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## Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: [info@chipsmall.com](mailto:info@chipsmall.com) Web: [www.chipsmall.com](http://www.chipsmall.com)

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China





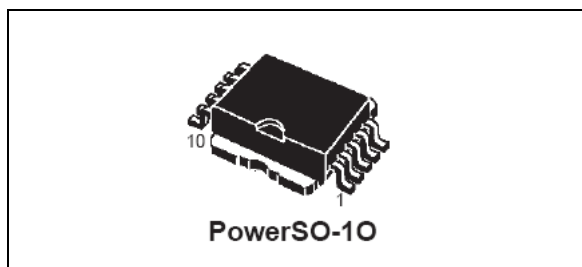
## VN380SP

### Smart solenoid driver solid state relay

#### Features

Type	$V_{load(cl)}$	$I_n$	$R_{on}$
VN380SP	60 V	5 A	0.11 $\Omega$

- Load current up to 7 A
- CMOS compatible
- Thermal shutdown
- Diagnostic output
- Integrated clamps
- Over current protection
- Open coil detection
- Overvoltage detection



#### Description

The VN380SP is monolithic device made using STMicroelectronics VIPower™ Technology, intended for driving inductive loads. The inputs are CMOS compatible. The diagnostic output provides an indication of open-load and demagnetization mode. Built-in thermal shutdown protects the chip from over temperature. In case of over current or over temperature or overvoltage the product will automatically operate in recirculation mode.

Table 1. Device summary

Package	Order codes			
	Tube	Tube (lead free)	Tape and reel	Tape and reel (lead free)
PowerSO-10	VN380SP	VN380SP-E	VN380SP13TR	VN380SPTR-E

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# 1 Block diagram and pin description

Figure 1. Block diagram

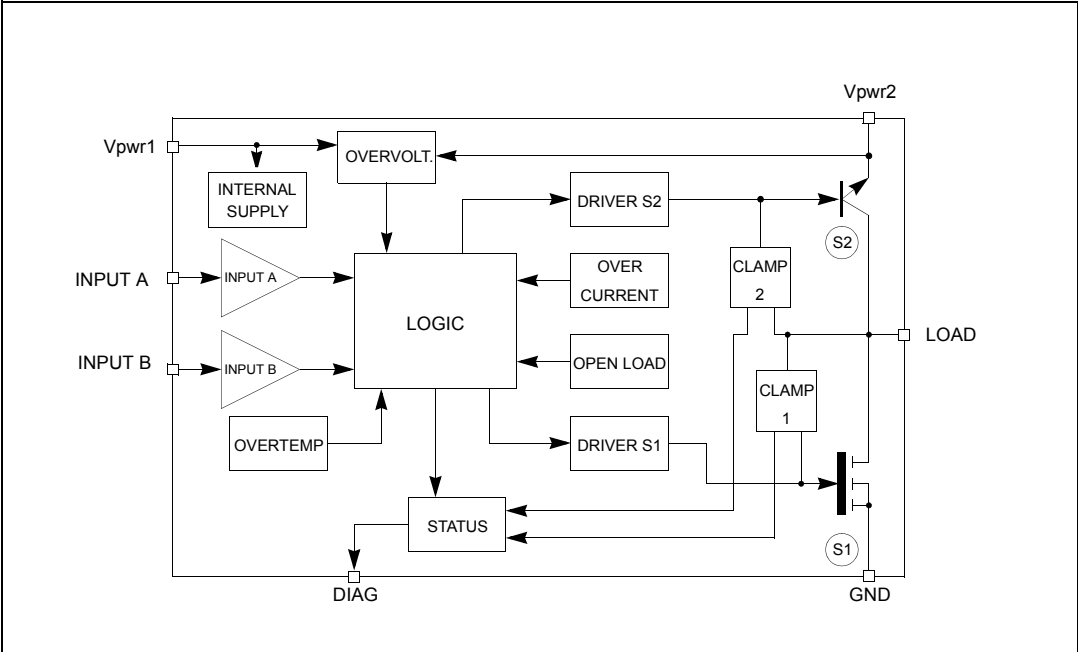
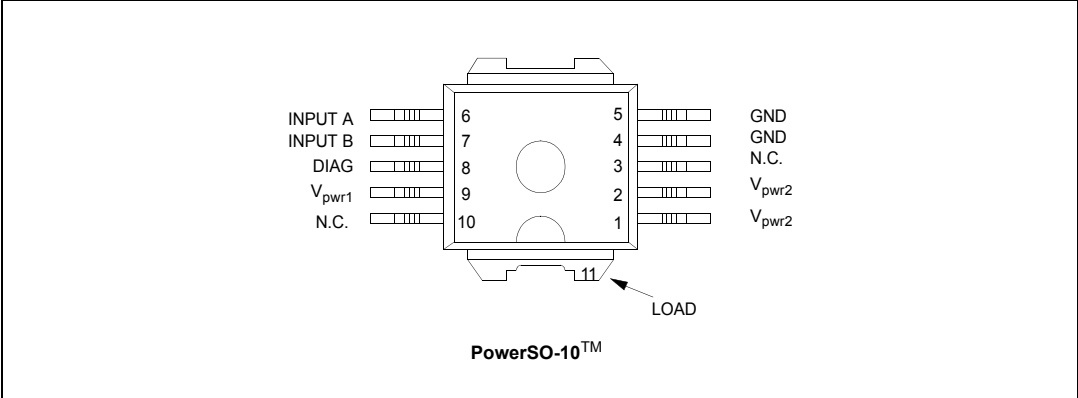
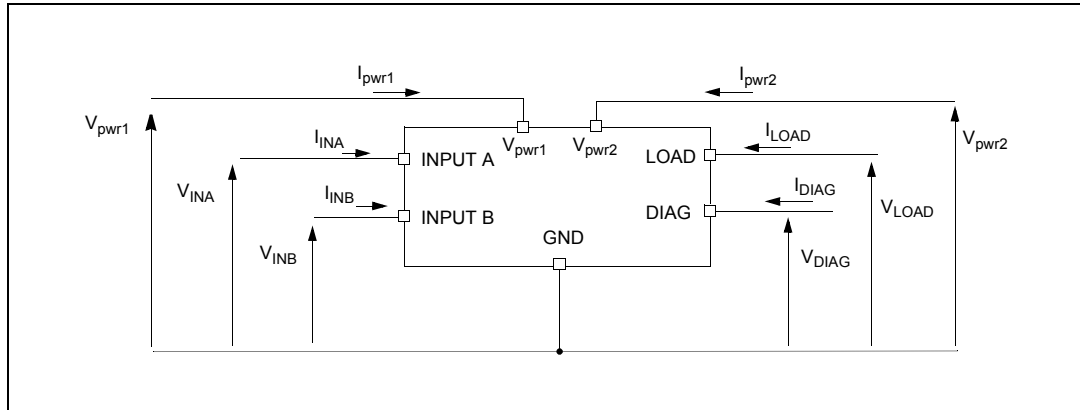


Figure 2. Configuration diagram (top view)



## 2 Electrical specifications

Figure 3. Current and voltage conventions



### 2.1 Absolute maximum ratings

Table 2. Absolute maximum ratings

Symbol	Parameter	Value	Unit
$V_{load}$	Maximum DC load voltage	Internally clamped	V
$I_{load}$	Maximum DC load current	Internally clamped	A
$I_{rload}$	Reverse load current, $T_{case} = 25\text{ }^{\circ}\text{C}$	-10	A
$E_c$	Maximum clamping energy, $T_{case} = 150\text{ }^{\circ}\text{C}$ , $f = 40\text{ Hz}$ , 1000 hours (f: input A frequency)	100	mJ
$E_c$	Maximum clamping energy, $T_{case} = -40\text{ }^{\circ}\text{C}$ , $f = 75\text{ Hz}$ , 5 minutes (f: input A frequency)	100	mJ
$I_{in}$	Inputs current	+/-10	mA
$I_{diag}$	Diagnostic output current	+/-10	mA
$V_{ESD}$	Electrostatic discharge ( $R = 1.5\text{ k}\Omega$ , $C = 100\text{ pF}$ , all pins)	2000	V
$V_{pwr1}$	Power voltage 1	60	V
$V_{pwr2}$	Power voltage 2	60	V
$R_{Vpwr}$	Reverse power voltage	-0.3	V
$T_j$	Junction operating temperature	-40 to 150 <sup>(1)</sup>	$^{\circ}\text{C}$
$T_{stg}$	Storage temperature	-55 to 150	$^{\circ}\text{C}$
$V_{in}$	Input voltages	8	V
$V_{diag}$	Diagnostic output voltage	8	V
$C_{load}$	Load capacity	1	$\mu\text{F}$

1. Higher temperature is allowed during a short time before thermal shutdown. Permanent operation above  $^{\circ}\text{C}$  150 is not allowed.



## 2.2 Thermal data

**Table 3. Thermal data**

Symbol	Parameter	PowerSO-10	Unit
$R_{thj-case}$	Thermal resistance junction-case max	1.67	°C/W
$R_{thj-amb}$	Thermal resistance junction-ambient max <sup>(1)</sup>	50	°C/W

1. When mounted using minimum recommended pad size on FR-4 board.

## 2.3 Electrical characteristics

10 V <  $V_{PWR1}$  < 18 V; -40 °C <  $T_J$  < 150 °C unless otherwise specified

**Table 4. Electrical characteristics**

Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
<b>Power</b>						
$V_{pwr1}$	Operating voltage		6	13	24	V
$R_{on1}$	On-state resistance (excitation path)	$I_{load} = I_n = 5\text{ A}$ ; $V_{inA} = V_{inB} = 5\text{ V}$			0.2	$\Omega$
$R_{on2}$	On-state resistance (recirculation path)	$V_{pwr1} = 13\text{ V}$ ; $I_{load} = I_n = 5\text{ A}$ $V_{inA} = 5\text{ V}$ ; $V_{inB} = \text{GND}$			0.4	$\Omega$
$V_{ce(sat)}$	Saturation voltage of bipolar S2	$I_{load} = I_n = 5\text{ A}$ $V_{pwr1} = V_{pwr2} = 13\text{ V}$ $I_{load} = 10\text{ A}$ ; $T_J > 125\text{ °C}$ $V_{pwr1} = V_{pwr2} = 13\text{ V}$			2	V
					2	V
$I_{sq}$	Supply quiescent current	$V_{pwr1} = 13\text{ V}$ ; $V_{inA} = V_{inB} = 5\text{ V}$			25	mA
$I_{lk}$	Output leakage current	$V_{pwr1} = 18\text{ V}$ ; $V_{inA} = V_{inB} = \text{GND}$			5	mA
$I_{off}$	Off-state supply current	$V_{inA} = V_{inB} = \text{GND}$ $V_{pwr1} = \text{not connected}$ 10 V < $V_{pwr2}$ < 24 V $T_J = 25\text{ °C}$			50	$\mu\text{A}$
<b>Switching (excitation path)</b>						
$t_{d(on)}$	Turn-on delay time	$R_{load} = 2.5\text{ }\Omega$ ; $V_{inA} = 5\text{ V}$ (see <a href="#">Figure 4</a> )			50	$\mu\text{s}$
$t_r$	Rise time of output current	$R_{load} = 2.5\text{ }\Omega$ ; $V_{inA} = 5\text{ V}$ (see <a href="#">Figure 4</a> )	1		20	$\mu\text{s}$
$t_{d(off)}$	Turn-off delay time	$R_{load} = 2.5\text{ }\Omega$ ; $V_{inA} = 5\text{ V}$ (see <a href="#">Figure 4</a> )			50	$\mu\text{s}$
$t_f$	Fall time of output current	$R_{load} = 2.5\text{ }\Omega$ ; $V_{inA} = 5\text{ V}$ (see <a href="#">Figure 4</a> )	1		20	$\mu\text{s}$
<b>Logic input</b>						
$V_{il}$	Input low level voltage				1.5	V

**Table 4. Electrical characteristics (continued)**

Symbol	Parameter	Test conditions	Min	Typ	Max	Unit
$V_{ih}$	Input high level voltage		3.5			V
$V_{i(hyst)}$	Input hysteresis voltage		0.5	0.8	2	V
$V_{i(CL)}$	Input clamp voltage	$I_{in} = 10 \text{ mA}$	8	9.5	11	V
$I_{in}$	Input current	$V_{inA} = V_{inB} = 2 \text{ V}$ $V_{inA} = V_{inB} = 5 \text{ V}$	20		250	$\mu\text{A}$ $\mu\text{A}$
<b>Protections and diagnostics</b>						
$T_{tsd}$	Thermal shutdown temperature		160	180	200	$^{\circ}\text{C}$
$I_{lim}$	Current cut off level		15		30	A
$V_{ov}$	Overvoltage threshold	$V_{inA} = V_{inB} = 5 \text{ V}$	27			V
$V_{diag}$	Status output voltage	Diagnostic output active (low) $I_{diag} = 2 \text{ mA}$			0.5	V
$V_{diag(CL)}$	Status output clamp voltage	$I_{diag} = 10 \text{ mA}$	8	9.5	11	V
$T_d$	Status propagation delay	Demagnetization mode (fast turn-off) $V_{diag} = 1 \text{ V}$ (see <a href="#">Figure 6</a> )			70	$\mu\text{s}$
$V_{cl1}$	Switch S1 detection clamp	$I_{load} = I_n = 5 \text{ A}$	60	70	80	V
$V_{cl2}$	Output inductive clamp voltage	$I_{load} = I_n = 5 \text{ A}$	24	28.5	33	V
$V_{fb}$	Flyback diagnostic threshold	Demagnetization mode (fast turn-off) $V_{cl} = V_{cl1} \text{ or } V_{cl2}$	$V_{cl}-5$		$V_{cl}$	V
$I_{ol}$	Open-load current level		5		700	mA

**Table 5. Truth table**

Conditions	In A	In B	S1	S2
Standby modes	L	L	Off	Off
	L	H	Off	Off
Excitation mode	H	H	On	Off
Recirculation mode	H	L	Off	On
Demagnetization mode (fast turn-off)				
$V_{pwr2} + V_{cl2} < V_{cl1}$	L	L	Off	On
$V_{pwr2} + V_{cl2} > V_{cl1}$	L	L	On	On
Thermal shutdown	H	H	Off	On
Current cut off	H	H	Off	On
Open-load	See open-load waveforms on <a href="#">Figure 5</a>			
Overvoltage	H	H	Off	On

### 3 Functional description

#### 3.1 Current cut off

When the load current rise above the current cut off level, S1 is automatically switched off and the device operates in recirculation mode (S2 active). S1 is latched off until A goes low and high again.

This default is not displayed by diagnostic flag.

#### 3.2 Open-load

If the load current is below the open-load current level, the flag of the open-load block is activated but this default is displayed by the diagnostic output on the falling edge of input B and the diagnostic output is latched at low level until input A goes low and high again. In case an open-load is detected during an active phase of input B, but disappears before a falling edge of input B, this default is not displayed by the diagnostic flag (see open-load waveforms on [Figure 5](#)).

#### 3.3 Thermal shutdown

The device is internally protected against over temperatures by the thermal circuit protection. When the device junction temperature exceeds the protection limit, S1 is automatically switched off. Therefore the device operates in recirculation mode (S2 active). S1 remain latched off until  $V_{pwr1}$  goes low and high again. This default is not displayed by the diagnostic flag.

#### 3.4 Overvoltage

During the on-state of S1 switch, if  $V_{pwr1}$  or  $V_{pwr2}$  is rising above the threshold detection S1 is automatically switched off, therefore the device operates in recirculation mode.

**Figure 4. Switching parameter test conditions**

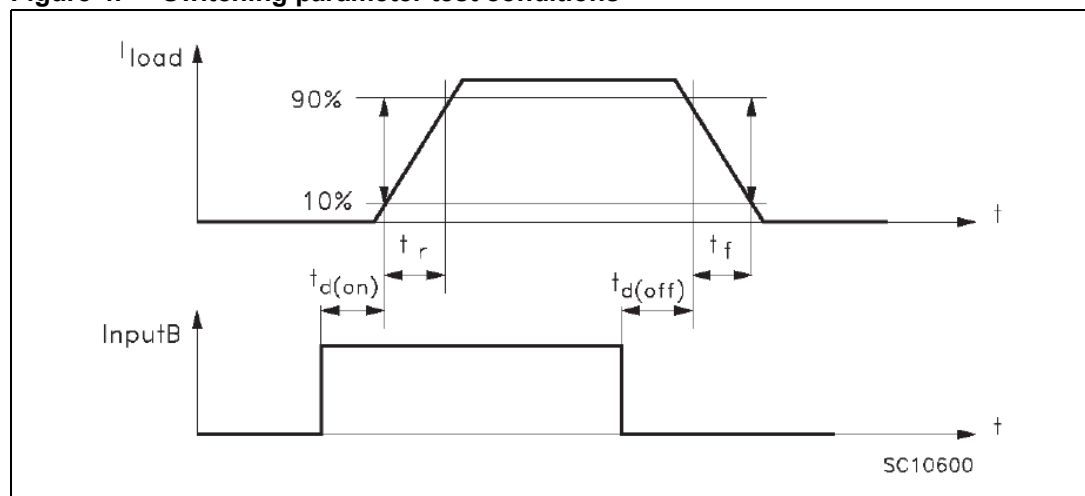




Figure 5. Switching waveforms

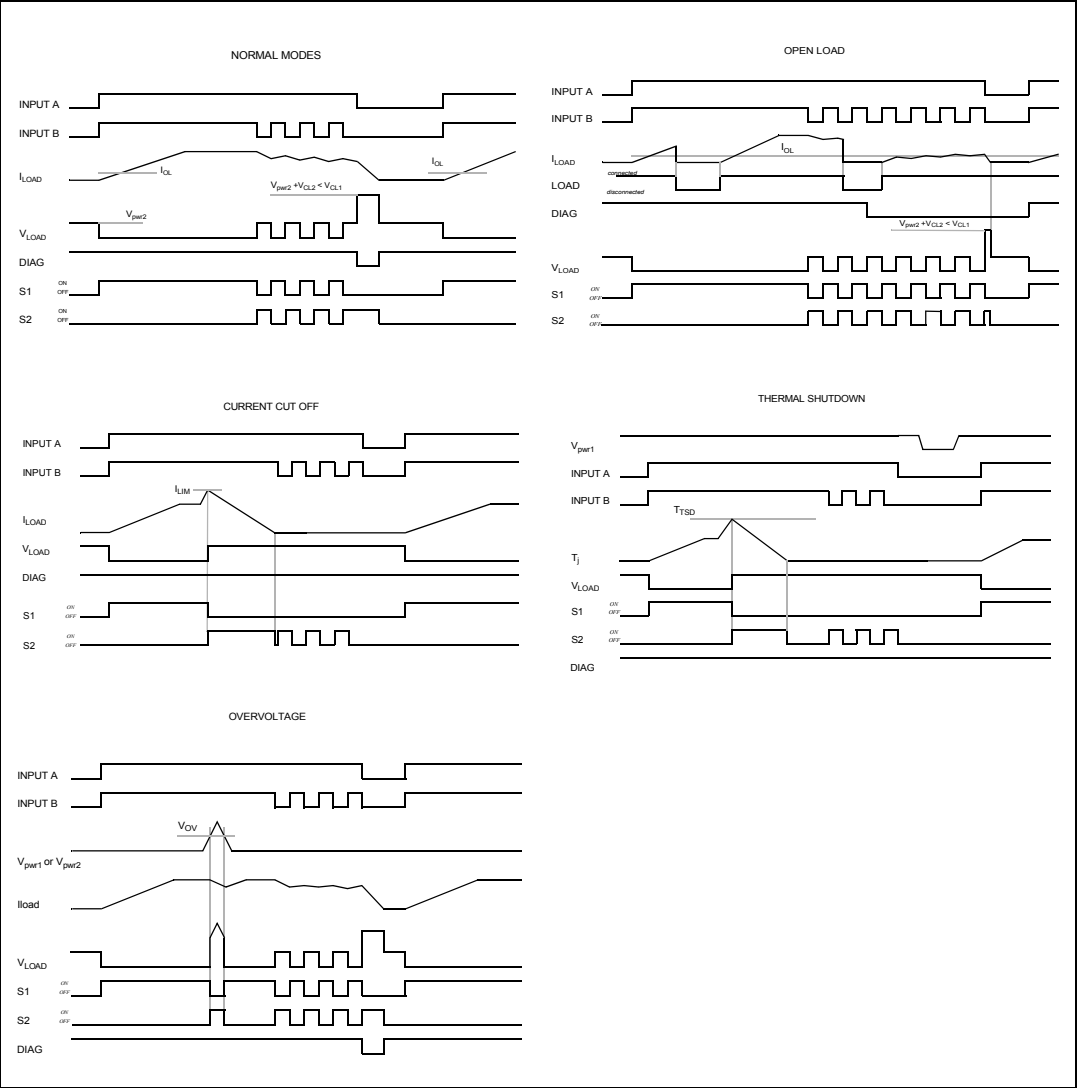
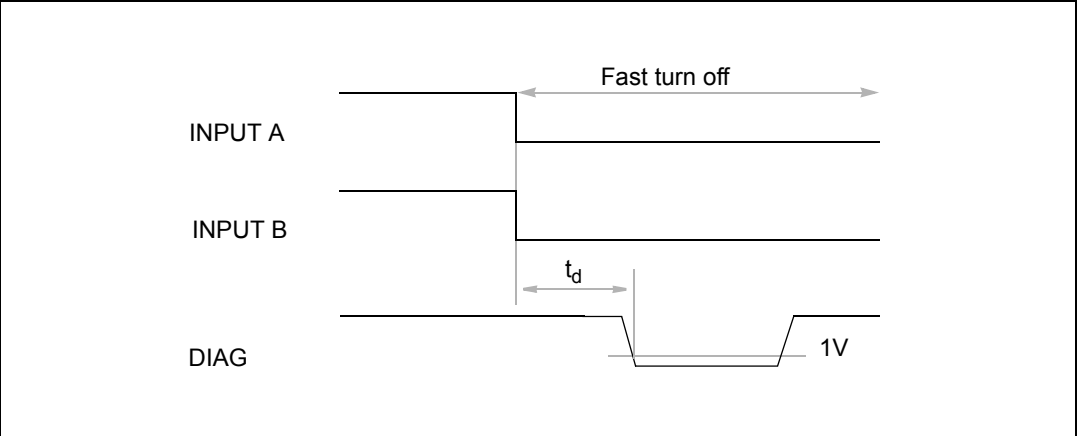


Figure 6. Demagnetization mode



## 4 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: [www.st.com](http://www.st.com).

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### 4.1 PowerSO-10 mechanical data

**Table 6. PowerSO-10 mechanical data**

Dim.	mm			inch		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	3.35		3.65	0.132		0.144
A1	0.00		0.10	0.000		0.004
B	0.40		0.60	0.016		0.024
c	0.35		0.55	0.013		0.022
D	9.40		9.60	0.370		0.378
D1	7.40		7.60	0.291		0.300
E	9.30		9.50	0.366		0.374
E1	7.20		7.40	0.283		0.291
E2	7.20		7.60	0.283		0.300
E3	6.10		6.35	0.240		0.250
E4	5.90		6.10	0.232		0.240
e		1.27			0.050	
F	1.25		1.35	0.049		0.053
H	13.80		14.40	0.543		0.567
h		0.50			0.002	
L	1.20		1.80	0.047		0.071
q		1.70			0.067	
$\alpha$	0°		8°			

Technical drawing of a 10-pin D-sub connector showing front, side, and detail views with dimensions and tolerances.

**Front View (Top Left):** Shows the connector body with dimensions  $H$ ,  $E$ ,  $E2$ ,  $10$ ,  $6$ ,  $1$ ,  $5$ ,  $e$ ,  $B$ , and a positional tolerance of  $\pm 0.25$ .

**Side View (Top Middle):** Shows the connector body with dimensions  $E3$ ,  $E1$ ,  $E4$ , and a surface texture symbol  $0.10$ . It includes a callout for **DETAIL "A"** and a **SEATING PLANE**.

**Top View (Top Right):** Shows the connector body with dimensions  $E4$  and  $10$ .

**Bottom View (Bottom Left):** Shows the connector body with dimensions  $D$ ,  $D1$ ,  $h$ ,  $A$ ,  $F$ ,  $A1$ , and  $10$ .

**Detail "A" (Bottom Middle):** Shows the connector body with dimensions  $A1$ ,  $L$ , and an angle  $\alpha$ . It includes a callout for **DETAIL "A"** and a **SEATING PLANE**.

## 5 Revision history

**Table 7. Document revision history**

Date	Revision	Changes
10-Jun-2009	1	Initial release.
20-Sep-2013	2	Updated Disclaimer.

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