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TWR-56F8400

User Manual Rev. 0.01

Freescale Semiconductor Inc. *Microcontroller Solutions Group*



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Revision History

Revision	Date	Changes	
0	12 Dec 2009	Input from Jay Hartvigsen	
0.01	4 Jan 2010	Update from Jay Hartvigsen	
O.02	21 Jan 2010	Reordered list of features in overview to match the table of contents order. Correction to Table 2. Added LED Label column in table 3. Added requested comment on CAN TXD and RXD nets – that they also go to the elevator connector. Improved description of USB Serial Bridge Interface and moved the circuit description of this interface from section 2.3.2 to section 2.4.2. Added Tower Elevator Connector table. Added an appendix to put the schematic in. Added BOM.	
0.03	29 Jan 2010	Updated document list in section 1.2 by Petr Stekl	
0.00	25 February 2012	JLW Ported from MC56F8257 to the 32-bit MC56F84789 Note: OSBDM implies "also OSJTAG" below. Due to the tight layout, added appendix for layout of headers used for jumpers to aid in their identification.	
0.01	27 February 2012	JLW responded to customer feedback as well as Ankar feedback.	
0.02	6 March 2012	JLW corrections to composite signal names	
0.03	6 March 2012	JLW removed schematic. Editor to embed schematic as object. Corrected TOWER signal names per latest. Included new functionality of S08 firmware for CDC serial port. Released to publications.	
0.04	7 March 2012	JLW added back schematic as rev B	



Overview

The MC56F8400 Tower 32-bit MCU Module (TWR-56F8400) is an evaluation, demonstration and development board. The TWR-56F8400 can operate stand-alone or as the main control board in a Tower system with peripheral modules. It can also be used as the main control board with an APMOTOR56F8000E motor control board.

The following list summarizes the features of the TWR-56F8400:

- 32 bit Digital Signal Controller module featuring MC56F84789
- Tower compatible
- Selectable Power sources:
 - o USB on 56F8400 card
 - Barrel connector on 56F8400 card
 - Motor control board plug direct to 56F8400 card, no Tower connection, plug Motor control to nine volts
 - Tower elevator board (USB or Barrel on Primary side)
- Filtered power for VDDA and VSSA on the 32-bit MC56F84789DSC
- MC56F84789 DSC (Digital Signal Controller) in an 100 LQFP package
- Optional 8 MHz crystal circuit for the MC56F84789 DSC
- 9 LEDs controlled by the MC56F84789 DSC
- Motor Control Board connector for the APMOTOR56F8000E motor control board
- Auxiliary Signal connector
- Four Thermistors for single ended or differential analog inputs to the MC56F84789 DSC
- CAN transceiver, header, and termination
- Two push buttons for user input or interrupts to the MC56F84789 DSC
- Reset push button for the MC56F84789 DSC
- JTAG header for the MC56F84789 DSC with header to disconnect from OSBDM/OSJTAG
- Headers to connect SCI signals to either USB bridge with CDC(one channel) or elevator board (two channels) or connect one to each
- Expansion via Primary Elevator connector
- MC9S08JM60 ('JM60) MCU with a 4 MHz crystal provides:
 - o Open Source Debug (OSBDM/OSJTAG) circuit
 - USB to SCI bridge with CDC and other techniques supported by third parties
 - Simultaneious OSBDM/OSJTAG and USB to SCI bridge functions with no header required to select
 - Bootloader enable header allows easy upgrade to latest S08 firmware pushed down by CodeWarrior
 - o BDM header for the MC9S08JM60 MCU
 - Status and Target Power indicator LEDs
 - o Control of semiconductor switch to enable power to board from USB



 Voltage translators between 5V MC9S08JM60 MCU chip and 3.3V MC56F84789 DSC chip

1.1 Block Diagram

A block diagram for the TWR-56F8400 is shown in Figure 1 below.

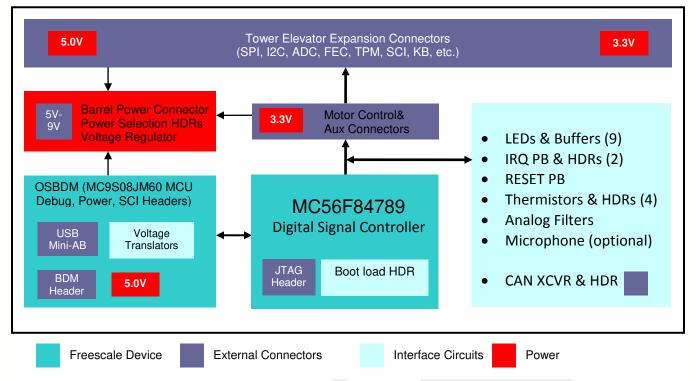


Figure 1. TWR-56F8400 Block Diagram

1.2 Reference Documents

The documents listed below should be referenced for more information on the Freescale Tower system and the TWR-56F8400. Refer to <u>http://www.freesale.com/tower</u> for the latest revision of all Tower documentation.

- Freescale Tower Electromechanical Specification
- TWR-56F8400 Quick Start Guide
- TWR-56F8400 Lab Tutorials
- MC56F84XXX Reference Manual
- MC56F84XXX Data Sheet
- MC56F84XXX Chip Errata [if exists]
- AN3561, USB Bootloader for the MC9S08JM60
- Serial Bootloader for MC56F84XXX User Guide
- APMOTOR56F8000e Motor Control Demonstration System User Manual



2 Hardware Features

This section provides more details about the features and functionality of the TWR-56F8400.

A drawing of the TWR-56F8400 showing the jack locations is shown in Appendix D. Features are discussed below.

2.1 Tower MCU Module

The TWR-56F8400 board is an MCU Module designed for standalone use (or with a Freescale Tower system) and complies with the electrical and mechanical specification as described in *Freescale Tower Electromechanical Specification*. Connection to the Tower system is through two expansion card-edge connectors that interface to the Elevator boards in a Tower system: the Primary and Secondary Elevator connectors. The Primary Elevator connector, comprised of sides A and B, is utilized by the TWR-56F8400, while the Secondary Elevator connector only makes connections to ground (GND). On sheet 8 of the schematic the J500A and J500B symbols have names assigned to the card edge fingers that correspond with the normal Tower pin assignments.

2.2 System Power

The TWR-56F8400 board has three power rails. They are P5V_USB, P3_3V and P3_3V/5V. They are sourced and used as follows:

2.2.1 P5V_USB

The P5V_USB power rail is derived from the Mini-B USB connector at J18 and the inductor at L2. It is used to power the on board OSBDM/OSJTAG/Serial Bridge circuit. This consists of the OSBDM/OSJTAG MCU at U6, several pull-up resistors at R13, R14, R15, R527, and R528, the USB power switch at U501, and the STATUS and TPWR LEDs at D12 and D13. If there is no USB cable connected to J18 there is no power on this rail and these circuits are all powered down.

2.2.2 P3_3V

The P3_3V power rail is derived from a) the P3_3V_MOTOR power net from the motor control board connector at J501, b) the P3_3V_ELEV power net from the tower connector at J500, or c) the on board 3.3V regulator at U1. The selection of which source is made with a shunt from J7-2 to another pin of J7 or to J6. **Table 6** shows the operation of the different shunt positions. The selection of power into the regulator is made with a shunt from J11-2 to another pin of J11 or to J10 which selects from a) the P5V_TRG_USB power net out of the USB switch at U501, b) the P5V_ELEV power net from the elevator connection at J500 pins A1 and B1, or c) the PWR_IN power net from the 2mm barrel jack at J3 through resettable fuse F1. **Table 6** shows the operation of the different shunt positions. The barrel jack input is protected from reverse voltage inputs by diode D11. The input to the barrel jack may be from a 5V to 9V source and needs to be center positive.



The P3_3V power rail provides power to the majority of the circuits on the board including the MC56F84789 (including the analog power pins through L500 and L501), inverters at U500 and U502, a buffer at U505, the on board LEDs at D1-D9, the thermistor divider circuits at RT1-RT4, and the pull-up resistors at R2, R3, R11, R565, R570, and R562.

2.2.3 P3_3V/5V

The P3_3V/5V power rail is derived from the diode OR (using D500 and D501) of a) the P5V_ELEV power net from the elevator connection (J500 pins A1 and B1), b) the P5V output of the USB power switch at U501, or c) the P3_3V power rail from J7. When there is a USB cable connected or when the tower elevator boards are connected this power rail will be a Schottky diode drop (about 0.3V) below the 5V power nets. When there is no 5V source this power rail will be a Schottky diode drop below the P3.3V power rail. This allows the inputs of the ICs powered by this rail to stay in a high impedance state instead of loading down the inputs through the input protection diodes as would happen if there were no power supplied to the buffers.

2.2.4 Default Power Configuration

The TWR-56F8400 board default power configuration uses the OSBDM/OSJTAG USB port for all power. As soon as the OSBDM/OSJTAG firmware has started it negotiates with the Host PC USB port for full USB power. Once approved it enables the 5V USB power switch (U501) which provides 5V to the P3_3V/5V power rail and to the 3.3V regulator (U1) through headers J10 and J11. Likewise, the on board voltage regulator provides 3.3V to the P3_3V power rail through headers J6 and J7. The 3.3V regulator is able to provide up to 700 mA subject to the power dissipation and temperature limits of the device.

2.3 MC56F84789 DSC

The primary circuits on the board are related to the MC56F84789 DSC. This part is supplied in a surface mounted 100pin LQFP package at U2. Although the board was laid out to allow a ZIF socket at U3 in parallel to the chip at U2 the TWR-56F8400 is only available for purchase with the surface mounted chip.

2.3.1 Clock Sources for the MC56F84789 DSC

Three options are provided for clocking the MC56F84789 device:

- 1. Oscillator internal to the MC56F84789 chip approximately 8 MHz.
- 2. 8 MHz crystal
- 3. External clock input from Primary Tower Connector or the AUX Connector.

The internal oscillator is used to clock the MC56F84789 immediately following reset. This is the default operation. In this mode the zero ohm resistors at R4 and R10 allow the GPIOC0 and GPIOC1 pins of the MC56F84789 to be used as inputs or outputs.



To use an external crystal with the MC56F84789, zero ohm resistors R4 and R10 must be removed and placed in the R5 and R7 positions. The desired crystal, load capacitors, and parallel resistor (if needed) must be soldered to the board at Y1, C5, C6, and R6. (These components are not provided with the TWR-56F8400 kit.) Following reset, reconfigure the GPIOC0 and GPIOC1 pins to the XTAL and EXTAL functions to allow the use of an external crystal.

To use an external clock for the MC56F84789 make sure the zero ohm resistors are installed at R4 and R10 and removed from R5 and R7. Provide a clock signal on either the Primary Tower Connector J500A - pin B24 (the pin designated as CLOCKIN0) or on the AUX connector J502 - pin 8. Following reset, configure the GPIOC0 pin to the CLKIN input function. In this mode the zero ohm resistor at R10 allows the GPIOC1 pin of the MC56F84789 (pin 10) to be used as an input or output.

2.3.2 Serial I/O Source Select Headers

The TWR-56F8400 board allows the UART functions of the MC56F84789 DSC to be connected to a serial interface at the primary Tower Connector J500A or through a USB bridge to the Host PC using the OSBDM/OSJTAG MCU (U6). The selection of the RXD connections is done with the header at J8 as shown in **Table 1.** The selection of the TXD connections is done with the header at J9 as shown in **Table 2.**

	J8 – RXD Source Select Header				
Pin #	Connected Signal	Description			
1	ELEV_RXD0 at J500A pin A41	Shunt pins 1 and 2 together to connect the DSC RXDO pin to the primary Tower Connector RXDO pin. (This is a default position.)			
2	GPIOF8/RXD0/TB1 from the 56F84789 DSC – pin 6 (RXD0 function)				
3	RXD_SEL from the USB bridge function on the OSBDM/OSJTAG MCU.	Shunt pins 2 and 3 together to connect the DSC RXD0 pin to the USB serial bridge function. Shunt pin 3 and 4 together to connect the DSC RXD1 pin to the USB serial bridge function.			
4	GPIOF5/RXD1/XB_OUT5 from the 56F84789 DSC – pin 42 (RXD1 function)				
5	ELEV_RXD1 at J500 pin A43	Shunt pins 4 and 5 together to connect the DSC RXD1 pin to the primary Tower Connector RXD1 pin. (This is a default position.)			

Table 1. J8 – RXD Source Select Header



	J9 – TXD Source Select Header				
Pin #	Connected Signal	Description			
1	ELEV_TXD0 at J500A pin A42	Shunt pins 1 and 2 together to connect the DSC TXDO pin to the primary Tower Connector TXDO pin. (This is a default position.)			
2	GPIOC2/TXD0/TB0/XB_IN2/CLKO from the 56F84789 DSC – pin 5 (TXD0 function)				
3	TXD_SEL to the USB bridge function on the OSBDM/OSJTAG MCU.	Shunt pins 2 and 3 together to connect the DSC TXDO pin to the USB serial bridge function. Shunt pin 3 and 4 together to connect the DSC TXD1 pin to the USB serial bridge function.			
4	GPIOF4/TXD1/XB_OUT4 from the 56F84789 DSC – pin 41 (TXD1 function)				
5	ELEV_TXD1 at J500 pin A44	Shunt pins 4 and 5 together to connect the DSC TXD1 pin to the primary Tower Connector TXD1 pin. (This is a default position.)			

Table 2. J9 – TXD Source Select Header

As can be seen in the tables the 56F84789 DSC serial signals may be connected to either the Tower serial signals or to the USB bridge chip; however, only one channel may be connected to the USB bridge chip. If the associated 56F84789 DSC serial pins are not being used for the serial functions the shunts should be removed from those pins. For more information on the USB Serial Bridge function see section **2.4.2 USB Serial Bridge Interface**.

2.3.3 LEDs Controlled by the MC56F84789 DSC

There are nine LEDs with buffers connected to the MC56F84789 DSC. Inverting buffers (U500A-F and U502D-F) isolate the LEDs from the DSC pins by providing high impedance inputs. The LEDs are powered by the P3_3V rail and draw about 5mA each. **Table 3** shows the DSC pin names associated with each LED.

LEDs Controlled by the MC56F84789 DSC							
MC56F84789 DSC MC56F84789 LED LED LED							
Pin Name	Pin Number	Reference	Label	Color			
GPIOE0/PWMA_0B	68	D1	EO	Green			
GPIOE1/PWMA_0A	69	D2	E1	Yellow			
GPIOE2/PWMA_1B	74	D3	E2	Green			
GPIOE3/PWMA_1A	75	D4	E3	Yellow			

Table 3. LEDs Controlled by the MC56F84789 DSC



GPIOE4/PWMA_2B/XB_IN2	82	D5	E4	Green
GPIOE5/PWMA_2A/XB_IN3	83	D6	E5	Yellow
GPIOE6/PWMA_3B/XB_IN4/PW	84	D7	E6	Green
MB_2B				
GPIOE7/PWMA_3A/XB_IN5/PW	85	D8	E7	Yellow
MB_2A				
GPIOF6/TB2/PWMA_3X/PWMB_	94	D9	F6	Amber
3X/XB_IN2				

2.3.4 Motor Control Connector

The TWR-56F8400 board may be connected to a motor control board such as the APMOTOR56F8000E. The motor control connector (J501) is on the bottom of the board to provide a convenient connection to the motor control board.

Some of the MC56F84789 DSC pins are connected to the motor control connector. Those pins associated with analog inputs have 100 ohm resistors in series to provide some ESD protection for the analog inputs of the DSC. Those pins providing analog signals from the motor control board have 2200 pf caps with the resistors to provide a low pass filter. The connector pin out is shown in **Table 4**.

	Motor Control Connector J501 Pin Out				
Pin	MC56F84789 DSC Signal	Pin	MC56F84789 DSC Signal		
#		#			
1	P3_3V_MOTOR	2	GPIOB7/ANB7&ANC15&CMPB_IN2		
			(With 100 ohms in series)		
3	GND	4	RESETB/ GPIOD4		
			(With 0 ohms in series – remove to		
			isolate)		
5	GPIOF4/TXD1/XB_OUT8	6	GPIOA3/ANA3&VREFLA&CMPA_IN2		
			(With 100 ohms in series)		
7	GPIOF3/SDA1/XB_OUT7	8	GND		
9	GPIOE1/PWMA_0A	10	GPIOA0/ANA0&CMPA_IN3/CMPC_O		
			(With 100 ohm, 2200 pf low pass filter)		
11	GPIOE0/PWMA_0B	12	GPIOA1/ANA1&CMPA_IN0		
			(With 100 ohm, 2200 pf low pass filter)		
13	GPIOC3/TA0/CMPA_0/RXD0/CLKIN1	14	GPIOA2/ANA2&VREFHA&CMPA_IN1		
			(With 100 ohm, 2200 pf low pass filter)		
15	GPIOC13/TA3/XB_IN6/EWM_OUT_B	16	GND		

Table 4. Motor Control Connector Pin Out



	Motor Control Connector J501 Pin Out				
Pin	MC56F84789 DSC Signal	Pin	MC56F84789 DSC Signal		
#		#			
17	GPIOC4/TA1/CMPB_O/XB_IN8/EWM_OUT_B	18	GPIOB0/ANB0&CMPB_IN3		
			(With 100 ohm, 2200 pf low pass filter)		
19	GPIOC6/TA2/XB_IN3/CMP_REF	20	GPIOB1/ANB1&CMPB_IN0		
			(With 100 ohm, 2200 pf low pass filter)		
21	GPIOC15/SCL0/XB_OUT5	22	GPIOB2/ANB2&VREFHB&CMPC_IN3		
			(With 100 ohm, 2200 pf low pass filter)		
23	GPIOC14/SDA0/XB_OUT4	24	GND		
25	TDI /GPIOD0	26	GPIOE7/PWMA_3A/XB_IN5/PWMB_2A		
27	TDO/ GPIOD1	28	GPIOE6/PWMA_3B/XB_IN4/PWMB_2B		
29	TCK/GPIOD2	30	GPIOE3/PWMA_1A		
31	TMS /GPIOD3	32	GPIOE2/PWMA_1B		
33	GPIOB3/ANB3&VREFLB&CMPC_IN0	34	GPIOE5/PWMA_2A/XB_IN3		
	(With 100 ohms in series)				
35	GPIOB4/ANB4&ANC12&CMPC_IN1	36	GPIOE4/PWMA_2B/XB_IN2		
	(With 100 ohms in series)				
37	GPIOB5/ANB5&ANC13&CMPC_IN2	38	GPIOA4/ANA4&ANC8&CMPD_IN0		
	(With 100 ohms in series)		(With 100 ohms in series)		
39	GPIOB6/ANB6&ANC14&CMPB_IN1	40	GPIOA5/ANA5&ANC9		
	(With 100 ohms in series)		(With 100 ohms in series)		

2.3.5 Auxiliary Connectors

In addition to the motor control connector the TWR-56F8400 board also provides two auxiliary connectors (J502 and J503) on the bottom of the board. These connectors provide access to the MC56F84789 DSC signals that are not covered by the motor control connector. Those pins associated with analog inputs have 100 ohm resistors in series to provide some ESD protection for the analog inputs of the DSC. The connector pin out is shown in **Table 5**.

	Auxiliary Connectors J502 and J503 Pin Out				
Pin	in MC56F84789 DSC Signal Pin MC56F84789 DSC Signal				
#		#			
J50	GPIOF0/XB_IN6/TB2/SCK1	J50	GPIOA6/ANA6&ANC10		
2-1		2-2	(With 100 ohms in series)		
J50	GPIOF1/CLKO1/XB_IN7/CMPD_O	J50	GPIOA7/ANA7&ANC11		
2-3		2-4	(With 100 ohms in series)		



	Auxiliary Connectors J502 and J503 Pin Out					
Pin	MC56F84789 DSC Signal	Pin	MC56F84789 DSC Signal			
#		#				
J50	GPIOF2/SCL1/XB_OUT6	J50	GND			
2-5		2-6				
J50	GPIOF5/RXD1/XB_OUT9	J50	GPIOC0/EXTAL/CLKIN0			
2-7		2-8				
J50	GPIOF6/TB2/PWMA_3X/PWMB_3X/XB_I	J50	GPIOC1/XTAL			
2-9	N2	2-				
		10				
J50	GPIOF7/TB3/CMPC_O/SS1_B/XB_IN3	J50	GPIOC2/TXD0/TB0/XB_IN2/CLKO0			
2-		2-				
11		12				
J50	GPIOF8/RXD0/TB1/CMPD_O	J50	GPIOC5/DACO/XB_IN7			
2-		2-				
13		14				
J50 2-	GPIOC11/CANTX/SCL1/TXD1	J50 2-	GPIOC7/SS0_B/TXD0			
15		16				
J50	GPIOC12/CANRX/SDA1/RXD1	J50	GPIOC8/MISO0/RXD0/XB IN9			
2-	GHOCIZ/CANNA/SDAI/NADI	2-				
17		18				
J50	GND	J50	GPIOC9/SCK0/XB IN4			
2-		2-				
19		20				
J50	No Connection	J50	GPIOC10/MOSI0/XB_IN5/MISO0			
2-		2-				
21		22				
J50	No Connection	J50	No Connection			
2-		2-				
23		24				
J50	No Connection	J50	No Connection			
2-		2-				
25		26				
J50	GPIOA8/ANC16&CMPD_IN1	J50	GPIOF12/MISO1/PWMB_FAULT2			
3-1		3-2				
J50	GPIOA9/ANC17&CMPD_IN2	J50	GPIOF13/MOSI1/PWMB_FAULT1			
3-3		3-4				
J50	GPIOA10/ANC18&CMPD_IN3	J50	GPIOF14/SCK1/PWMB_FAULT0			
3-5		3-6				



	Auxiliary Connectors J502 and J503 Pin Out				
Pin	MC56F84789 DSC Signal	Pin	MC56F84789 DSC Signal		
#		#			
J50	GPIOA11/ANC19&VREFHC	J50	GPIOF15/RXD0/XB_IN10		
3-7		3-8			
J50	GPIOB8/ANC20&VREFLC	J50	GPIOG0/PWMB_1B/XB_OUT6		
3-9		3-			
		10			
J50	GPIOB9/ANC21/XB_IN9/MISO2	J50	GPIOG1/PWMB_1A/XB_OUT7		
3-		3-			
11		12			
J50	GPIOB10/ANC22/XB_IN8/MOSI2	J50	GPIOG2/PWMB_0B/XB_OUT4		
3-		3-			
13		14			
J50	GPIOB11/ANC23/XB_IN7/SCK2	J50	GPIOG3/PWMB_0A/XB_OUT5		
3-		3-			
15		16			
J50	GPIOD5/RXD2/XB_IN5/XB_OUT9	J50	GPIOG4/PWMB_3B/PWMA_FAULT2		
3-		3-			
17		18			
J50	GPIOD6/TXD2/XB_IN4/XB_OUT8	J50	GPIOG5/PWMB_3A/PWMA_FAULT3		
3-		3-			
19		20			
J50	GPIOD7/XB_OUT11/XB_IN7/MISO1	J50	GPIOG6/PWMA_FAULT4/PWMB_FAULT4/TB2		
3-		3-	/XB_OUT8		
21		22			
J50	GPIOE8/PWMB_2B/PWMA_FAULT0	J50	GPIOG7/PWMA_FAULT5/PWMB_FAULT5/XB_		
3-		3-	OUT9		
23		24			
J50	GPIOE9/PWMB_2A/PWMA_FAULT1	J50	GPIOG8/PWMB_0X/PWMA_0X/TA2/XB_0UT1		
3-		3-	0		
25		26			
J50		J50	GPIOG9/PWMB_1X/PWMA_1X/TA3/XB_OUT1		
3-	RXD2/PWMA_FAULT7/PWMB_FAULT7/X	3-	1		
27	B_OUT11	28			
J50		J50	GPIOG10/PWMB_2X/PWMA_2X/XB_IN8/SS_B		
3-	/PWMA_FAULT6/PWMB_FAULT6/XB_OU	3-	2		
29		30			
J50 2	GPIOF11/TXD0/XB_IN11	J50 2	GPIOG11/TB3/CLKO0/MOSI1		
3- 21		3-			
31		32			



2.3.6 Tower Elevator Connectors

The TWR-56F8400 board features two expansion card-edge connectors that interface to Elevator boards in a Tower System: the Primary and Secondary Elevator connectors. The Primary Elevator connector, comprised of sides A and B, is utilized by the TWR-56F8400 board, while the Secondary Elevator connector only makes connections to ground (GND). **Table 7** in **Appendix A – Tower Elevator Connector Pin Functions** lists the pin functions for the Primary Elevator Connector.

2.3.7 Thermistors as Analog Inputs

The TWR-56F8400 board provides four thermistors (RT1-4) near the corners of the board that can be used as single ended or differential analog inputs to the MC56F84789 DSC as can be seen on sheet 6 of the schematic. In addition to each thermistor there is a resistor between the thermistor and P3_3V and another resistor between the thermistor and ground. The thermistors are all 10K ohm parts but the associated divider chain uses different resistors. This makes the voltage across the thermistor larger or smaller and provides the ability to try the different gain settings on the analog channels. All four thermistor circuits are designed to provide useable differential inputs over the temperature range of 90°C to -20°C. RT2 and RT4 both give a differential voltage of ~1.65V at 25°C. RT1 gives a differential voltage of 0.10V and RT3 gives a differential voltage of 0.28V at 25°C.

In addition to the thermistor voltage divider chain each thermistor has a 0.1 uF capacitor in parallel. Each thermistor circuit also has a header that allows the thermistor to be disconnected from the analog inputs to the DSC. If a user wishes to apply an external analog value these headers may be removed and the external analog signal attached to the DSC side of the headers. Finally, each analog input to the DSC has a 100 ohm series resistor and a 2200 pF capacitor as a low pass filter. This helps protect the DSC from electrostatic discharges and lowers the impedance of the analog signal so that it can be sampled with less noise.

2.3.8 CAN Transceiver

The TWR-56F8400 board has a CAN transceiver circuit that may be connected to the CAN pins of the DSC. The CAN transceiver (U503) can be connected to the GPIOC11/CANTX/SCL1/TXD1 and GPIOC12/CANRX/SDA1/RXD1 pins of the DSC through the header at J16. Installing a shunt from pin 1 to pin 2 connects the TXD nets and installing a shunt from pin 3 to pin 4 connects the RXD nets. Note that the GPIOC11/CANTX/SCL1/TXD1 and GPIOC12/CANRX/SDA1/RXD1 nets also go to the primary elevator edge connector (J500A) pins B41 and B42 and to the Auxiliary connector (J502) pins 15 and 17. When using these nets for CAN communications care must be taken that these nets are not driven from these other connectors.

The transceiver is capable of running from 3.3V and is powered by the P3_3V/5V power rail. The transceiver output is connected to header J13 with CANH connected to pin 4 and CANL connected to



pin 3. A 120 ohm parallel termination resistor, R560, may be connected between these nets by installing a shunt on header J15.

2.3.9 IRQ or Input Pushbuttons

The TWR-56F8400 board has two pushbuttons (SW1 and SW2) that can be used to provide inputs or interrupts to the DSC. Each has a 10K ohm pull up resistor to P3_3V and a 0.1 uF capacitor to ground to minimize bounce on the output.

Pushbutton SW1 is connected to header J4 where the switch output can be connected to either DSC pin GPIOC2/TXD0/TB0/XB_IN2/CLKO0 (default) or GPIOF6/TB2/PWMA_3X/PWMB_3X/XB_IN2 depending on the position of the shunt on the header (pin 1 to pin 2 is the default). Similarly, pushbutton SW2 is connected to header J5 where the switch output can be connected to either DSC pin GPIOF8/RXD0/TB1/CMPD_O (default) or GPIOF7/TB3/CMPC_O/SS1_B/XB_IN3 depending on the position of the shunt on the header (pin 1 to pin 2 is the default).

If the pushbutton switches are not being used as an interrupt, or other purpose, it is best to remove the shunt to the DSC so that the 0.1 uF capacitor is not loading down the DSC pins.

2.3.10 RESET

The GPIOD4/RESET_B pin of the DSC is connected to the motor control connector and the tower connector but also to a pushbutton (SW3) and through buffers to the OSBDM/OSJTAG chip. It is pulled to P3_3V by a 10K ohm resistor. It may be pulled low by the pushbutton or by Q1 in response to a high output from the OSBDM/OSJTAG chip (pin 1) on the TRESET_OUT net. The state of the GPIOD4/RESET_B signal is provided to the OSBDM/OSJTAG chip through a voltage translator (U504B). This buffer is powered by the P3_3V/5V power rail so that its input will remain high impedance when there is no USB cable connected. The buffered RESET signal is provided to pin 33 of the OSBDM/OSJTAG chip and is used by the OSBDM/OSJTAG program in that chip.

2.3.11 JTAG Header and OSBDM/OSJTAG Disconnect Header

The TWR-56F8400 board includes an OSBDM/OSJTAG circuit as a debug interface to the MC56F84789 DSC for normal purposes. If the user desires to use a different debugger connection, header J14 provides a connection point for an external JTAG aware debugger. If an external debugger is connected to the JTAG header the shunts at J21 (pins 1 to 2, 3 to 4, 5 to 6, and 7 to 8) which connect the OSBDM/OSJTAG circuit to the JTAG signals should be removed, allowing the external debugger to control the JTAG port, rather than the 'JM60.

The TWR-56F8400 board provides a 2.2K ohm pull up resistor to 3.3V on the TMS line. If an external JTAG aware debugger also has a pull up on this line, the external debugger may not be able to pull the TMS line low. If this happens, remove one of the pull up resistors on the TMS line.



2.4 OSBDM/OSJTAG

2.4.1 Debug Interface

An on-board MC9S08JM60 based Open Source BDM (OSBDM/OSJTAG) circuit provides a debug interface to the MC56F84789. A standard USB A male to Mini-B male cable (supplied) can be used for debugging via the USB connector, J18.

2.4.2 USB Serial Bridge Interface

The on-board MC9S08JM60 can also be used as a USB to Serial bridge interface for the UART signals from the MC56F84789 DSC. This bridge circuit is described in detail in section **2.3.2 Serial I/O Source Select Headers.**

The RXD_SEL signal goes to the MC56F84789 DSC. The USB bridge chip is powered by 5V so its output is a 5V output. The buffer (U505) is able to accept the 5V signal from the USB bridge chip (T_TXD1) and converts it to the 3.3V signal (RXD_SEL) for the DSC. The buffer output is enabled by an inverted RTS signal (TXD_RXD_EN_B) from the USB bridge chip. If there is no USB connection to the TWR board the RTS signal is not driven and the 3.3V powered inverter (U502C) input is biased low disabling the output of the buffer.

In a similar way TXD_SEL is a 3.3V signal from the MC56F84789 DSC. The USB bridge chip is expecting a 5V input on T_RXD1. The buffer between these two signals (U504C) is powered by P3_3V/5V. It will accept the 3.3V input from the DSC and convert it to the 5V signal needed by the USB bridge chip. The buffer output is enabled by the same inverted RTS signal (TXD_RXD_EN_B) discussed above. If there is no USB connection to the TWR board, the RTS signal is not driven and the 5V powered buffer disabled so nothing is driving the powered down USB bridge chip.

The serial interface signals from the MC56F84789 DSC may be routed to the MC9S08JM60 serial interface via header and Berg straps. Using the USB serial bridge the MC9S08JM60 will convert the serial interface data into USB packets and send them to the host PC where they may be handled by a PC application normally conversant with a serial port.

2.4.3 Clocking the OSBDM/OSJTAG MCU (MC9S08JM60)

The MC9S08JM60 MCU uses an on board 4 MHz external crystal circuit (Y2, R16, C7, and C9) for its clock. There are no user options for clocking the MC9S08JM60.

2.4.4 Reserved Function Select Header

Header J20 selects whether the on-board MC9S08JM60 MCU operates as an OSBDM/OSJTAG debug interface or as a USB Serial Bridge interface on *older* versions of S08 firmware such as may have existed



on prototypes of the TWR56F8400. Leaving the shunt on the header enables the OSBDM/OSJTAG debug interface. Removing the shunt on header J20 enables the USB Serial Bridge interface. The header, J20, is subsequently reserved for future use.

2.4.5 Bootloader Enable

In addition to the OSBDM/OSJTAG Debug interface and the USB Serial Bridge interface the MC9S08JM60 device used in the OSBDM/OSJTAG circuit is preprogrammed with a USB Bootloader. The USB Bootloader will run following a power-on reset if a shunt is installed on header J17. This allows in-circuit reprogramming of the JM60 flash memory via USB. This enables the OSBDM/OSJTAG firmware to be upgraded by the user when upgrades become available. In normal OSBDM/OSJTAG / USB Serial Bridge operation this shunt must be left off. For details on the USB Bootloader, refer to <u>Application Note AN3561</u> on the Freescale website (<u>http://www.freescale.com</u> The USB Bootloader communicates with a GUI application running on a host PC. The GUI application

can be found on the <u>Freescale website</u>; search keyword "JM60 GUI". Refer to section 2.5 and 3.3 of AN3561 for details on installing and running the application.

2.4.6 BDM Header

The BDM header at J22 is used for initial programming of the MC9S08JM60 MCU or if reprogramming when the bootloader fails. An external 9S08 BDM debugger would be connected to J22 and used to program the MCU. This is not expected to be a normal user interface, however it is useful if the 'JM60 device is inadvertently reprogrammed with firmware that is not functional.

2.4.7 OSBDM/OSJTAG Status LEDs

The MC9S08JM60 OSBDM/OSJTAG MCU controls two status LEDs at D12 and D13. Refer to the OSBDM/OSJTAG instructions for the meaning of the LEDs.

2.4.8 OSBDM/OSJTAG Voltage Translation

Since the OSBDM/OSJTAG MCU runs from 5V and the 56F84789 DSC runs from 3.3V there needs to be voltage translation between the two circuits. This is done through U505, U504A and U502B. U505 has 5V tolerant inputs and provides 3.3V signals (TCK, TDI, and TMS) to the DSC's JTAG pins through the shunts on header J21. U504A is powered by the P3_3V/5V rail and translates the 3.3V TDO signal from the DSC to a 5V signal for the OSBDM/OSJTAG MCU. The outputs of both of these translators are high impedance if the signal OUT_EN_B goes high. This happens if the OSBDM/OSJTAG circuit looses power (no power to the USB connector). In that case the OUT_EN signal from the OSBDM/OSJTAG MCU (pin 15) is biased low by R12. The inverter at U502B then drives OUT_EN_B high in response. Additional information is included in section **2.4.2**.



3 Jumper Table

There are several headers provided for isolation, configuration, and feature selection. Refer to **Table 6** for details. The default shunt positions are shown in **bold**.

Jumper	Function	Shunts	Description
J1	Thermistor RT1 Connect	1-2, 3-4	Connect RT1 circuit to the MC56F827 DSC
JI	Thermistor TTT Connect	none	Disconnect RT1 circuit from the MC56F84789 DSC
J2	Thermistor RT2 Connect	1-2, 3-4	Connect RT2 circuit to the MC56F827 DSC
JZ		none	Disconnect RT2 circuit from the MC56F84789 DSC
			Connect SW1 to MC56F84789 DSC pin
		1-2	GPIOC2/TXD0/TB0/XB_IN2/CLKO0
J4	IRQ1 Select	3-4	Connect SW1 to MC56F84789 DSC pin
			GPIOF6/TB2/PWMA_3X/PWMB_3X/XB_IN2 Disconnect SW1 from the MC56F84789 DSC
		none	Connect SW2 to MC56F84789 DSC pin
		1-2	GPIOF8/RXD0/TB1/CMPD_O
J5	IRQ0 Select		Connect SW2 to MC56F84789 DSC pin
		3-4	GPIOF7/TB3/CMPC_O/SS1_B/XB_IN3
		none	Disconnect SW2 from the MC56F84789 DSC
		J6-1 to	Connect the on-board voltage regulator to the
		J7-2	P3_3V power rail
		J7-1 to	Connect P3_3V_MOTOR to the P3_3V power rail
J6 and J7	3.3V Source Select	J7-2 J7-2 to	(power the 3.3V rail from the motor control connector) Connect P3 3V ELEV to the P3 3V power rail
J7		J7-2 10 J7-3	(power the 3.3V rail from the tower connector)
		J7-2	
		open	Disconnect the P3_3V power rail – no power
			Connect ELEV_RXD0 from the Tower connector
			to MC56F84789 DSC pin
		1-2	GPIOF8/RXD0/TB1/CMPD_O
			Connect RXD_SEL from the USB Serial Bridge to
			MC56F84789 DSC pin
		2-3	GPIOF8/RXD0/TB1/CMPD_O
10	RXD Source Select (note that	Pin 2	Disconnect MC56F84789 DSC pin
J8	only one connection can be made to pin 3 at a time)	open	GPIOF8/RXD0/TB1/CMPD_O
			Connect RXD_SEL from the USB Serial Bridge to
		3-4	MC56F84789 DSC pin GPIO F5 /RXD1/XB_OUT9
			Connect ELEV_RXD1 from the Tower connector
		4-5	to MC56F84789 DSC pin GPIO F5 /RXD1/XB_OUT9
		Pin 4	Disconnect MC56F84789 DSC pin
		open	GPIOF5/RXD1/XB OUT9
		open	

Table 6. TWR-56F8400 Jumper Table



Jumper	Function	Shunts	Description
		Chanto	Connect ELEV_TXD0 from the Tower connector to MC56F84789 DSC pin
		1-2	GPIOC2/TXD0/TB0/XB IN2/CLKO0
			Connect TXD_SEL from the USB Serial Bridge to
			MC56F84789 DSC pin
		2-3	GPIOC2/TXD0/TB0/XB_IN2/CLKO0
	TXD Source Select (note that	Pin 2	Disconnect MC56F84789 DSC pin
J9	only one connection can be	open	GPIOC2/TXD0/TB0/XB IN2/CLKO0
	made to pin 3 at a time)		Connect TXD_SEL from the USB Serial Bridge to
		3-4	MC56F84789 DSC pin GPIOF4/TXD1/XB_OUT8
			Connect ELEV_TXD1 from the Tower connector
		4-5	to MC56F84789 DSC pin GPIO F4 /TXD1/XB_OUT8
		Pin 4	Disconnect MC56F84789 DSC pin
		open	GPIOF4/TXD1/XB OUT8
		J10-1 to	Connect the power in barrel connector (through fuse
		J11-2	F1) to the input of the 3.3V voltage regulator
	5V Source Select	J11-1 to	Connect P5V_TRG_USB (the switched USB 5V) to
J10 and		J11-2	the input of the 3.3V voltage regulator
J11		J11-2 to J11-3	Connect P5V_ELEV to the input of the 3.3V voltage
		J11-3	regulator
		open	Disconnect the input of the 3.3V voltage regulator
J12	Unused	open	Unused
J15	CAN Termination Enable	1-2	Connect the 120 ohm CAN termination resistor
010	CAN TERMINATION ENable	open	No CAN termination
			Connect the CAN transceiver TXD and RXD to
14.0			MC56F84789 DSC pins
J16	CAN Enable	1-2, 3-4	GPIOC11/CANTX/SCL1/TXD1 GPIOC12/CANRX/SDA1/RXD1
		open	Disconnect the CAN transceiver
		1-2	Enable USB bootloading of the MCU Flash memory
J17	MC9S08JM60 Bootload Enable	open	Disable bootloading
		1-2, 3-4	Connect RT3 circuit to the MC56F827 DSC
J19	Thermistor RT3 Connect	none	Disconnect RT3 circuit from the MC56F84789 DSC
100	RESERVEC /	1-2	Reserved-deprecated
J20	OSBDM/OSJTAG Enable	none	Reserved-deprecated
J21		1-2, 3-4,	Connect the OSBDM/OSJTAG debug signals
	OSBDM/OSJTAG Connect to	5-6, 7-8	(JTAG) to the MC56F84789 DSC JTAG pins
	JTAG		Disconnect OSBDM/OSJTAG from the MC56F84789
		none	DSC
J23	Thermistor RT4 Connect	1-2, 3-4	Connect RT4 circuit to the MC56F827 DSC Disconnect RT4 circuit from the MC56F84789 DSC
		none	DISCONDECT BIT4 CITCUIL FROM THE MICSHE84789 DSC



Appendix A – Tower Elevator Connector Pin Functions

Table 7 provides the pin out for the Primary Elevator Connector. An "**X**" in the "Used" column indicates that there is a connection from the TWR-56F8400 board to that pin on the Elevator connector. An "**X**" in the "Jmp" column indicates that a jumper is available that can isolate the onboard circuitry from the Elevator connector. An "<u>X</u>" in the "Jmp" column indicates that a jumper is available that can isolate part of the onboard circuitry from the Elevator connector.

The function listed in the "Usage" column is the function(s) that the pin is expected to be programmed to provide when used with the Tower system. All of the MC56F84789 pins (except power) have multiple functions. Not all of the possible functions are shown.

Note that all analog pins (ANAn or ANBn) have a low pass filter to ground consisting of a 100 ohm resistor and a 2200 pf capacitor. This is to protect the analog inputs of the DSC from a static discharge at one of the connectors. See schematic sheets 6 and 7 in **Appendix B – TWR-56F8400 Board Schematic**.

	TWR-56F8400 Primary Connector								
Pin	Name	Usage	Used	Jmp	Pin	Name	Usage	Used	Jmp
B1	5V_1	5V Power	Х	х	A1	5V_2	5V Power	х	Х
B2	GND	Ground	x		A2	GND_9	Ground	х	
B3	3.3V_1	3.3V Power	x	х	A3	3.3V_4	3.3V Power	х	х
B4	ELE_PS_SENSE_1	3.3V Power	х	x	A4	3.3V_5	3.3V Power	х	х
B5	GND_2	Ground	х		A5	GND_10	Ground	х	
B6	GND_3	Ground	х		A6	GND_11	Ground	х	
Β7	SDHC_CLK / SPI1_CLK	SCK (see also pin B48)	х		A7	I2C0_SCL	SCLO	х	
B8	SDHC_D3 / SPI1_CS1_b				A8	I2C0_SDA	SDA0	х	
В9	SDHC_D3 / SPI1_CS0_b	SS_B (see also pin B46)	х		A9	GPIO9/UART1_CTS1	GPIOA4/ANA4	х	<u>X</u>
B10	SDHC_CMD / SPI1_MOSI	MOSI (see also pin B45)	х		A10	GPIO8/SDHC_D2	GPIOA5/ANA5	х	<u>X</u>
B11	SDHC_D0 / SPI1_MISO	MISO (see also pin B44)	х		A11	GPIO7 / SD_WP_DET	GPIOA6/ANA6	х	<u>X</u>
								- 1	
B12	ETH_COL_1				A12	ETH_CRS			
B13	ETH_RXER_1				A13	ETH_MDC_1			
B14	ETH_TXCLK_1				A14	ETH_MDIO_1			
B15	ETH_TXEN_1				A15	ETH_RXCLK_1			
B16	ETH_TXER				A16	ETH_RXDV_1			
B17	ETH_TXD3				A17	ETH_RXD3			
B18	ETH_TXD2				A18	ETH_RXD2			
B19	ETH_TXD1_1				A19	ETH_RXD1_1			
B20	ETH_TXD0_1				A20	ETH_RXD0_1			
B21	GPIO1 / UART1_RTS1	GPIOB4/ANB4&CMPC_M1	х	<u>X</u>	A21	I2S0_MCLK			
B22	GPIO2 / SDHC_D1	GPIOB5/ANB5&CMPC_M2	х	<u>X</u>	A22	I2S0_DOUT_SCLK			

Table 7. TWR-56F8400 Primary Elevator Connector Pin Out



	TWR-56F8400 Primary Connector								
Pin	Name	Usage	Used			Name	Usage	Used	Jmp
B23	GPIO3	GPIOB6/ANB6&CMPB M1	х	<u>X</u>	A23	I2S0_DOUT_WS			
B24	CLKIN0	XTAL&CLKIN	х	<u>X</u>	A24	I2S0_DOUT_DIN0			
B25	CLKOUT1				A25	I2S0_DOUT_DOUT0			
B26	GND_4	Ground	х		A26	GND_12	Ground	х	
B27	 AN7	ANB3&CMPC_M0	х		A27	AN3	ANA3&CMPA_M2	х	<u>X</u>
B28	AN6	ANB2&CMPC_P2	х		A28	AN2	ANA2&CMPA_M1	Х	
B29	AN5	ANB1&VERFLB&CMPB_M0	х		A29	AN1	ANA1&VREFLA&CMPA_M0	х	
B30	AN4	ANB0&VERFHB&CMPB P2	х		A30	AN0	ANA0&VREFHA&CMPA_P2/CMPC_O	х	
B31	GND_5	Ground	х		A31	GND_13	Ground	х	
B32	DAC1				A32	DACO	DACO	х	
B33	TMR3	TA3	х		A33	TMR1	TA1	х	
B34	TMR2	TA2	х		A34	TMR0	ТАО	х	
B35	GPIO4	GPIOB7/ANB7&CMPB M2	х	X	A35	GPIO6	GPIOA7/ANA7	х	X
B36	3.3V 2	3.3V Power	х	x	A36	3.3V_6	3.3V Power	х	x
B37	PWM7	PWM3B	х		A37	PWM3	PWM3A	х	
B38	PWM6	PWM2B	х		A38	PWM2	PWM2A	х	
B39	PWM5	PWM1B	X		A39	PWM1	PWM1A	X	
B40	PWM4	PWM0B	X		A40	PWM0	PWM0A	X	
B41	CAN0_RX0	CANRX	X	X	A41	UART0_RX	ELEV_RXD0 (see also pin B61)	X	x
B42	 CAN0 TX0	CANTX	X	X	A42	UART0_TX	ELEV TXD0 (see also pin B62)	X	x
B43	1WIRE				A43	UART1_RX	ELEV_RXD1	X	x
B44	SPI0_MISO/IO1	MISO (see also pin B11)	х		A44	UART1_TX	 ELEV_TXD1	X	х
B45	SPI0_MOSI/IO0	MOSI (see also pin B10)	X		A45	VSSA	_		
B46	SPI0_CS0_b	SS_B (see also pin B9)	X		A46	VDDA			
B47	SPI0_CS1_b	,			A47	CAN1_RX			
B48	SPIO_CLK	SCK (see also pin B7)	х		A48	CAN1 TX			
B49	 GND_6	Ground	x		A49	GND_14	Ground	х	-
B50	I1C1 SCL1	SCL1	х		A50	GPIO14			-
B51	I2C1 SDA1	SDA1	х		A51	GPIO15			
B52	GPIO5/SPI0 HOLD/IO3	GPIOF0	х		A52	GPIO16/SPI0_WP/IO2			
B53	RSRV_B53				A53	GPIO17			
B54	RSRV B54				A54	USB0_DM			
B55	IRQ_H				A55	USB0_DP			
B56	IRQ_G				A56	USB0_ID			
B57	IRQ_F				A57	USB0_VBUS			
B58	IRQ_E				A58	I2S0_DIN_SCK	ТВЗ	х	<u>x</u>
B59	IRQ_D				A59	 I2S0_DIN_WS	ТВ2	х	X
B60	IRQ_C				A60	I2S0_DIN1			
B61	IRQ_B	TB1 (see also pin A41)	х	Х	A61	I2S0_DOUT1			1
B62	IRQ_A	TB0 (see also pin A42)	X	X	A62	 RSTIN_b	RESET_B	х	
B63	EBI_ALE / EBI_CS1_b		-		A63	 RSTOUT_b	RESET_B	X	
B64	EBI_CS0_b				A64	CLKOUT0	CLKO	X	
B65	 GND_7	Ground	х		A65	GND_15	Ground	X	
B66	EBI_AD15				A66	EBI_AD14			



	TWR-56F8400 Primary Connector								
Pin	Name	Usage	Used	Jmp	Pin	Name	Usage	Used	Jmp
B67	EBI_AD16				A67	EBI_AD13			
B68	EBI_AD17				A68	EBI_AD12			
B69	EBI_AD18				A69	EBI_AD11			
B70	EBI_AD19				A70	EBI_AD10			
B71	EBI_R/ W_b				A71	EBI_AD9			
B72	EBI_OE_b				A72	EBI_AD8			
B73	EBI_D7				A73	EBI_AD7			
B74	EBI_D6				A74	EBI_AD6			
B75	EBI_D5				A75	EBI_AD5			
B76	EBI_D4				A76	EBI_AD4			
B77	EBI_D3				A77	EBI_AD3			
B78	EBI_D2				A78	EBI_AD2			
B79	EBI_D1				A79	EBI_AD1			
B80	EBI_D0				A80	EBI_AD0			
B81	GND_8	Ground	х		A81	GND_16	Ground	х	
B82	3.3V_3	3.3V Power	X	Х	A82	3.3V_7	3.3V Power	х	Х



Appendix B – TWR-56F8400 Board Schematic

The Schematic supplied a standalone PDF file. Please go to <u>www.freescale.com/TWR-56F8400</u> to download.



Appendix C – TWR-56F8400 Board BOM

The BOM is supplied as an embedded worksheet object, just below. Right click on the object below and select "Worksheet Object", then "Open" to read the BOM or work with it as a spreadsheet.

Qty	Ref.	Mfr. Name	Mfr. Part Number	Mfr. Part Description		
3	C508,C511,C 545	TDK	C1608X5R1A225K	CAP CER 2.2UF 10V 10% X5R 0603		
		VENKEL COMPANY	C0603X5R100-225KNE	CAP CER 2.2UF 10V 10% X5R 0603		
		MURATA	GRM188R61A225KE34D	CAP CER 2.2UF 10V 10% X5R 0603		
25	C3,C4,C8,C50 0,C501,C503, C505,C509,C 510,C513,C51 4,C515,C530, C532,C533,C 535,C536,C53 7,C538,C539, C542,C543,C 544,C546,C54 7		CC0603KRX7R8BB104	CAP CER 0.10UF 25V 10% X7R 0603		
		WALSIN TECHNOLOGY CORP.	0603B104K250CT	CAP CER 0.10UF 25V 10% X7R 0603		
		VENKEL COMPANY	C0603X7R250-104KNE	CAP CER 0.10UF 25V 10% X7R 0603		
		MURATA	GRM188R71E104KA01	CAP CER 0.10UF 25V 10% X7R 0603		
		AVX	06033C104KAT2A	CAP CER 0.10UF 25V 10% X7R 0603		
		KEMET	C0603C104K3RAC	CAP CER 0.10UF 25V 10% X7R 0603		
2	C7,C9	SKYMOS	0603CG180J500NT	CAP CER 18PF 50V 5% C0G 0603		
		VENKEL COMPANY	C0603C0G500-180JNE	CAP CER 18PF 50V 5% C0G 0603		
		WALSIN TECHNOLOGY CORP.	0603N180J500LT	CAP CER 18PF 50V 5% C0G 0603		
		KEMET	C0603C180J5GAC	CAP CER 18PF 50V 5% C0G 0603		
		AVX	06035A180JAT2A	CAP CER 18PF 50V 5% C0G 0603		
		MURATA	GRM1885C1H180JA01J	CAP CER 18PF 50V 5% C0G 0603		
		YAGEO AMERICA	CC0603JRNPO9BN180	CAP CER 18PF 50V 5% C0G 0603		
7	C1,C2,C506,C 516,C520,C54 0,C541	TECHNOLOGY CORP.	0805X106K160CT	CAP CER 10UF 16V 10% X5R 0805		
		KYOCERA	CM21X5R106K16AT	CAP CER 10UF 16V 10% X5R 0805		



		YAGEO AMERICA	CC0805KKX5R7BB106	CAP CER 10UF 16V 10% X5R 0805
		AVX	0805YD106KAT2A	CAP CER 10UF 16V 10% X5R 0805
		KEMET	C0805C106K4PAC	CAP CER 10UF 16V 10% X5R 0805
		MURATA	GRM21BR61C106KE15L	CAP CER 10UF 16V 10% X5R 0805
15	C502,C504,C 507,C512,C51 7,C518,C519, C521,C522,C 523,C524,C52 5,C526,C527, C528	SMEC	MCCE222K0NRTF	CAP CER 2200PF 50V 10% X7R 0402
		WALSIN TECHNOLOGY CORP.	0402B222K500CT	CAP CER 2200PF 50V 10% X7R 0402
1	C534	MURATA	GRM1885C1H102JA01D	CAP CER 1000PF 50V 5% C0G 0603
		WALSIN TECHNOLOGY CORP.	0603N102J500LT	CAP CER 1000PF 50V 5% C0G 0603
2	L1,L2	TDK	MPZ2012S331A	IND FER BEAD 330OHM@100MHZ 2.5A SMT
2	L500,L501	MURATA	BLM18BD601SN1D	IND 600 OHM@100MHZ 0.2A 25% 0603 SMT
3	J15,J17,J20	SAMTEC	HTSW-102-07-G-S	HDR 1X2 TH 100MIL SP 335H AU 95L
		ANYTRONIC CORPORATIO N LIMITED	090021S02015-2LF	HDR 1X2 TH 100MIL SP 339H AU 98L
		SAMTEC	HTSW-102-07-SM-S	HDR 1X2 TH 100MIL SP 330H AU 100L
		SAMTEC	TSW-102-07-G-S	HDR 1X2 TH 100MIL SP 330H AU 100L
		3M	929647-01-02-EU	HDR 1X2 TH 100MIL SP 330H AU 100L
		SAMTEC	TSW-102-07-S-S	HDR 1X2 TH 100MIL SP 330H AU 100L
		FCI	77311-801-02LF	HDR 1X2 TH 100MIL SP 330H AU 100L
		ANYTRONIC CORPORATIO N LIMITED	090021S02018-2LF	HDR 1X2 TH 100MIL SP 339H AU 98L
1	TP4	COMPONENTS CORPORATIO N	TP-105-01-00	TEST POINT PIN .100 x .45 BLACK TH
		KEYSTONE ELECTRONICS	5001	TEST POINT BLACK 40 MIL DRILL 180 MIL TH
		KOBICONN	151-203-RC	TEST POINT PIN .100 x .45 BLACK TH
4	J4,J5,J7,J11	Pinrex Enterprise Co., Ltd	210-91-03GB01	HDR 1X3 TH 100MIL SP 339H AU 118L
		FCI	77311-801-03LF	HDR 1X3 TH 100MIL SP 339H AU 118L