, 16 bit inp.		-98	-95	dB
		10 kHz full scale, 16 bit inp		-98	-95	dB
		15 kHz full scale, 16 bit inp		-98	-95	dB
		1 kHz full scale, 20 bit inp.		-119	-116	dB
		2 kHz full scale, 20 bit inp.		-116	-113	dB
		5 kHz full scale, 20 bit inp.		-112	-109	dB
		10 kHz full scale, 20 bit inp		-108	-105	dB
		15 kHz full scale, 20 bit inp		-105	-102	dB
DR	Dynamic Range	1 kHz -60 dB - 16 bit inp. A-weighted	97	100		dB
	fratio = 0.82	1 kHz -60 dB - 24 bit inp. A-weighted	141	145		dB
R <sub>p</sub>	Pass band ripple	from 20Hz to 15kHz		0.4	0.5	dB
F <sub>ratio</sub>	Sampling frequency in/out ratio	Fsout = 44.1 kHz	0.7		1.13	

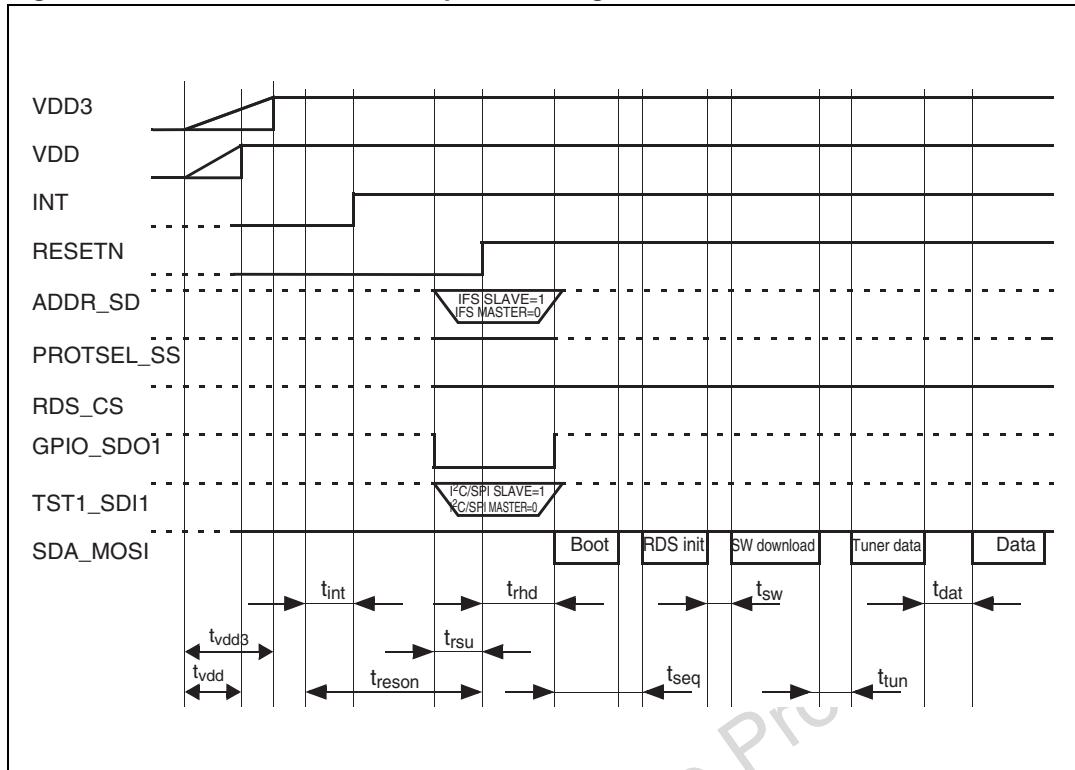
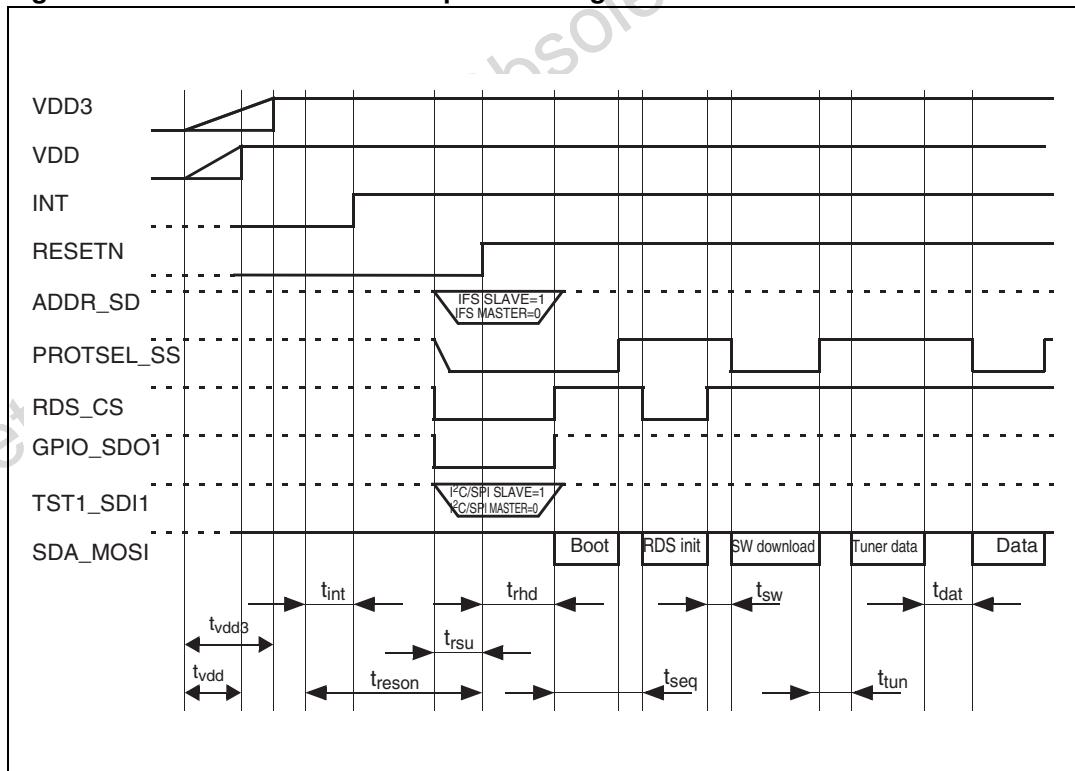
Figure 3. Power on and boot sequence using I<sup>2</sup>C

Figure 4. Power on and boot sequence using SPI



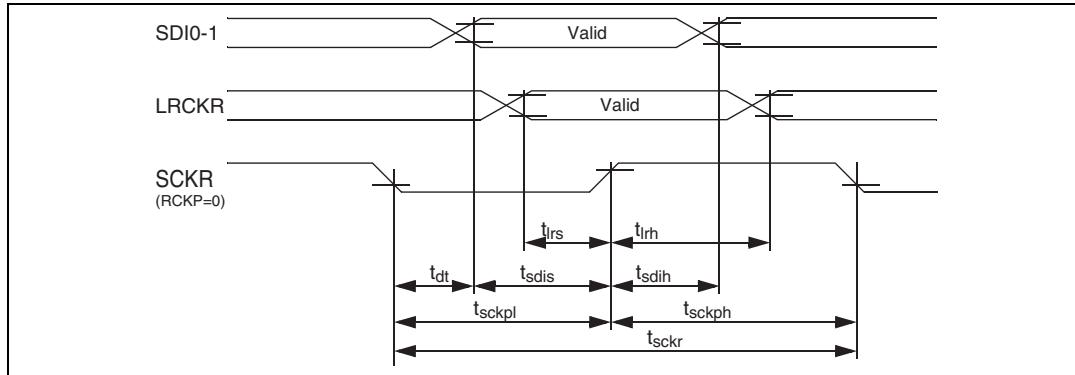
**Table 16. SPI and I<sup>2</sup>C timing table**(T<sub>j</sub> = -40°C to 125°C; V<sub>DD</sub> = 1.7V to 1.9V, V<sub>DD3</sub> = 3.15V to 3.45V)

Timing	Description	Min	Typ	Max	Unit
t <sub>vdd3</sub>	Rise time of 3.3V supply	1	13	25	ms
t <sub>vdd</sub>	Rise time of 1.8V supply	1	6	10	ms
t <sub>int</sub>	Maximum delay for INT signal	-	-	1	ms
t <sub>reson</sub>	Minimum RESETN hold time at 0 after the start-up	40	-	-	ms
t <sub>rsu</sub>	Minimum data set-up time	250			μs
t <sub>rhd</sub>	Minimum data hold time	250			μs
t <sub>seq</sub>	Minimum wait time including boot	4			ms
t <sub>sw</sub>	Minimum wait time before downloading the program software	30			μs
t <sub>tun</sub>	Minimum wait time before downloading the software to the FE	1			μs
t <sub>dat</sub>	Minimum wait time before using interface protocols	1			μs

Obsolete Product(s) - Obsolete Product(s)

### 3 SAI Interface

**Figure 5. SAI Timings**



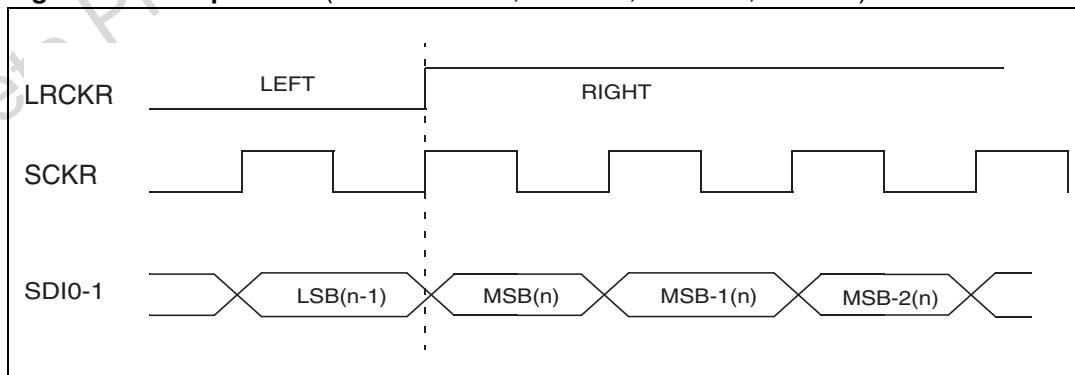
**Table 17. SAI Timing table**

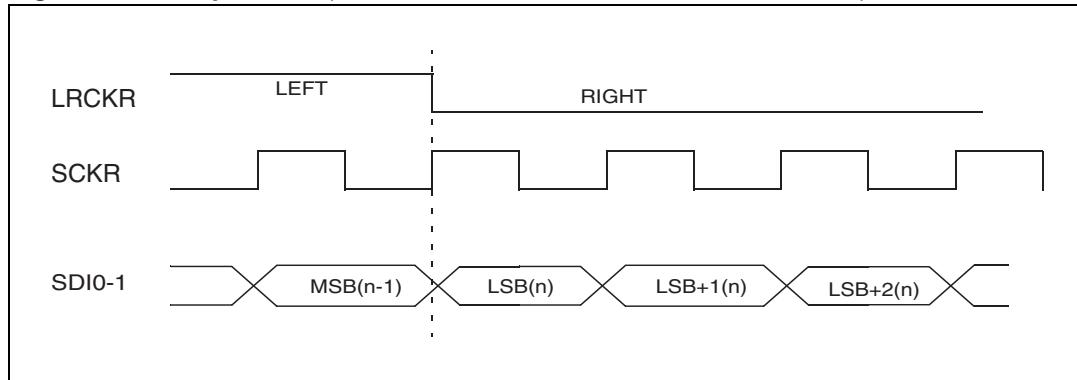
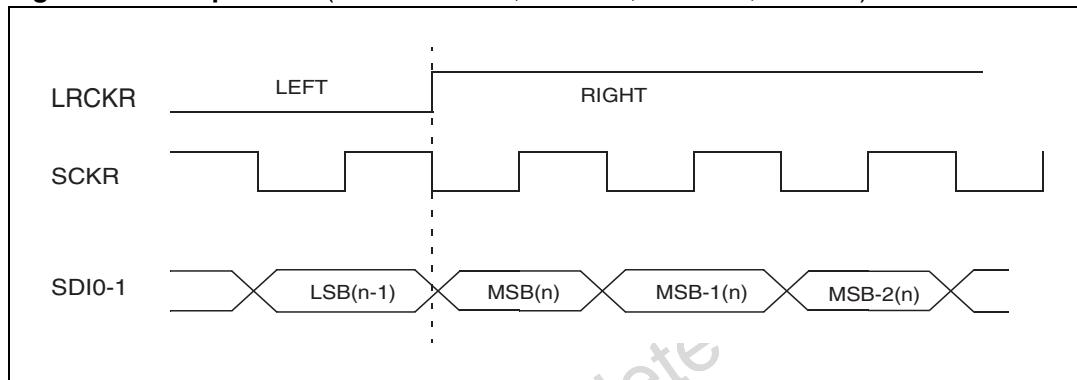
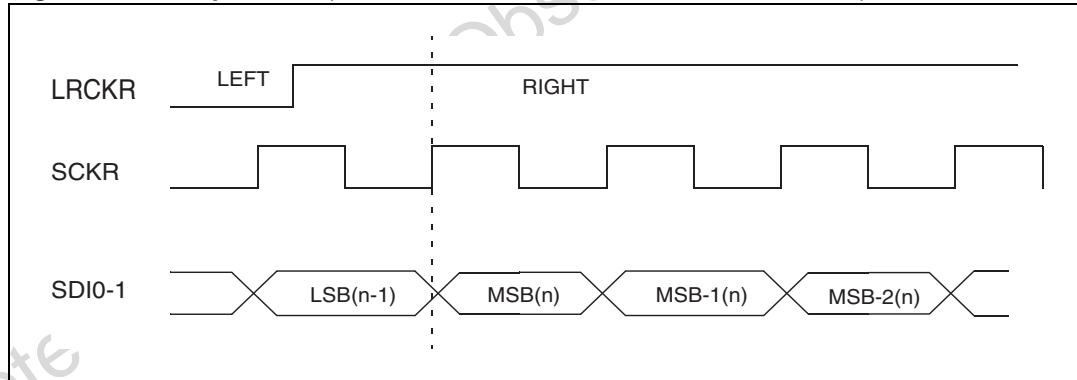
( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ;  $V_{DD} = 1.7\text{V}$  to  $1.9\text{V}$ ,  $V_{DD3} = 3.15\text{V}$  to  $3.45\text{V}$ )  $C_{load}$  The values on the table are consistent with a capacitance load on SAI lines of  $160\text{pF}$

Timing	Description	Min	Typ	Max	Unit
$t_{sckr}$	Clock Cycle	302		976	ns
$t_{dt}$	SCKR active edge to data out valid	48		65	ns
$t_{lrs}$	LRCK setup time	25			ns
$t_{lrh}$	LRCK hold time	25			ns
$t_{sdis}$	SDI setup time	65			ns
$t_{sdih}$	SDI hold time	65			ns
$t_{sckph}$	SCK high time	146			ns
$t_{sckpl}$	SCK low time	146			ns

Note:  $T_{DSP} = \text{DSP master clock cycle time} = 1/F_{DSP}$

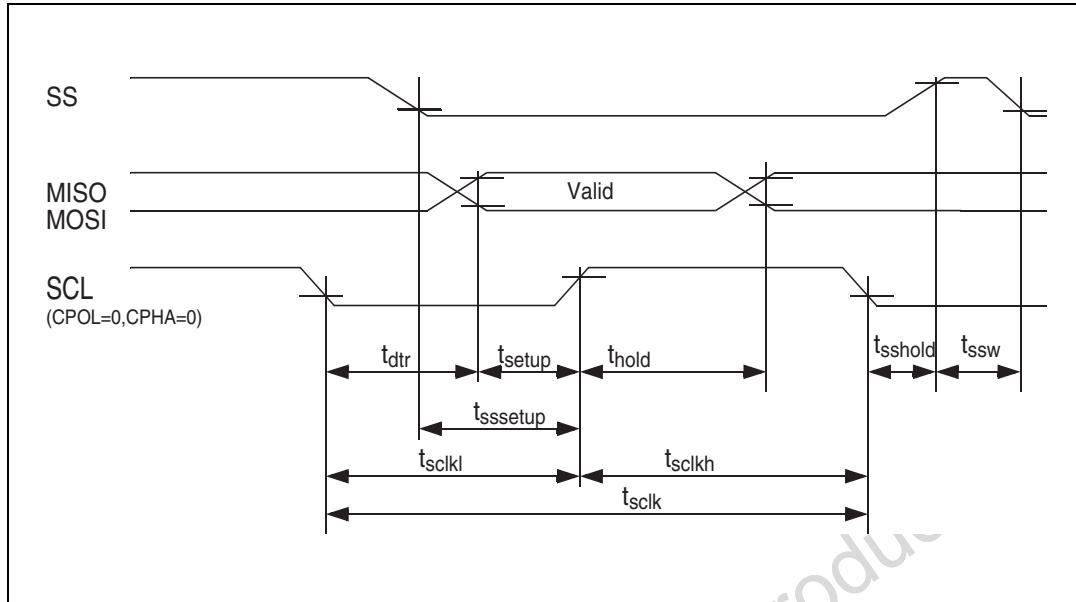
**Figure 6. SAI protocol** (when: RLRS=0; RREL=0; RCKP=1; RDIR=0)



**Figure 7.** SAI protocol (when: RLRS=1; RREL=0; RCKP=1; RDIR=1)**Figure 8.** SAI protocol (when: RLRS=0; RREL=0; RCKP=0; RDIR=0)**Figure 9.** SAI protocol (when: RLRS=0; RREL=1; RCKP=1; RDIR=0)

## 4 RDS SPI interface

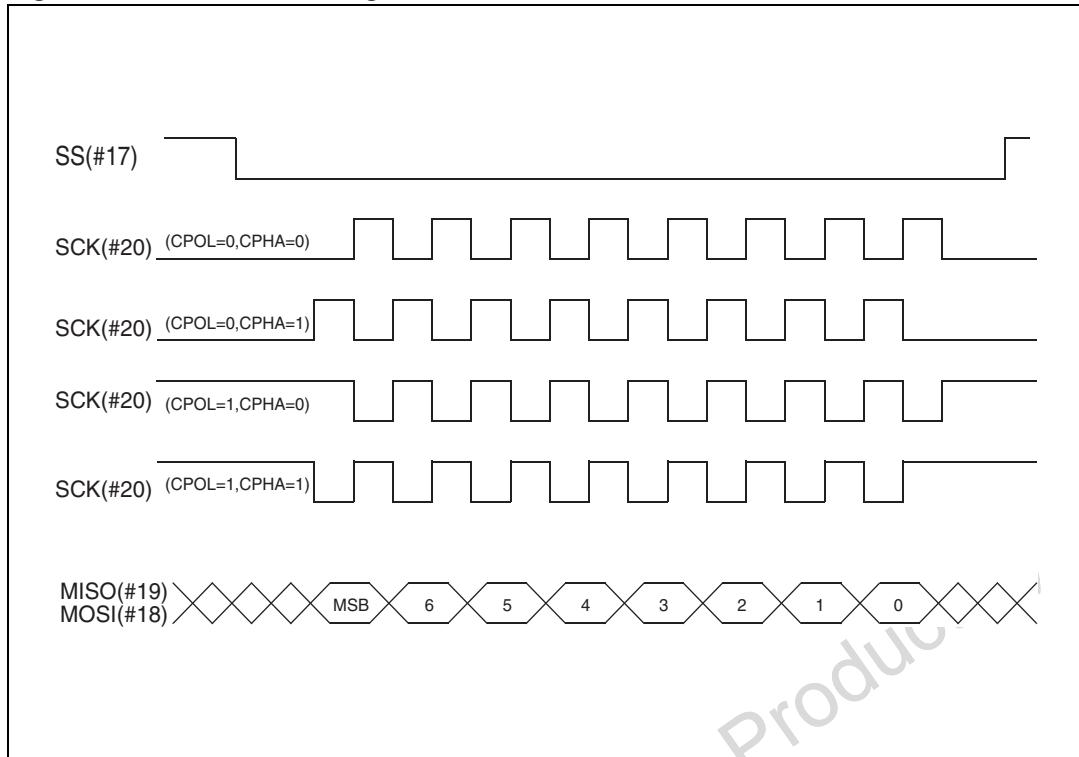
**Figure 10. RDS SPI timings**



**Table 18. RDS SPI timing table**

( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ;  $V_{DD} = 1.7\text{V}$  to  $1.9\text{V}$ ,  $V_{DD3} = 3.15\text{V}$  to  $3.45\text{V}$ )  $C_{load}$  The values on the table are consistent with a capacitance load on RDS SPI lines of  $80\text{pF}$

Symbol	Description	Min	Typ	Max	Unit
<b>Slave configured</b>					
$t_{sclk}$	Clock cycle	1240			ns
$t_{dtr}$	Sclk edge to MISO valid	239		365	ns
$t_{setup}$	MOSI setup time	255			ns
$t_{hold}$	MOSI hold time	365			ns
$t_{sclkh}$	SCK high time width	620			ns
$t_{sclkl}$	SCK low time width	620			ns
$t_{sssetup}$	SS setup time	620			ns
$t_{sshould}$	SS hold time	620			ns
$t_{ssw}$	SS pulse width	1240			ns

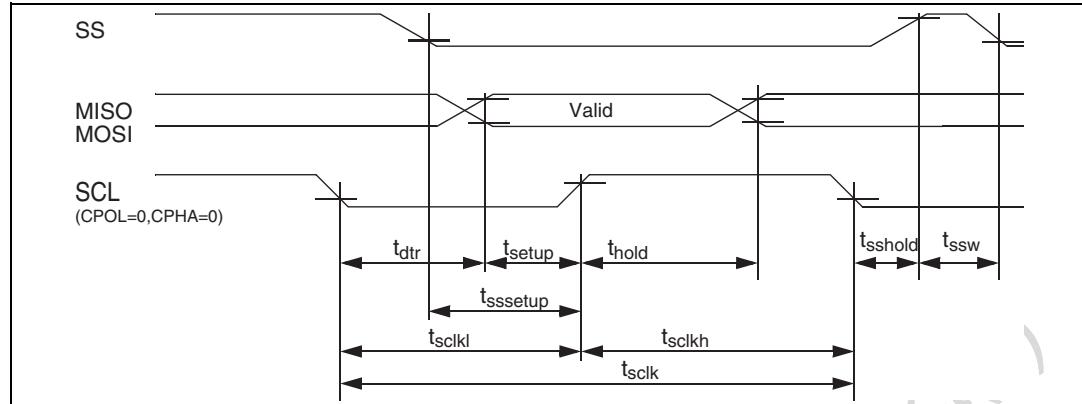
**Figure 11. RDS SPI clocking scheme**

## 5 BSPi interface

( $T_j = -40^\circ\text{C}$  to  $125^\circ\text{C}$ ;  $V_{DD} = 1.7\text{V}$  to  $1.9\text{V}$ ,  $V_{DD3} = 3.15\text{V}$  to  $3.45\text{V}$ )  $C_{load}$

The values on the table are consistent with a capacitance load on BSPi lines of 160pF

**Figure 12. BSPi timings**



**Table 19. BSPi timing table**

Symbol	Description	Min	Typ	Max	Unit
<b>Master configured</b>					
$t_{sclk}$	Clock cycle	184			ns
$t_{dtr}$	Sclk edge to MOSI valid	61		92	ns
$t_{setup}$	MISO setup time	52			ns
$t_{hold}$	MISO hold time	52			ns
$t_{sclkh}$	SCK high time	92			ns
$t_{sclkl}$	SCK low time	92			ns
$t_{sssetup}$	SS setup time	92			ns
$t_{sshold}$	SS hold time	92			ns
$t_{ssw}$	SS pulse width	184			ns
<b>Slave configured</b>					
$t_{sclk}$	Clock cycle	238			ns
$t_{dtr}$	Sclk edge to MISO valid	88		119	ns
$t_{setup}$	MOSI setup time	65			ns
$t_{hold}$	MOSI hold time	65			ns
$t_{sclkh}$	SCK high time	119			ns
$t_{sclkl}$	SCK high low	119			ns
$t_{sssetup}$	SS setup time	119			ns
$t_{sshold}$	SS hold time	119			ns
$t_{ssw}$	SS pulse width	238			ns

**Figure 13. BSPI clocking scheme**