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Features

- Supply Voltage 5V
- Very Low Power Consumption 125 mW
- Very Good Image Rejection By Means of Phase Control Loop for Precise 90° Phase Shifting
- Duty-cycle Regeneration for Single-ended LO Input Signal
- Low LO Input Level -10 dBm
- LO Frequency from 70 MHz to 1 GHz
- Power-down Mode
- 25 dB Gain Control
- Very Low I/Q Output DC Offset Voltage Typically < 5 mV

Benefits

- Low Current Consumption
- Easy to Implement
- Perfect Performance for Large Variety of Wireless Applications

Electrostatic sensitive device.

Observe precautions for handling.



1. Description

The silicon monolithic integrated circuit U2794B is a quadrature demodulator manufactured using Atmel's advanced UHF technology. This demodulator features a frequency range from 70 MHz to 1000 MHz, low current consumption, selectable gain, power-down mode and adjustment-free handling. The IC is suitable for direct conversion and image rejection applications in digital radio systems up to 1 GHz such as cellular radios, cordless telephones, cable TV and satellite TV systems.



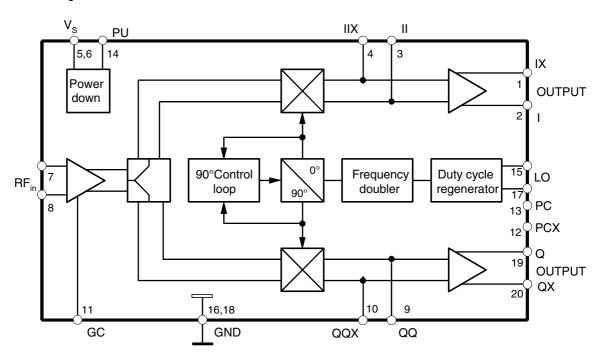
1000-MHz Quadrature Demodulator

U2794B





Figure 1-1. Block Diagram



2. Pin Configuration

Figure 2-1. Pinning SSO20

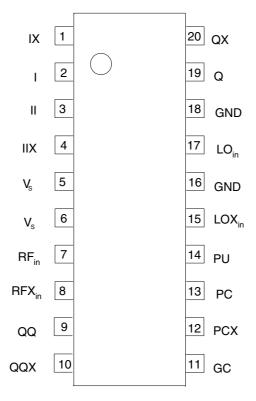


Table 2-1.Pin Description

	1 111 200011	
Pin	Symbol	Function
1	IX	IX output
2	I	I output
3	II	II lowpass filter I
4	IIX	IIX lowpass filter I
5	V _S	Supply voltage
6	V _S	Supply voltage
7	RF _{in}	RF input
8	RFX _{in}	RFX input
9	QQ	QQ lowpass filter Q
10	QQX	QQX lowpass filter Q
11	GC	GC gain control
12	PCX	PCX phase control
13	PC	PC phase control
14	PU	PU power up
15	LOX _{in}	LOX input
16	GND	Ground
17	LO _{in}	LO input
18	GND	Ground
19	Q	Q output
20	QX	QX output





3. Absolute Maximum Ratings

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Parameters	Symbol	Value	Unit
Supply voltage	V_S	6	V
Input voltage	V _i	0 to V _S	V
Junction temperature	T _j	+125	°C
Storage-temperature range	T _{stg}	-40 to +125	°C

4. Thermal Resistance

Parameters	Symbol	Value	Unit	
Junction ambient SSO20	R_{thJA}	140	K/W	

5. Operating Range

Parameters	Symbol	Value	Unit
Supply-voltage range	V_S	4.75 to 5.25	V
Ambient-temperature range	T _{amb}	-40 to +85	°C

6. Electrical Characteristics

Test conditions (unless otherwise specified); $V_S = 5V$, $T_{amb} = 25^{\circ}C$, referred to test circuit System impedance $Z_O = 50\Omega$, $f_{iLO} = 950$ MHz, $P_{iLO} = -10$ dBm

No.	Parameters	Test Conditions	Pin	Symbol	Min.	Тур.	Max.	Unit	Type*
1.1	Supply-voltage range		5, 6	V _S	4.75		5.25	V	Α
1.2	Supply current		5, 6	I _S	22	30	35	mA	Α
2	Power-down Mode								
2.1	"OFF" mode supply current	$V_{PU} \le 0.5V$ $V_{PU} = 1.0 V^{(1)}$	14, 5 6	I _{SPU}		≤ 1 20		μ Α μ Α	B D
3	Switch Voltage								
3.1	"Power ON"		14	V _{PON}	4			V	D
3.2	"Power DOWN"		14	V _{POFF}			1	V	D
4	LO Input, LO _{in}								
4.1	Frequency range		17	f _{iLO}	70		1000	MHz	D
4.2	Input level	(2)	17	P _{iLO}	-12	-10	- 5	dBm	D
4.3	Input impedance	See Figure 6-10	17	Z _{iLO}		50		Ω	D
4.4	Voltage standing wave ratio	See Figure 6-3	17	VSWR _{LO}		1.2	2		D
4.5	Duty-cycle range		17	DCR _{LO}	0.4		0.6		D
5	RF Input, RF _{in}		•	•	•	1	•	•	
5.1	Noise figure (DSB) symmetrical output	at 950 MHz ⁽³⁾ at 100 MHz	7, 8	NF		12 10		dB	D
5.2	Frequency range	$f_{iRF} = f_{iLO} \pm BW_{YQ}$	7, 8	f _{iRF}	40		1030	MHz	D
5.3	-1 dB input compression point	High gain Low gain	7, 8	P _{1dBHG} P _{1dBLG}		-8 +3.5		dBm	D
5.4	Second order IIP	(4)	7, 8	IIP _{2HG}		35		dBm	D
5.5	Third order IIP	High gain Low gain	7, 8	IIP _{3HG} IIP _{3LG}		+3 +13		dBm	D
5.6	LO leakage	Symmetric input Asymmetric input	7, 8	L _{OL}		≤ – 60 ≤ – 55		dBm	D
5.7	Input impedance	see Figure 6-10	7, 8	Z _{iRF}		500110.8		ΩlpF	D

^{*)} Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Notes: 1. During power-down status a load circuitry with DC-isolation to GND is assumed, otherwise a current of I \approx (VS -0.8V)/RI has to be added to the above power-down current for each output I, IX, Q, QX.

- 2. The required LO-Level is a function of the LO frequency (see Figure 6-6).
- 3. Measured with input matching. For 950 MHz, the optional transmission line T3 at the RF input may be used for this purpose. Noise figure measurements without using the differential output signal result in a worse noise figure.
- 4. Using pins 7 and 8 as a symmetric RF input, the second-order IIP can be improved.
- 5. Due to test board parasitics, this bandwidth may be reduced and not be equal for I, IX, Q, QX. If symmetry and full bandwidth is required, the lowpass pins 3, 4 and 9, 10 should be isolated from the board. the bandwidth of the I/Q outputs can be increased further by using a resistor between pins 3, 4, 9 and 10. These resistors shunt the internal loads of RI \sim 5.4 k Ω The decrease in gain here has to be considered.
- 6. The internal current of the output emitter followers is 0.6 mA. This reduces the undistorted output voltage swing at a 50Ω load to approximately 30 mV. For low signal distortion the load impedance should be RI $\geq 5 \text{ k}\Omega$
- 7. Referred to the level of the output vector $\sqrt{I^2 + Q^2}$
- 8. The low-gain status is achieved with an open or high-ohmic pin 11. A recommended application circuit for switching between high and low gain status is shown in Figure 6-1.





6. Electrical Characteristics (Continued)

Test conditions (unless otherwise specified); $V_S = 5V$, $T_{amb} = 25^{\circ}C$, referred to test circuit System impedance $Z_O = 50\Omega$, $f_{iLO} = 950$ MHz, $P_{iLO} = -10$ dBm

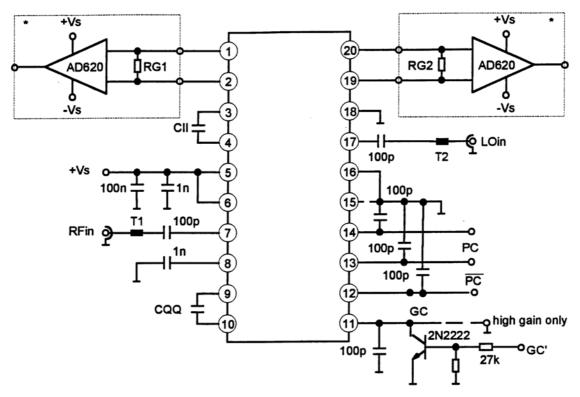
Parameters	Test Conditions	Pin	Symbol	Min.	Тур.	Max.	Unit	Type*
I/Q Outputs (I, IX, Q,	QX) Emitter Follower	I = 0.6 mA						
3-dB bandwidth w/o external C		1, 2, 19, 20	BWI/Q	≥ 30			MHz	D
I/Q amplitude error		1, 2, 19, 20	Ae	-0.5	≤±0.2	+0.5	dB	В
I/Q phase error		1, 2, 19, 20	Pe	-3	≤ ±1.5	+3	Deg	В
I/Q maximum output swing	Symm. output $R_L > 5 \text{ k}\Omega$	1, 2, 19, 20	V _{PP}			2		D
DC output voltage		1, 2, 19, 20	V _{OUT}	2.5	2.8	3.1	V	Α
DC output offset voltage	(6)	1, 2, 19, 20	V _{offset}		< 5		mV	Test spec.
Output impedance	see Figure 6-10	1, 2, 19, 20	Z _{out}		50		Ω	D
Gain Control, GC								
Control range power Gain high Gain low	(7)	11	GCR G _H G _L		25 23 –2		dB dBm dBm	D B D
Switch Voltage	•							
"Gain high"		11				1	V	
"Gain low"	(8)	11 < open			_			
Settling Time, ST								
Power "OFF" - "ON"			T _{SON}		< 4		μs	D
Power "ON" - "OFF"			T _{SOFF}		< 4		μs	D
	Parameters I/Q Outputs (I, IX, Q, G) 3-dB bandwidth w/o external C I/Q amplitude error I/Q phase error I/Q maximum output swing DC output voltage DC output offset voltage Output impedance Gain Control, GC Control range power Gain high Gain low Switch Voltage "Gain high" "Gain low" Settling Time, ST Power "OFF" - "ON"	I/Q Outputs (I, IX, Q, QX) Emitter Follower 3-dB bandwidth w/o external C I/Q amplitude error I/Q phase error I/Q maximum output swing Symm. output R _L > 5 kΩ DC output voltage DC output offset voltage (6) Output impedance see Figure 6-10 Gain Control, GC Control range power Gain high Gain low (7) Switch Voltage (8) "Gain low" (8) Settling Time, ST Power "OFF" - "ON"	$ \begin{array}{ c c c c c } \hline \textbf{Parameters} & \textbf{Test Conditions} & \textbf{Pin} \\ \hline \textbf{I/Q Outputs (I, IX, Q, QX) Emitter Follower I = 0.6 mA} \\ \hline \textbf{3-dB bandwidth} & 1, 2, 19, \\ 20 & 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{I/Q amplitude error} & 1, 2, 19, \\ 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{I/Q phase error} & Symm. output & 1, 2, 19, \\ 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{DC output voltage} & 1, 2, 19, \\ 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{DC output offset} & \textbf{(6)} & 1, 2, 19, \\ 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{DC output impedance} & see Figure 6-10 & 1, 2, 19, \\ 20 & \textbf{Gain Control, GC} & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{Control range power Gain high Gain low} & \textbf{11} & 20 & 20 & 20 & 20 & 20 & 20 \\ \hline \textbf{Switch Voltage} & \textbf{(7)} & \textbf{11} & \textbf{11} & \textbf{(8)} & \textbf{11} & \textbf{(9en)} & \textbf{Settling Time, ST} \\ \hline \textbf{Power "OFF" - "ON"} & \textbf{Power "OFF" - "ON"} & \textbf{(6)} & \textbf{(6)} & \textbf{(6)} & \textbf{(6)} & \textbf{(7)} & \textbf{(6)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(7)} & \textbf{(7)} & \textbf{(7)} & \textbf{(7)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(8)} & \textbf{(7)} & \textbf{(7)} & \textbf{(8)} & \textbf{(8)} & \textbf{(8)} & \textbf{(7)} & \textbf{(8)} & $	$ \begin{array}{ c c c c c } \hline \textbf{Parameters} & \textbf{Test Conditions} & \textbf{Pin} & \textbf{Symbol} \\ \hline \textbf{I/Q Outputs (I, IX, Q, QX) Emitter Follower I = 0.6 mA} \\ \hline \textbf{3-dB bandwidth} & 1, 2, 19, \\ w/o external C & 1, 2, 19, \\ 20 & Ae \\ \hline \textbf{I/Q amplitude error} & 1, 2, 19, \\ 20 & Ae \\ \hline \textbf{I/Q phase error} & 1, 2, 19, \\ 20 & Pe \\ \hline \textbf{I/Q maximum output} & Symm. output \\ R_L > 5 k\Omega & 20 & V_{PP} \\ \hline \textbf{DC output voltage} & 1, 2, 19, \\ 20 & V_{OUT} \\ \hline \textbf{DC output offset} & \textbf{(6)} & 1, 2, 19, \\ 20 & V_{offset} \\ \hline \textbf{Output impedance} & see Figure 6-10 & 1, 2, 19, \\ \hline \textbf{Cain Control, GC} \\ \hline \textbf{Control range power} & \\ Gain high & Gain low & GL \\ \hline \textbf{Switch Voltage} & \textbf{(8)} & 11 < open \\ \hline \textbf{Settling Time, ST} \\ \hline \textbf{Power "OFF" - "ON"} & T_{SON} \\ \hline \end{array} $	$\begin{array}{ c c c c c } \hline \textbf{Parameters} & \textbf{Test Conditions} & \textbf{Pin} & \textbf{Symbol} & \textbf{Min.} \\ \hline \textbf{I/Q Outputs (I, IX, Q, QX) Emitter Follower I = 0.6 mA} \\ \hline \textbf{3-dB bandwidth} & 1, 2, 19, \\ $	$ \begin{array}{ c c c c c } \hline \textbf{Parameters} & \textbf{Test Conditions} & \textbf{Pin} & \textbf{Symbol} & \textbf{Min.} & \textbf{Typ.} \\ \hline \textbf{I/Q Outputs (I, IX, Q, QX) Emitter Follower I = 0.6 mA} \\ \hline \textbf{3-dB bandwidth} & 1, 2, 19, \\ w/o \text{external C} & 20 & BWI/Q & \geq 30 \\ \hline \textbf{I/Q amplitude error} & 1, 2, 19, \\ 20 & Ae & -0.5 & \leq \pm 0.2 \\ \hline \textbf{I/Q phase error} & 1, 2, 19, \\ 20 & Pe & -3 & \leq \pm 1.5 \\ \hline \textbf{I/Q maximum output} & Symm. output \\ R_L > 5 k\Omega & 20 & V_{PP} \\ \hline \textbf{DC output voltage} & 1, 2, 19, \\ 20 & V_{OUT} & 2.5 & 2.8 \\ \hline \textbf{DC output offset} & (6) & 1, 2, 19, \\ 20 & V_{offset} & <5 \\ \hline \textbf{Output impedance} & see Figure 6-10 & 1, 2, 19, \\ 20 & V_{offset} & 50 \\ \hline \textbf{Gain Control, GC} & & & & & & \\ \hline \textbf{Control range power} & & & & & & & \\ \hline \textbf{Gain low} & & & & & & & \\ \hline \textbf{Switch Voltage} & & & & & & \\ \hline \textbf{Gain low}^{T} & & & & & & & \\ \hline \textbf{Settling Time, ST} & & & & & & \\ \hline \textbf{Power "OFF" - 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"ON"} & & & & & & & & \\ \hline \textbf{Tson} & & & & & & & \\ \hline \textbf{Ae} & & & & & & & \\ \hline \textbf{Settling Time, ST} & & & & & & \\ \hline \textbf{Power "OFF" - "ON"} & & & & & & & \\ \hline Control Poly Empty of the proper in the proper is a symbol of the proper in the proper in the proper is a symbol of the proper in the proper in the proper is a symbol of the proper in the$	$ \begin{array}{ c c c c c c } \hline \textbf{Parameters} & \textbf{Test Conditions} & \textbf{Pin} & \textbf{Symbol} & \textbf{Min.} & \textbf{Typ.} & \textbf{Max.} & \textbf{Unit} \\ \hline \textbf{I/Q Outputs (I, IX, Q, QX) Emitter Follower I = 0.6 mA} \\ \hline \textbf{3-dB bandwidth} & & 1, 2, 19, \\ w/o \ \text{external C} & & 1, 2, 19, \\ 20 & Ae & -0.5 & \leq \pm 0.2 & \pm 0.5 & dB \\ \hline \textbf{I/Q amplitude error} & & 1, 2, 19, \\ 20 & Pe & -3 & \leq \pm 1.5 & \pm 3 & Deg \\ \hline \textbf{I/Q phase error} & & 1, 2, 19, \\ 20 & V_{PP} & & 2 & \\ \hline \textbf{DC output voltage} & Symm. output \\ swing & R_L > 5 \ k\Omega & 1, 2, 19, \\ 20 & V_{OUT} & 2.5 & 2.8 & 3.1 & V \\ \hline \textbf{DC output offset} \\ voltage & & & & & & & & & & & & \\ \hline \textbf{Output impedance} & see \ \textbf{Figure 6-10} & & & & & & & & & & \\ \hline \textbf{Sem Control, GC} & & & & & & & & & & & \\ \hline \textbf{Control range power} \\ \textbf{Gain low} & & & & & & & & & & & & & \\ \hline \textbf{Switch Voltage} & & & & & & & & & & \\ \hline \textbf{Switch Voltage} & & & & & & & & & & \\ \hline \textbf{Cain low}^n & & & & & & & & & & & \\ \hline \textbf{Settling Time, ST} & & & & & & & & & & & \\ \hline \textbf{Power "OFF" - "ON"} & & & & & & & & & & & & \\ \hline \textbf{Power "OFF" - "ON"} & & & & & & & & & & & \\ \hline \textbf{Settling Time, ST} & & & & & & & & & & & & \\ \hline \textbf{Power "OFF" - "ON"} & & & & & & & & & & & \\ \hline \textbf{Settling Time, ST} & & & & & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & & & & & & & \\ \hline \textbf{MHz} & & $

^{*)} Type means: A = 100% tested, B = 100% correlation tested, C = Characterized on samples, D = Design parameter

Notes: 1. During power-down status a load circuitry with DC-isolation to GND is assumed, otherwise a current of I ≈ (VS –0.8V)/RI has to be added to the above power-down current for each output I, IX, Q, QX.

- 2. The required LO-Level is a function of the LO frequency (see Figure 6-6).
- 3. Measured with input matching. For 950 MHz, the optional transmission line T3 at the RF input may be used for this purpose. Noise figure measurements without using the differential output signal result in a worse noise figure.
- 4. Using pins 7 and 8 as a symmetric RF input, the second-order IIP can be improved.
- 5. Due to test board parasitics, this bandwidth may be reduced and not be equal for I, IX, Q, QX. If symmetry and full bandwidth is required, the lowpass pins 3, 4 and 9, 10 should be isolated from the board. the bandwidth of the I/Q outputs can be increased further by using a resistor between pins 3, 4, 9 and 10. These resistors shunt the internal loads of RI \sim 5.4 k Ω The decrease in gain here has to be considered.
- 6. The internal current of the output emitter followers is 0.6 mA. This reduces the undistorted output voltage swing at a 50Ω load to approximately 30 mV. For low signal distortion the load impedance should be RI \geq 5 k Ω
- 7. Referred to the level of the output vector $\sqrt{I^2 + Q^2}$
- 8. The low-gain status is achieved with an open or high-ohmic pin 11. A recommended application circuit for switching between high and low gain status is shown in Figure 6-1.

Figure 6-1. Test Circuit



^{*} optional for single-ended tests (notice 3 dB bandwidth of AD620)

T1, T2 = transmission line $Z_O = 50\Omega$

If no GC function is required, connect Pin 11 to GND.

For high and low gain status GC $\acute{}$ is to be switched to GND respectively to V_S .

Figure 6-2. I and Q phase for $f_{RF} > f_{LO}$. For $f_{RF} < f_{LO}$ the phase is inverted.

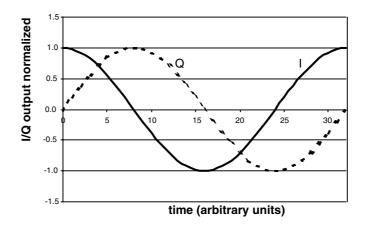






Figure 6-3. Typical VSWR Frequency Response of the LO Input

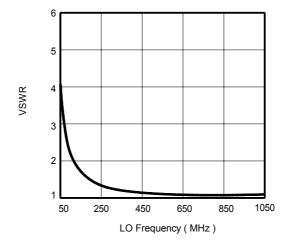


Figure 6-4. Noise Figure versus LO Frequency; o: Value at 950 MHz with RF Input Matching with T3

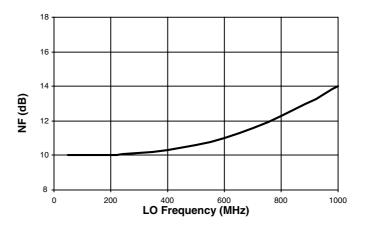


Figure 6-5. Typical Suitable LO Power Range versus Frequency

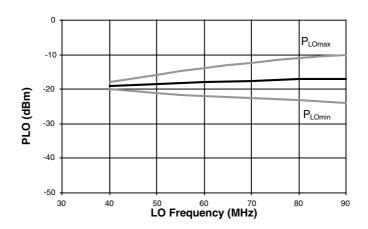


Figure 6-6. Gain versus LO Frequency; x: Value at 950 MHz with RF Input Matching with T3

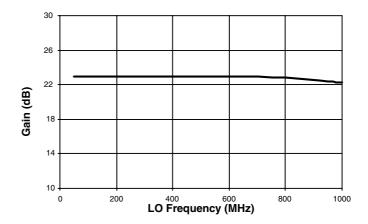


Figure 6-7. Typical Output Signal versus LO Frequency for $P_{RF} = -15$ dBm and PLO = -15 dBm

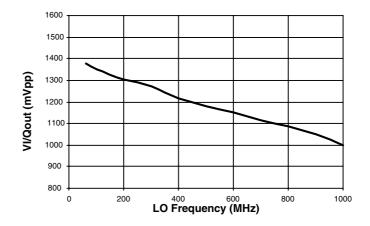


Figure 6-8. Typical Suitable LO Power Range versus Frequency

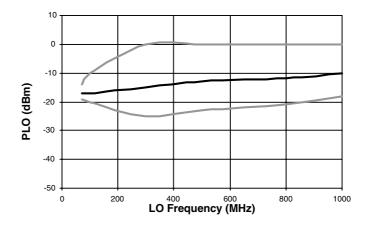






Figure 6-9. Typical Output Voltage (single ended) versus P_{RF} at $T_{amb} = 25^{\circ}C$ and PLO = -15 dBm

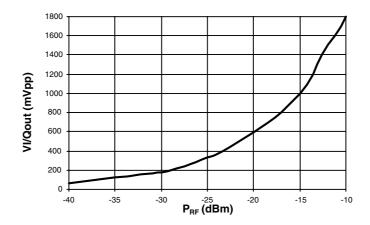
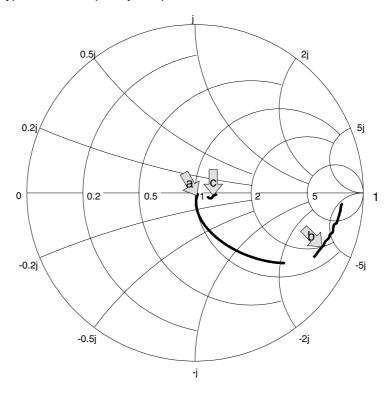


Figure 6-10. Typical S11 Frequency Response



a: LO input, LO frequency from 100 MHz to 1100 MHz, marker: 950 MHz b: RF input, RF frequency from 100 MHz to 1100 MHz, marker: 950 MHz c: I/Q Outputs, Baseband Frequency from 5 MHz to 55 MHz, marker: 25 MHz

Figure 6-11. Evaluation Board Layout

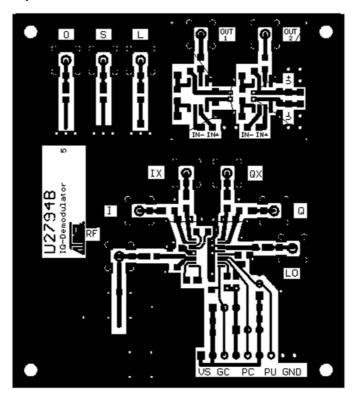
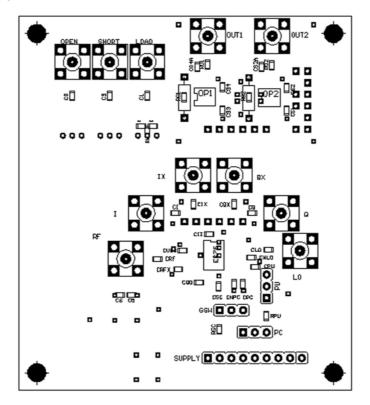


Figure 6-12. Evaluation Board







6.1 **External Components**

CUCC 100 nF CRFX 1 nF CLO 100 pF **CNLO** 1 nF CRF 100 pF CII, CQQ

optional external lowpass filters

Т3 transmission line for RF-input matching, to connect optionally

CI, CIX optional for AC-coupling at

CQ, CQX baseband outputs not connected

CPDN 100 pF

CGC 100 pF CPC 100 pF not connected **CNPC**

100 pF not connected GSW gain switch

6.2 **Calibration Part**

CO, CS, CL 100 pF RL 50Ω

Conversion to Single Ended Output 6.3

(see datasheet of AD620)

OP1, OP2 AD620

RG1, RG2 prog. gain, see datasheet, for 5.6 k Ω a gain of 1 at 50 Ω is

achieved together with RD1 and RD2.

RD1, RD2 450Ω CS1, CS2 100 nF CS3, CS4 100 nF

7. Description of the Evaluation Board

Board material: epoxy; $\varepsilon r = 4.8$, thickness = 0.5 mm, transmission lines: $Z_{\Omega} = 50\Omega$

The board offers the following functions:

- Test circuit for the U2794B:
 - The supply voltage and the control inputs GC, PC and PU are connected via a plug strip. The control input voltages can be generated via external potentiometers; then the inputs should be AC-grounded (time requirements in burst mode for power up have to be considered).
 - The outputs I, IX, Q, QX are DC coupled via an plug strip or can be AC-connected via SMB plugs for high frequency tests e.g. noise figure or s-parameter measurement. The Pins II, IIX, QQ, QQX allow user-definable filtering with 2 external capacitors CII, CQQ.
 - The offsets of both channels can be adjusted with two potentiometers or resistors.
 - The LO- and the RF-inputs are AC-coupled and connected via SMB plugs. If transmission line T3 is connected to the RF-input and AC-grounded at the other end, gain and noise performance can be improved (input matching to 50Ω).
 - The complementary RF-input is AC-coupled to GND (CRFX = 1 nF), the same appears to the complementary LO input (CNLO = 1 nF).
- A calibration part which allows to calibrate an s-parameter analyzer directly to the in- and output- signal ports of the U2794B.
- For single-ended measurements at the demodulator outputs, two OPs (e.g., AD620 or other) can be configured with programmable gain; together with an output-divider network RD = 450Ω to RL = 50Ω , direct measurements with 50Ω load impedances are possible at frequencies t < 100 kHz.

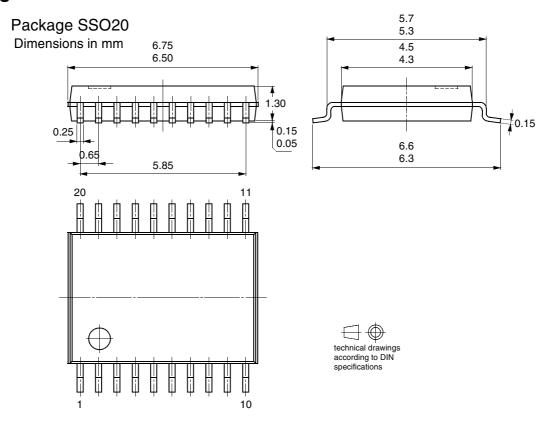




8. Ordering Information

Extended Type Number	Package	Remarks		
U2794B-NFSH	SSO20	Tube, MOQ 830 pcs, Pb-free		
U2794B-NFSG3H	SSO20	Taped and reeled, MOQ 4000 pcs, Pb-free		

9. Package Information





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