

Chipsmall Limited consists of a professional team with an average of over 10 year of expertise in the distribution of electronic components. Based in Hongkong, we have already established firm and mutual-benefit business relationships with customers from, Europe, America and south Asia, supplying obsolete and hard-to-find components to meet their specific needs.

With the principle of "Quality Parts, Customers Priority, Honest Operation, and Considerate Service", our business mainly focus on the distribution of electronic components. Line cards we deal with include Microchip, ALPS, ROHM, Xilinx, Pulse, ON, Everlight and Freescale. Main products comprise IC, Modules, Potentiometer, IC Socket, Relay, Connector. Our parts cover such applications as commercial, industrial, and automotives areas.

We are looking forward to setting up business relationship with you and hope to provide you with the best service and solution. Let us make a better world for our industry!



Contact us

Tel: +86-755-8981 8866 Fax: +86-755-8427 6832

Email & Skype: info@chipsmall.com Web: www.chipsmall.com

Address: A1208, Overseas Decoration Building, #122 Zhenhua RD., Futian, Shenzhen, China









16M × 8 BANKS × 16 BIT DDR3L SDRAM

Table of Contents-

1.		GENERAL	DESCRIPTION	5
2.		FEATURE	S	5
3.		ORDER IN	IFORMATION	6
1.		KFY PARA	AMETERS	
5.			IFIGURATION	
3. 3.			CRIPTION	
			AGRAM	
7.				
3.	0.4		NAL DESCRIPTION	
	8.1 8.2		ctionalityd Initialization Procedure	
	0.2	8.2.1	Power-up Initialization Sequence	
		8.2.2	Reset Initialization with Stable Power	
	8.3	•	ing the Mode Registers	
	0.5	8.3.1	Mode Register MR0	
		8.3.1.1	Burst Length, Type and Order	
		8.3.1.2		
		8.3.1.3	Test Mode	
		8.3.1.4	DLL Reset	
		8.3.1.5	Write Recovery	
		8.3.1.6	Precharge PD DLL	
		8.3.2	Mode Register MR1	
		8.3.2.1	DLL Enable/Disable	
		8.3.2.2	Output Driver Impedance Control	
		8.3.2.3	ODT RTT Values	
		8.3.2.4	Additive Latency (AL)	
		8.3.2.5	Write leveling	
		8.3.2.6	Output Disable	
		8.3.3	Mode Register MR2	
		8.3.3.1	Partial Array Self Refresh (PASR)	23
		8.3.3.2	CAS Write Latency (CWL)	23
		8.3.3.3	Auto Self Refresh (ASR) and Self Refresh Temperature (SRT)	23
		8.3.3.4	Dynamic ODT (Rtt_WR)	23
		8.3.4	Mode Register MR3	24
		8.3.4.1	Multi Purpose Register (MPR)	
	8.4	No OPerat	ion (NOP) Command	25
	8.5		Command	
	8.6		ode	
	8.7		switching procedure	
		8.7.1	DLL "on" to DLL "off" Procedure	
		8.7.2	DLL "off" to DLL "on" Procedure	
	8.8	•	frequency change	
		8.8.1	Frequency change during Self-Refresh	
	0.0	8.8.2	Frequency change during Precharge Power-down	
	8.9	Write Leve	ling	
		0.9.1	DRAW Seludo for write leveling & DRAW Termination function in that mode	

Publication Release Date: Nov. 22, 2017

THE Winbond SEELS

	8.9.2	Write Leveling Procedure	31
	8.9.3	Write Leveling Mode Exit	33
8.10	Multi Purpo	se Register	34
	8.10.1	MPR Functional Description	35
	8.10.2	MPR Register Address Definition	36
	8.10.3	Relevant Timing Parameters	36
	8.10.4	Protocol Example	36
8.11	ACTIVE Co	mmand	42
8.12	PRECHAR	GE Command	42
8.13	READ Ope	ration	43
	8.13.1	READ Burst Operation	43
	8.13.2	READ Timing Definitions	44
	8.13.2.1	READ Timing; Clock to Data Strobe relationship	45
	8.13.2.2	READ Timing; Data Strobe to Data relationship	46
	8.13.2.3	tLZ(DQS), tLZ(DQ), tHZ(DQS), tHZ(DQ) Calculation	47
	8.13.2.4	tRPRE Calculation	48
	8.13.2.5	tRPST Calculation	48
	8.13.2.6		
8.14		eration	
	8.14.1	DDR3L Burst Operation	
	8.14.2	WRITE Timing Violations	
	8.14.2.1	•	
	8.14.2.2		
	8.14.2.3	·	
	8.14.2.4		
	8.14.3	Write Data Mask	
	8.14.4	tWPRE Calculation	
	8.14.5	tWPST Calculation	
8.15		mmand	
8.16		h Operation	
8.17		n Modes	
0.17	8.17.1	Power-Down Entry and Exit	
	8.17.2	Power-Down clarifications - Case 1	
	8.17.3	Power-Down clarifications - Case 2	
	8.17.4	Power-Down clarifications - Case 3	
8.18		tion Commands	
0.10	8.18.1	ZQ Calibration Description	
	8.18.2	•	
		ZQ Calibration Timing	
0.10	8.18.3	ZQ External Resistor Value, Tolerance, and Capacitive loadingmination (ODT)	
8.19	8.19.1	ODT Mode Register and ODT Truth Table	
	8.19.2	•	
		Synchronous ODT Mode	
	8.19.2.1		
	8.19.2.2	ů	
	8.19.2.3	3	
	8.19.3	Dynamic ODT	
	8.19.3.1	P	
	8.19.3.2		
	8.19.4	Asynchronous ODT Mode	88

		8.1	9.4.1	Synchronous to Asynchronous ODT Mode Transitions	89
		8.1	9.4.2	Synchronous to Asynchronous ODT Mode Transition during Power-Down E	ntry89
		8.1	9.4.3	Asynchronous to Synchronous ODT Mode Transition during Power-Down E	xit92
			9.4.4 v periods	Asynchronous to Synchronous ODT Mode during short CKE high and should be sho	ort CKE
9.		OPEF	RATION M	ODE	94
	9.1	Comn	nand Truth	Table	94
	9.2	CKE	Truth Table	9	96
	9.3	Simpl	ified State	Diagram	97
10.		ELEC	TRICAL C	HARACTERISTICS	98
	10.1	Absol	ute Maxim	um Ratings	98
	10.2	•	• .	perature Condition	
	10.3	DC &	•	ting Conditions	
		10.3.1		ommended DC Operating Conditions	
	10.4	-		t Leakage Currents	
	10.5			onditions	
	10.6		•	ut Measurement Levels	
		10.6.1		and AC Input Levels for Single-Ended Command and Address Signals	
		10.6.2		and AC Input Levels for Single-Ended Data Signals	
		10.6.3		erential swing requirements for clock (CK - CK#) and strobe (DQS - DQS#)	
		10.6.4	_	gle-ended requirements for differential signals	
		10.6.5		erential Input Cross Point Voltage	
		10.6.6 10.6.7		v Rate Definitions for Single-Ended Input Signalsv Rate Definitions for Differential Input Signalsv	
	10.7			put Measurement Levels	
	10.7	10.7.1		put Slew Rate Definition and Requirements	
		_	.7.1.1	Single Ended Output Slew Rate	
		_	.7.1.2	Differential Output Slew Rate	
	10.8	-		Driver DC Electrical Characteristics	
		10.8.1	•	put Driver Temperature and Voltage sensitivity	
	10.9	On-Di		tion (ODT) Levels and Characteristics	
		10.9.1		Γ Levels and I-V Characteristics	
		10.9.2	OD	Γ DC Electrical Characteristics	113
		10.9.3	OD	Г Temperature and Voltage sensitivity	113
		10.9.4	Des	ign guide lines for RTT _{PU} and RTT _{PD}	114
	10.10)	ODT Timii	ng Definitions	115
		10.10.1	Tes	t Load for ODT Timings	115
		10.10.2	OD	Γ Timing Definitions	115
	10.11			out Capacitance	
	10.12	2		t and Undershoot Specifications	
		10.12.1		Overshoot /Undershoot Specification for Address and Control Pins:	
		10.12.2		Overshoot /Undershoot Specification for Clock, Data, Strobe and Mask Pins:	
	10.13			DDQ Specification Parameters and Test Conditions	
		10.13.1		and IDDQ Measurement Conditions	
		10.13.2		Current Specifications	
	10.14		•	ecification	
	10.15			ns	
		10.15.1 10.15.2		R3L-1600 Speed Bin and Operating Conditions	
		10.15.2		R3L-1866 Speed Birr and Operating Conditions	

winbond 10.15.4 10.15.5 10.16 AC Characteristics 138 10.16.1 AC Timing and Operating Condition for -09/09I/09J/-11/11I/11J speed grades138 AC Timing and Operating Condition for -12/12I/12J/-15/15I/15J speed grades142 10.16.2 10.16.3 10.16.4 10.16.5 11. 11.1 11.2 11.3 11.4 12. 13.



1. GENERAL DESCRIPTION

The W632GU6MB is a 2G bits DDR3L SDRAM, organized as 16,777,216 words \times 8 banks \times 16 bits. This device achieves high speed transfer rates up to 2133 MT/s (DDR3L-2133) for various applications. This device is sorted into the following speed grades: -09, -11, -12, -15, 09I, 11I, 12I, 15I, 09J, 11J, 12J and 15J.

The -09 ,09I and 09J speed grades are compliant to the DDR3-2133L (14-14-14) specification (The 09I industrial grade which is guaranteed to support -40°C \leq TCASE \leq 95°C, the 09J industrial plus grade which is guaranteed to support -40°C \leq TCASE \leq 105°C).

The -11 ,11I and 11J speed grades are compliant to the DDR3L-1866 (13-13-13) specification (The 11I industrial grade which is guaranteed to support -40°C \leq TCASE \leq 95°C, the 11J industrial plus grade which is guaranteed to support -40°C \leq TCASE \leq 105°C).

The -12, 12I and 12J speed grades are compliant to the DDR3L-1600 (11-11-11) specification (The 12I industrial grade which is guaranteed to support -40°C \leq TCASE \leq 95°C, the 12J industrial plus grade which is guaranteed to support -40°C \leq TCASE \leq 105°C).

The -15, 15I and 15J speed grades are compliant to the DDR3L-1333 (9-9-9) specification (The 15I industrial grade which is guaranteed to support -40°C \leq TCASE \leq 95°C, the 15J industrial plus grade which is guaranteed to support -40°C \leq TCASE \leq 105°C).

The W632GU6MB is designed to comply with the following key DDR3L SDRAM features such as posted CAS#, programmable CAS# Write Latency (CWL), ZQ calibration, on die termination and asynchronous reset. All of the control and address inputs are synchronized with a pair of externally supplied differential clocks. Inputs are latched at the cross point of differential clocks (CK rising and CK# falling). All I/Os are synchronized with a differential DQS-DQS# pair in a source synchronous fashion.

2. FEATURES

- Power Supply: 1.35V (typ.), VDD, VDDQ = 1.283V to 1.45V
- Backward compatible to VDD, VDDQ = 1.5V ± 0.075V
- Double Data Rate architecture: two data transfers per clock cycle
- Eight internal banks for concurrent operation
- 8 bit prefetch architecture
- CAS Latency: 5, 6, 7, 8, 9, 10, 11, 13 and 14
- Burst length 8 (BL8) and burst chop 4 (BC4) modes: fixed via mode register (MRS) or selectable On-The-Fly (OTF)
- Programmable read burst ordering: interleaved or nibble sequential
- Bi-directional, differential data strobes (DQS and DQS#) are transmitted / received with data
- Edge-aligned with read data and center-aligned with write data
- DLL aligns DQ and DQS transitions with clock
- Differential clock inputs (CK and CK#)
- Commands entered on each positive CK edge, data and data mask are referenced to both edges of a differential data strobe pair (double data rate)
- Posted CAS with programmable additive latency (AL = 0, CL 1 and CL 2) for improved command, address and data bus efficiency
- Read Latency = Additive Latency plus CAS Latency (RL = AL + CL)

Publication Release Date: Nov. 22, 2017



- Auto-precharge operation for read and write bursts
- Refresh, Self-Refresh, Auto Self-refresh (ASR) and Partial array self refresh (PASR)
- Precharged Power Down and Active Power Down
- Data masks (DM) for write data
- Programmable CAS Write Latency (CWL) per operating frequency
- Write Latency WL = AL + CWL
- Multi purpose register (MPR) for readout a predefined system timing calibration bit sequence
- System level timing calibration support via write leveling and MPR read pattern
- ZQ Calibration for output driver and ODT using external reference resistor to ground
- Asynchronous RESET# pin for Power-up initialization sequence and reset function
- Programmable on-die termination (ODT) for data, data mask and differential strobe pairs
- Dynamic ODT mode for improved signal integrity and preselectable termination impedances during writes
- 2K Byte page size
- Packaged in VFBGA 96 Ball (7.5 x13 mm² with thickness of 1.0 mm), using lead free materials with RoHS compliant

3. ORDER INFORMATION

PART NUMBER	SPEED GRADE	OPERATING TEMPERATURE
W632GU6MB-09	DDR3L-2133 (14-14-14)	0°C ≤ Tcase ≤ 95°C
W632GU6MB09I	DDR3L-2133 (14-14-14)	-40°C ≤ TCASE ≤ 95°C
W632GU6MB09J	DDR3L-2133 (14-14-14)	-40°C ≤ TCASE ≤ 105°C
W632GU6MB-11	DDR3L-1866 (13-13-13)	0°C ≤ Tcase ≤ 95°C
W632GU6MB11I	DDR3L-1866 (13-13-13)	-40°C ≤ TCASE ≤ 95°C
W632GU6MB11J	DDR3L-1866 (13-13-13)	-40°C ≤ TCASE ≤ 105°C
W632GU6MB-12	DDR3L-1600 (11-11-11)	0°C ≤ Tcase ≤ 95°C
W632GU6MB12I	DDR3L-1600 (11-11-11)	-40°C ≤ TCASE ≤ 95°C
W632GU6MB12J	DDR3L-1600 (11-11-11)	-40°C ≤ TCASE ≤ 105°C
W632GU6MB-15	DDR3L-1333 (9-9-9)	0°C ≤ Tcase ≤ 95°C
W632GU6MB15I	DDR3L-1333 (9-9-9)	-40°C ≤ TCASE ≤ 95°C
W632GU6MB15J	DDR3L-1333 (9-9-9)	-40°C ≤ TCASE ≤ 105°C

Publication Release Date: Nov. 22, 2017



4. KEY PARAMETERS

Part Number Extension	Speed Bin					DDR3L-2133 DD		DDR3L-1866		DDR3L-1600		DDR3L-1333	
Part Number Extension Sym. Min. Max. Min. Ma		CL-nRCE	14-14-14		13-13-13		11-11-11		9-9-9		Unit		
Maximum oberating frequency using maximum allowed settings for Sup_CL and Sup_CMI for Max in all products of Sup_CL and Sup_CMI for Max in all products of Sup_CL and Sup_CMI for Max in all products of Sup_CL and Sup_CMI for Max in all products of Sup_CMI fo	Par	t Number	-09/09	-09/09I/09J -11/11I/11J		-12/12I/12J		-15/15I/15J		Offic			
maximum allowed Settings: Uriting and Sup_CWL. fckmax 1066 933 800 667 MHz Internal read command to first data 1AA 13.09 20 13.91 20 13.75 20 13.55 20 ns ACT to internal read or write delay time tree 13.09 13.91 13.75 13.55 ns PRE command period tree 46.09 47.91 43.75 413.55 ns ACT to ACT or REF command period trax 46.09 47.91 48.01 48.01 48.01 48.01 48.01 48.01 48.01 48.01 48.01 13.35 ns ACT to ACT or REF command period trax trax 14.80 3.0 3.3 3.0 3.3	Р	arameter		Sym.	Min.	Max.	Min.	Max.	Min.	Max.	Min.	Max.	
ACT to intermal read orbinand to first data TAA 13.99 20 13.91 20 (13.125)*8 20 (1	maximum allov	ved settings		fCKMAX	ı	1066	ı	933	-	800	_	667	MHz
ACT to internal read or write delay time 18.09 18.09 18.91 18.91 18.75 18.75 18.55	Internal read c	ommand to	first data	taa	13.09	20	13.91	20		20		20	nS
ACT to ACT or REF command period TRC 46.09 - 47.91 - (13.125)* - (13.125)* - 49.5 -		al read or	write delay	tRCD	13.09	-	13.91	-		-		-	nS
ACT to ACT \(\to ACT \) \(\to ACT \) to RE \(\to MA) \(\to ACT \) to PRE \(\to MA) \(\to MA) \(\to MA) \) to PRE \(\to MA) \(\to MA) \(\to MA) \(\to MA) \) to PRE \(\to MA) \(\to MA) \(\to MA) \(\to MA) \) to PRE \(\to MA) \(\to MA) \(\to MA) \\(\to MA)	PRE command	period		trp	13.09	-	13.91	-		-	13.5 (13.125)* ⁵	-	nS
CL = 5 CWL = 5 tCK(AVG) 3.0 3.3 3.0 3.3 3.0 3.3 3.0 3.3 3.0 3.3 3.0 3.3 3.0 3.3 3.0 3.3 1.5 CL = 6 CWL = 5 tCK(AVG) 2.5 3.3 2.5 3.3 2.5 3.3 2.5 3.3 2.5 3.3 nS CL = 7 CWL = 6 tCK(AVG) 1.875 < 2.5	ACT to ACT or	REF comm	and period	trc	46.09	_	47.91	-	48.75	-	49.5	_	nS
CL = 6 CWL = 5 tck(AVG) 2.5 3.3 2.5 3.3 2.5 3.3 2.5 3.3 2.5 3.3 ns CL = 7 CWL = 6 tck(AVG) 1.875 < 2.5	ACT to PRE co	ommand per	iod	tras	33	9 * tREFI	34	9 * tREFI	35	9 * tREFI		9 * tREFI	nS
CL = 7	CL =	5	CWL = 5	tck(avg)	3.0	3.3	3.0	3.3	3.0	3.3	3.0	3.3	nS
CL = 8	CL =	6	CWL = 5	tck(avg)	2.5	3.3	2.5	3.3	2.5	3.3	2.5	3.3	nS
CL = 9 CWL = 7 tok(AVG) 1.5 < 1.875 Resured 1.5 < 1.875 1.5 < 1.875 ns CL = 10 CWL = 7 tok(AVG) 1.5 < 1.875	CL =	7	CWL = 6	tck(avg)	1.875	< 2.5	Rese	erved	1.875	< 2.5	1.875	< 2.5	nS
CL = 10	CL =	8	CWL = 6	tck(avg)	1.875	< 2.5	1.875	< 2.5	1.875	< 2.5	1.875	< 2.5	nS
CL = 11	CL =	9	CWL = 7	tck(avg)	1.5	< 1.875	Rese	erved	1.5	< 1.875	1.5	< 1.875	nS
CL = 13 CWL = 9 tCK(AVG) 1.07 < 1.25 Reserved Reserved nS CL = 14 CWL = 10 tCK(AVG) 0.938 < 1.07	CL = 1	0	CWL = 7	tck(avg)	1.5	< 1.875	1.5	< 1.875	1.5	< 1.875	1.5	< 1.875	nS
CL = 14 CWL = 10 tCK(AVG) 0.938 < 1.07 Reseved Reseved Reseved ns ms Supported CW Settings Sup_CWL 5, 6, 7, 8, 9, 10, 13, 14, 13, 14 5, 6, 7, 9 5, 6, 7, 8, 9, 10, 11 5, 6, 7, 8, 9, 10 nCK Average periodic refresh Interval -40°C ≤ TCASE ≤ 85°C 85°C 85°C 25°C 85°C 25°C 25°C 25°C 25°C 25°C 25°C 25°C 2	CL = 1	1	CWL = 8	tck(avg)	1.25	< 1.5	Rese	erved	1.25	< 1.5	Rese	erved	nS
Supported CL Settings Sup_CL 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 11, 13, 14 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 13 5, 6, 7, 8, 9, 10, 15, 12 5, 6, 7, 8, 9, 10, 15, 12 5, 6, 7, 8, 9, 10, 16 7, 8*2, 3, 10 CK Average Prioriodic Pr	CL = 1	3	CWL = 9	tck(avg)	1.07	< 1.25	1.07	< 1.25	Rese	erved	Rese	erved	nS
Supported CV Settings Sup_CV 11, 13, 14 5, 6, 7, 9 5, 6, 7, 8 5, 6, 7 nCK	CL = 1	4	CWL = 10	tck(avg)	0.938	< 1.07	Rese	erved	Rese	erved	Rese	erved	nS
Average periodic periodic refresh Interval -40°C ≤ TCASE ≤ 85°C / 0°C ≤ TCASE ≤ 85°C / 85°C < TCASE ≤ 95°C / 95°C < TCASE ≤ 105°C	Supported CL	Settings		Sup_CL			5, 6, 8,	10, 13			5, 6, (7)	8, 9, 10	nCK
O°C ≤ TCASE ≤ 85°C Teresh EEFI	Supported CW	L Settings		Sup_CWL	5, 6, 7,	8, 9, 10	5, 6,	7, 9	5, 6,	,	5, (6, 7	nCK
refresh Interval 85°C < TCASE ≤ 95°C TREFI - 3.9*4<													
Interval 95°C < TCASE ≤ 105°C - 3.9*4 - 3.9*4 - 3.9*4 - 3.9*4 - 3.9*4 μS				trefi								-	
Operating One Bank Active-Precharge Current Operating One Bank Active-Read-Precharge Current Operating Burst Read Current IDD1 - 175 - 160 - 145 - 130 mA Operating Burst Read Current Operating Burst Write Current IDD4R - 230 - 210 - 190 - 165 mA Operating Burst Write Current IDD5B - 195 - 190 - 180 - 175 mA Normal Temperature Self-Refresh Current Current Current Current DD6 - 11 - 11 - 11 mA							-		_		_		
Operating One Bank Active-Read-Precharge Current IDD1 - 175 - 160 - 145 - 130 mA Operating Burst Read Current IDD4R - 230 - 210 - 190 - 165 mA Operating Burst Write Current IDD4W - 260 - 235 - 210 - 185 mA Burst Refresh Current IDD5B - 195 - 190 - 180 - 175 mA Normal Temperature Self-Refresh Current IDD6 - 11 - 11 - 11 - 11 mA	Operating One Bank Active-Precharge			IDD0			_		_		_		
Operating Burst Read Current IDD4R - 230 - 210 - 190 - 165 mA Operating Burst Write Current IDD4W - 260 - 235 - 210 - 185 mA Burst Refresh Current IDD5B - 195 - 190 - 180 - 175 mA Normal Temperature Self-Refresh Current IDD6 - 11 - 11 - 11 - 11 mA	Operating One Bank Active-Read-			IDD1	_	175	_	160	_	145	_	130	mA
Operating Burst Write Current IDD4W - 260 - 235 - 210 - 185 mA Burst Refresh Current IDD5B - 195 - 190 - 180 - 175 mA Normal Temperature Self-Refresh Current IDD6 - 11 - 11 - 11 - 11 mA				IDD4R	_	230	_	210	_	190	_	165	mA
Burst Refresh Current IDD5B - 195 - 190 - 180 - 175 mA Normal Temperature Self-Refresh Current IDD6 - 11 - 11 - 11 - 11 - 11 mA	Operating Burst Write Current IDD4W				_	260	_	235	_	210	-	185	mA
Normal Temperature Self-Refresh Current IDD6 - 11 - 11 - 11 mA				_	_	195	_	190	_	180	_	175	mA
Operating Bank Interleave Current IDD7 - 290 - 260 - 235 - 205 mA	Normal Temperature Self-Refresh Inne				-	11	_	11	_	11	-	11	mA
	Operating Ban	k Interleave	Current	IDD7	_	290	_	260	-	235	-	205	mA

Notes: (Field value contents in blue font or parentheses are optional AC parameter and CL setting)

- 1. All speed grades support 0°C ≤ TCASE ≤ 85°C with full JEDEC AC and DC specifications.
- 2. The -09, -11, -12 and -15 speed grades, $-40^{\circ}\text{C} \le \text{TCASE} < 0^{\circ}\text{C}$ is not available.
- 3. The 09I, 09J, 11I, 11J, 12I, 12J, 15I and 15J speed grades support -40°C ≤ TCASE ≤ 85°C with full JEDEC AC and DC specifications.
- 4. The -09, 09I, -11, 11I, -12, 12I, -15 and 15I speed grades, TCASE is able to extend to 95°C. The 09J, 11J, 12J and 15J speed grades, TCASE is able to extend to 105°C. They are with doubling Auto Refresh commands in frequency to a 32 mS period (tREFI = $3.9 \mu S$), it is mandatory to either use the Manual Self-Refresh mode with Extended Temperature Range capability (MR2 A6 = 0_b and MR2 A7 = 1_b) or enable the Auto Self-Refresh mode (ASR) (MR2 A6 = 1_b , MR2 A7 is don't care).
- 5. For devices supporting optional down binning to CL=7 and CL=9, tax/tRcD/tRP min must be 13.125 nS or lower. SPD settings must be programmed to match. For example, DDR3L-1333 (9-9-9) devices supporting down binning to DDR3L-1066 (7-7-7) should program 13.125 nS in SPD bytes for taxmin (Byte 16), trcpmin (Byte 18), and trpmin (Byte 20). DDR3L-1600 (11-11-11) devices supporting down binning to DDR3L-1333 (9-9-9) or DDR3L-1066 (7-7-7) should program 13.125 nS in SPD bytes for taxmin (Byte16), trcpmin (Byte 18), and trpmin (Byte 20). Once trp (Byte 20) is programmed to 13.125 nS, trcmin (Byte 21, 23) also should be programmed accordingly. For example, 49.125nS (trasmin + trpmin = 36 nS + 13.125 nS) for DDR3L-1333 (9-9-9) and 48.125 nS (trasmin + trpmin = 35 nS + 13.125 nS) for DDR3L-1600 (11-11-11).

Publication Release Date: Nov. 22, 2017



5. BALL CONFIGURATION

1	2	3	4	5	6	7	8	9
VDDQ	DQU5	DQU7		Α		DQU4	VDDQ	VSS
VSSQ	VDD	VSS		В		DQSU#	DQU6	VSSQ
VDDQ	DQU3	DQU1		С		DQSU	DQU2	VDDQ
VSSQ	VDDQ	DMU		D		DQU0	VSSQ	VDD
VSS	VSSQ	DQL0		E		DML	VSSQ	VDDQ
VDDQ	DQL2	DQSL		F		DQL1	DQL3	VSSQ
VSSQ	DQL6	DQSL#		G		VDD	VSS	VSSQ
VREFDQ	VDDQ	DQL4		Н		DQL7	DQL5	VDDQ
NC	VSS	RAS#		J		СК	VSS	NC
ODT	VDD	CAS#		К		CK#	VDD	CKE
NC	CS#	WE#		L		A10/AP	ZQ	NC
VSS	BA0	BA2		М		NC	VREFCA	VSS
VDD	А3	A0		N		A12/BC#	BA1	VDD
VSS	A5	A2		Р		A1	A4	VSS
VDD	A7	A9		R		A11	A6	VDD
VSS	RESET#	A13		т		NC	A8	VSS



6. BALL DESCRIPTION

BALL NUMBER	SYMBOL	TYPE	DESCRIPTION
J7, K7	CK, CK#	Input	Clock: CK and CK# are differential clock inputs. All address and control input signals are sampled on the crossing of the positive edge of CK and negative edge of CK#.
К9	CKE	Input	Clock Enable: CKE HIGH activates, and CKE Low deactivates, internal clock signals and device input buffers and output drivers. Taking CKE Low provides Precharge Power Down and Self-Refresh operation (all banks idle), or Active Power Down (row Active in any bank). CKE is asynchronous for Self-Refresh exit. After VREFCA and VREFDQ have become stable during the power on and initialization sequence, they must be maintained during all operations (including Self-Refresh). CKE must be maintained high throughout read and write accesses. Input buffers, excluding CK, CK#, ODT and CKE, are disabled during power down. Input buffers, excluding CKE, are disabled during Self-Refresh.
L2	CS#	Input	Chip Select: All commands are masked when CS# is registered HIGH. CS# provides for external Rank selection on systems with multiple Ranks. CS# is considered part of the command code.
K1	ODT	Input	On Die Termination: ODT (registered HIGH) enables termination resistance internal to the DDR3L SDRAM. When enabled, ODT is applied to each DQ, DQSU, DQSU#, DQSL, DQSL#, DMU, and DML signal. The ODT signal will be ignored if Mode Registers MR1 and MR2 are programmed to disable ODT and during Self Refresh.
J3, K3, L3	RAS#, CAS#, WE#	Input	Command Inputs: RAS#, CAS# and WE# (along with CS#) define the command being entered.
D3, E7	DMU, DML	Input	Input Data Mask: DMU and DML are the input mask signals control the lower or upper bytes for write data. Input data is masked when DMU/DML is sampled HIGH coincident with that input data during a Write access. DM is sampled on both edges of DQS.
M2, N8, M3	BA0-BA2	Input	Bank Address Inputs: BA0-BA2 define to which bank an Active, Read, Write, or Precharge command is being applied. Bank address also determines which mode register is to be accessed during a MRS cycle.
N3, P7, P3, N2, P8, P2, R8, R2, T8, R3, L7, R7, N7, T3	A0-A13	Input	Address Inputs: Provide the row address for Active commands and the column address for Read/Write commands to select one location out of the memory array in the respective bank. (A10/AP and A12/BC# have additional functions; see below). The address inputs also provide the op-code during Mode Register Set command. Row address: A0-A13. Column address: A0-A9.
L7	A10/AP	Input	Auto-precharge: A10 is sampled during Read/Write commands to determine whether Auto-precharge should be performed to the accessed bank after the Read/Write operation. (HIGH: Auto-precharge; LOW: no Auto-precharge). A10 is sampled during a Precharge command to determine whether the Precharge applies to one bank (A10 LOW) or all banks (A10 HIGH). If only one bank is to be precharged, the bank is selected by bank addresses.
N7	A12/BC#	Input	Burst Chop: A12/BC# is sampled during Read and Write commands to determine if burst chop (on-the-fly) will be performed. (HIGH, no burst chop; LOW: burst chopped). See section 9.1 "Command Truth Table" on page 94 for details.
T2	RESET#	Input	Active Low Asynchronous Reset: Reset is active when RESET# is LOW, and inactive when RESET# is HIGH. RESET# must be HIGH during normal operation. RESET# is a CMOS rail to rail signal with DC high and low at 80% and 20% of VDD, RESET# active is destructive to data contents.

____winbond ____

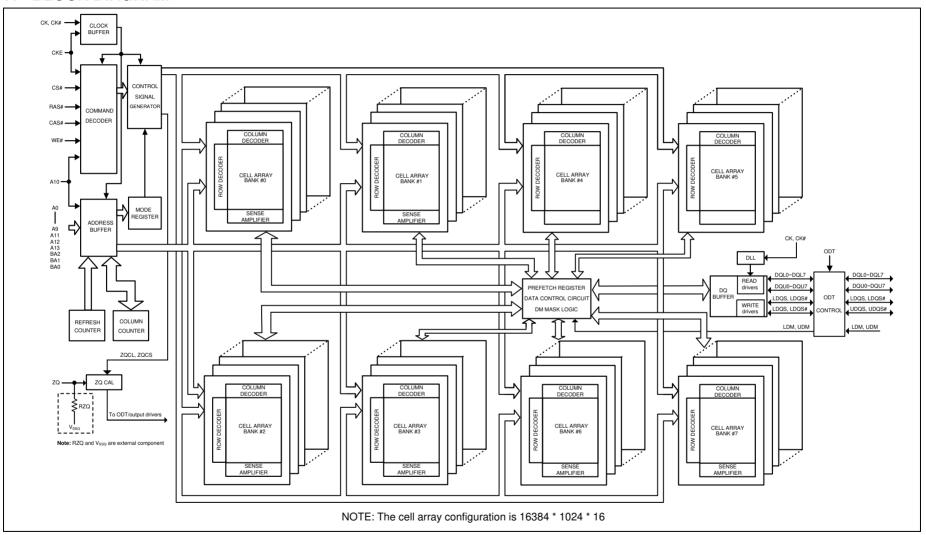
E3, F7, F2, F8, H3, H8, G2, H7	DQL0-DQL7	Input/Output	Data Input/Output: Lower byte of Bi-directional data bus.
D7, C3, C8, C2, A7, A2, B8, A3	DQU0-DQU7	Input/Output	Data Input/Output: Upper byte of Bi-directional data bus.
F3, G3	DQSL, DQSL#	Input/Output	Lower byte data Strobe: Data Strobe output with read data, input with write data of DQL[7:0]. Edge-aligned with read data, centered in write data. DQSL is paired with DQSL# to provide differential pair signaling to the system during read and write data transfer. DDR3L SDRAM supports differential data strobe only and does not support single-ended.
C7, B7	DQSU, DQSU#	Input/Output	Upper byte data Strobe: Data Strobe output with read data, input with write data of DQU[7:0]. Edge-aligned with read data, centered in write data. DQSU is paired with DQSU# to provide differential pair signaling to the system during read and write data transfer. DDR3L SDRAM supports differential data strobe only and does not support single-ended.
B2, D9, G7, K2, K8, N1, N9, R1, R9	VDD	Supply	Power Supply: 1.283V to 1.45V operational.
A9, B3, E1, G8, J2, J8, M1, M9, P1, P9, T1, T9	Vss	Supply	Ground.
A1, A8, C1, C9, D2, E9, F1, H2, H9	VDDQ	Supply	DQ Power Supply: 1.283V to 1.45V operational.
B1, B9, D1, D8, E2, E8, F9, G1, G9	Vssq	Supply	DQ Ground.
H1	VREFDQ	Supply	Reference voltage for DQ.
M8	VREFCA	Supply	Reference voltage for Control, Command and Address inputs.
L8	ZQ	Supply	External reference ball for output drive and On-Die Termination Impedance calibration: This ball needs an external 240 Ω \pm 1% external resistor (RZQ), connected from this ball to ground to perform ZQ calibration.
J1, J9, L1, L9, M7, T7	NC		No Connect: No internal electrical connection is present.

Note:

Input only balls (BA0-BA2, A0-A13, RAS#, CAS#, WE#, CS#, CKE, ODT and RESET#) do not supply termination.



7. BLOCK DIAGRAM



Publication Release Date: Nov. 22, 2017



8. FUNCTIONAL DESCRIPTION

8.1 Basic Functionality

The DDR3L SDRAM is a high-speed dynamic random-access memory internally configured as an eight-bank DRAM. The DDR3L SDRAM uses an 8n prefetch architecture to achieve high-speed operation. The 8n prefetch architecture is combined with an interface designed to transfer two data words per clock cycle at the I/O pins. A single read or write operation for the DDR3L SDRAM consists of a single 8n-bit wide, four clock data transfer at the internal DRAM core and eight corresponding n-bit wide, one-half clock cycle data transfers at the I/O pins.

Read and write operation to the DDR3L SDRAM are burst oriented, start at a selected location, and continue for a burst length of eight or a 'chopped' burst of four in a programmed sequence. Operation begins with the registration of an Active command, which is then followed by a Read or Write command. The address bits registered coincident with the Active command are used to select the bank and row to be activated (BA0-BA2 select the bank; A0-A13 select the row). The address bits registered coincident with the Read or Write command are used to select the starting column location for the burst operation, determine if the auto precharge command is to be issued (via A10), and select BC4 or BL8 mode 'on the fly' (via A12) if enabled in the mode register.

Prior to normal operation, the DDR3L SDRAM must be powered up and initialized in a predefined manner. The following sections provide detailed information covering device reset and initialization, register definition, command descriptions, and device operation.

8.2 RESET and Initialization Procedure

8.2.1 Power-up Initialization Sequence

The following sequence is required for POWER UP and Initialization.

- 1. Apply power (RESET# is recommended to be maintained below 0.2 * VDD; all other inputs may be undefined). RESET# needs to be maintained for minimum 200 µS with stable power. CKE is pulled "Low" anytime before RESET# being de-asserted (min. time 10 nS). The power voltage ramp time between 300 mV to VDD min. must be no greater than 200 mS; and during the ramp, VDD ≥ VDDQ and (VDD VDDQ) < 0.3 Volts.</p>
 - VDD and VDDQ are driven from a single power converter output, AND
 - The voltage levels on all pins other than VDD, VDDQ, VSS, VSSQ must be less than or equal to VDDQ and VDD on one side and must be larger than or equal to VSSQ and VSS on the other side. In addition, VTT is limited to 0.95 V max once power ramp is finished, AND
 - VREF tracks VDDQ/2.

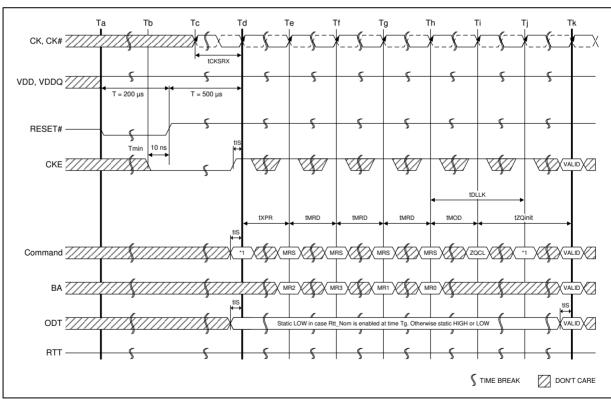
OR

- Apply VDD without any slope reversal before or at the same time as VDDQ.
- Apply VDDQ without any slope reversal before or at the same time as VTT & VREF.
- The voltage levels on all pins other than VDD, VDDQ, VSS, VSSQ must be less than or equal to VDDQ and VDD on one side and must be larger than or equal to VSSQ and VSS on the other side.
- 2. After RESET# is de-asserted, wait for another 500 μ S until CKE becomes active. During this time, the DRAM will start internal state initialization; this will be done independently of external clocks.
- 3. Clocks (CK, CK#) need to be started and stabilized for at least 10 nS or 5 tck (which is larger) before CKE goes active. Since CKE is a synchronous signal, the corresponding set up time to clock (tis) must be met. Also, a NOP or Deselect command must be registered (with tis set up time to clock) before CKE goes active. Once the CKE is registered "High" after Reset, CKE needs to be continuously registered "High" until the initialization sequence is finished, including expiration of tDLLK and tZQinit.

Publication Release Date: Nov. 22, 2017

winhand

- 4. The DDR3L SDRAM keeps its on-die termination in high-impedance state as long as RESET# is asserted. Further, the SDRAM keeps its on-die termination in high impedance state after RESET# deassertion until CKE is registered HIGH. The ODT input signal may be in undefined state until tis before CKE is registered HIGH. When CKE is registered HIGH, the ODT input signal may be statically held at either LOW or HIGH. If Rtt_Nom is to be enabled in MR1, the ODT input signal must be statically held LOW. In all cases, the ODT input signal remains static until the power up initialization sequence is finished, including the expiration of tDLLK and tZQinit.
- 5. After CKE is being registered high, wait minimum of Reset CKE Exit time, tXPR, before issuing the first MRS command to load mode register. (tXPR=max (tXS; 5 * tCK)
- 6. Issue MRS Command to load MR2 with all application settings. (To issue MRS command for MR2, provide "Low" to BA0 and BA2, "High" to BA1.)
- 7. Issue MRS Command to load MR3 with all application settings. (To issue MRS command for MR3, provide "Low" to BA2, "High" to BA0 and BA1.)
- 8. Issue MRS Command to load MR1 with all application settings and DLL enabled. (To issue "DLL Enable" command, provide "Low" to A0, "High" to BA0 and "Low" to BA1-BA2).
- 9. Issue MRS Command to load MR0 with all application settings and "DLL reset". (To issue DLL reset command, provide "High" to A8 and "Low" to BA0-2).
- 10. Issue ZQCL command to starting ZQ calibration.
- 11. Wait for both tDLLK and tZQinit completed.
- 12. The DDR3L SDRAM is now ready for normal operation.



Note:

1. From time point "Td" until "Tk" NOP or DES commands must be applied between MRS and ZQCL commands.

Figure 1 - Reset and Initialization Sequence at Power-on Ramping

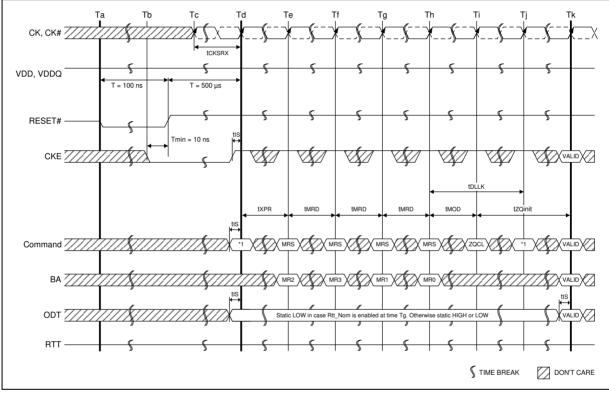
Publication Release Date: Nov. 22, 2017



8.2.2 Reset Initialization with Stable Power

The following sequence is required for RESET at no power interruption initialization.

- 1. Asserted RESET below 0.2 * VDD anytime when reset is needed (all other inputs may be undefined). RESET needs to be maintained for minimum 100 nS. CKE is pulled "LOW" before RESET being de-asserted (min. time 10 nS).
- 2. Follow Power-up Initialization Sequence steps 2 to 11.
- 3. The Reset sequence is now completed; DDR3L SDRAM is ready for normal operation.



Note:

1. From time point "Td" until "Tk" NOP or DES commands must be applied between MRS and ZQCL commands.

Figure 2 - Reset Procedure at Power Stable Condition

Publication Release Date: Nov. 22, 2017



8.3 Programming the Mode Registers

For application flexibility, various functions, features, and modes are programmable in four Mode Registers, provided by the DDR3L SDRAM, as user defined variables and they must be programmed via a Mode Register Set (MRS) command. As the default values of the Mode Registers (MR#) are not defined, contents of Mode Registers must be fully initialized and/or re-initialized, i.e., written, after power up and/or reset for proper operation. Also the contents of the Mode Registers can be altered by re-executing the MRS command during normal operation. When programming the mode registers, even if the user chooses to modify only a sub-set of the MRS fields, all address fields within the accessed mode register must be redefined when the MRS command is issued. MRS command and DLL Reset do not affect array contents, which mean these commands can be executed any time after power-up without affecting the array contents.

The mode register set command cycle time, tMRD is required to complete the write operation to the mode register and is the minimum time required between two MRS commands shown in Figure 3.

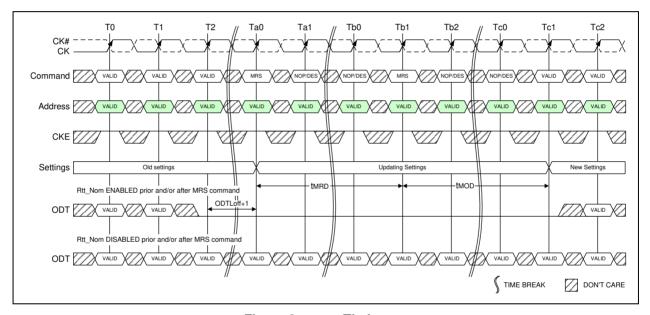


Figure 3 - tMRD Timing

Publication Release Date: Nov. 22, 2017

massa winbond sassa

The MRS command to Non-MRS command delay, tMOD is required for the DRAM to update the features, except DLL reset, and is the minimum time required from a MRS command to a non-MRS command excluding NOP and DES shown in Figure 4.

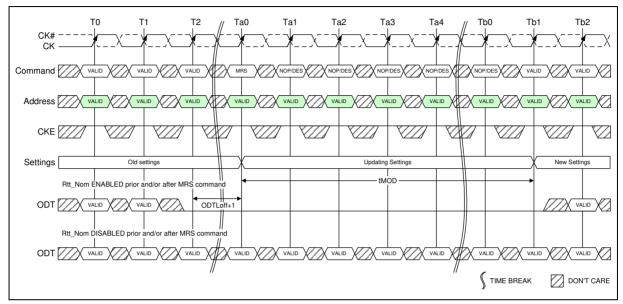


Figure 4 - tMOD Timing

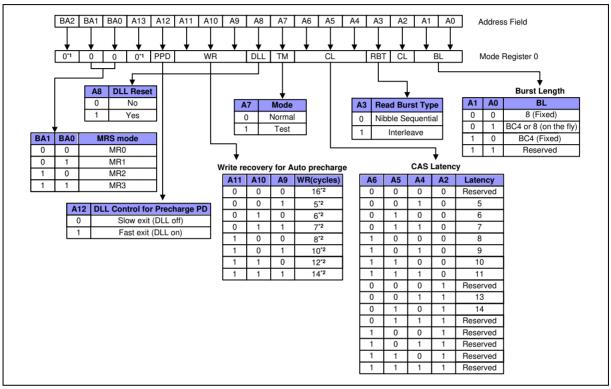
The mode register contents can be changed using the same command and timing requirements during normal operation as long as the DRAM is in idle state, i.e., all banks are in the precharged state with trp satisfied, all data bursts are completed and CKE is high prior to writing into the mode register. If the Rtt_Nom Feature is enabled in the Mode Register prior and/or after a MRS command, the ODT signal must continuously be registered LOW ensuring RTT is in an off state prior to the MRS command. The ODT signal may be registered high after tmod has expired. If the Rtt_Nom feature is disabled in the Mode Register prior and after a MRS command, the ODT signal can be registered either LOW or HIGH before, during and after the MRS command. The mode registers are divided into various fields depending on the functionality and/or modes.

Publication Release Date: Nov. 22, 2017



8.3.1 Mode Register MR0

The mode register MR0 stores the data for controlling various operating modes of DDR3L SDRAM. It controls burst length, read burst type, CAS latency, test mode, DLL reset, WR and DLL control for precharge Power Down, which include various vendor specific options to make DDR3L SDRAM useful for various applications. The mode register is written by asserting low on CS#, RAS#, CAS#, WE#, BA0, BA1 and BA2, while controlling the states of address pins according to the Figure 5 below.



Notes:

- 1. BA2 and A13 are reserved for future use and must be programmed to "0" during MRS.
- 2. WR (write recovery for Auto precharge)min in clock cycles is calculated by dividing tWR (in nS) by tCK (in nS) and rounding up to the next integer: WRmin[cycles] = Roundup(tWR[nS] / tCK(avg)[nS]). The WR value in the mode register must be programmed to be equal or larger than WRmin. The programmed WR value is used with tRP to determine tDAL.
- The table only shows the encodings for a given Cas Latency. For actual supported CAS Latency, please refer to "Speed Bins" tables for each frequency.
- 4. The table only shows the encodings for Write Recovery. For actual Write recovery timing, please refer to AC timing table.

Figure 5 - MR0 Definition

Publication Release Date: Nov. 22, 2017



8.3.1.1 Burst Length, Type and Order

Accesses within a given burst may be programmed to sequential or interleaved order. The burst type is selected via bit A3 as shown in Figure 5. The ordering of accesses within a burst is determined by the burst length, burst type, and the starting column address as shown in Table 1. The burst length is defined by bits A0-A1. Burst length options include fixed BC4, fixed BL8 and 'on the fly' which allows BC4 or BL8 to be selected coincident with the registration of a Read or Write command via A12/BC#.

Burst type = Sequential Burst type = Interleaved READ/ **Starting Column Address** Burst (decimal) (decimal) **NOTES** WRITE Length (A2, A1, A0) A3 = 0A3 = 1000 0,1,2,3,T,T,T,T 0,1,2,3,T,T,T,T 1, 2, 3 001 1, 2, 3 1,2,3,0,T,T,T,T 1,0,3,2,T,T,T,T 010 2,3,0,1,T,T,T,T 2.3.0.1.T.T.T.T 1, 2, 3 3,2,1,0,T,T,T,T 1, 2, 3 011 3,0,1,2,T,T,T,T READ 100 4,5,6,7,T,T,T,T 4,5,6,7,T,T,T,T 1, 2, 3 Chop 1, 2, 3 101 5,6,7,4,T,T,T,T 5,4,7,6,T,T,T,T 1, 2, 3 110 6,7,4,5,T,T,T,T 6,7,4,5,T,T,T,T 111 7,4,5,6,T,T,T,T 7,6,5,4,T,T,T,T 1, 2, 3 0,V,V 0,1,2,3,X,X,X,X 0,1,2,3,X,X,X,X 1, 2, 4, 5 WRITE 1,V,V 4,5,6,7,X,X,X,X 4,5,6,7,X,X,X,X 1, 2, 4, 5 000 0,1,2,3,4,5,6,7 0,1,2,3,4,5,6,7 2 001 1,2,3,0,5,6,7,4 1,0,3,2,5,4,7,6 2 010 2,3,0,1,6,7,4,5 2,3,0,1,6,7,4,5 011 3,0,1,2,7,4,5,6 2 3,2,1,0,7,6,5,4 READ 8 100 4,5,6,7,0,1,2,3 4,5,6,7,0,1,2,3 2 101 5,6,7,4,1,2,3,0 5,4,7,6,1,0,3,2 2 110 6,7,4,5,2,3,0,1 6,7,4,5,2,3,0,1 2 111 7,4,5,6,3,0,1,2 7,6,5,4,3,2,1,0 2

Table 1 - Burst Type and Burst Order

Notes:

1. In case of burst length being fixed to 4 by MR0 setting, the internal write operation starts two clock cycles earlier than for the BL8 mode. This means that the starting point for tWR and tWTR will be pulled in by two clocks. In case of burst length being selected on-the-fly via A12/BC#, the internal write operation starts at the same point in time like a burst of 8 write operation. This means that during on-the-fly control, the starting point for tWR and tWTR will not be pulled in by two clocks.

0,1,2,3,4,5,6,7

- 2. 0...7 bit number is value of CA[2:0] that causes this bit to be the first read during a burst.
- 3. T: Output driver for data and strobes are in high impedance.
- 4. V: a valid logic level (0 or 1), but respective buffer input ignores level on input pins.

V,V,V

5. X: Don't Care.

8.3.1.2 CAS Latency

WRITE

The CAS Latency is defined by MR0 (bits A2, A4, A5 and A6) as shown in Figure 5. CAS Latency is the delay, in clock cycles, between the internal Read command and the availability of the first bit of output data. DDR3L SDRAM does not support any half-clock latencies. The overall Read Latency (RL) is defined as Additive Latency (AL) + CAS Latency (CL); RL = AL + CL. For more information on the supported CL and AL settings based on the operating clock frequency, refer to section 10.15 "Speed Bins" on page 133. For detailed Read operation refer to section 8.13 "READ Operation" on page 43.

Publication Release Date: Nov. 22, 2017

0,1,2,3,4,5,6,7

Revision: A02

2, 4



8.3.1.3 Test Mode

The normal operating mode is selected by MR0 (bit A7 = 0) and all other bits set to the desired values shown in Figure 5. Programming bit A7 to a '1' places the DDR3L SDRAM into a test mode that is only used by the DRAM Manufacturer and should NOT be used. No operations or functionality is specified if A7 = 1.

8.3.1.4 DLL Reset

The DLL Reset bit is self-clearing, meaning that it returns back to the value of '0' after the DLL reset function has been issued. Once the DLL is enabled, a subsequent DLL Reset should be applied. Any time that the DLL reset function is used, tDLLK must be met before any functions that require the DLL can be used (i.e., Read commands or ODT synchronous operations).

8.3.1.5 Write Recovery

The programmed WR value MR0 (bits A9, A10 and A11) is used for the auto precharge feature along with tRP to determine tDAL. WR (write recovery for auto-precharge) min in clock cycles is calculated by dividing tWR (in nS) by tCK(avg) (in nS) and rounding up to the next integer: WRmin[cycles] = Roundup(tWR[nS]/tCK(avg)[nS]). The WR must be programmed to be equal to or larger than tWR(min).

8.3.1.6 Precharge PD DLL

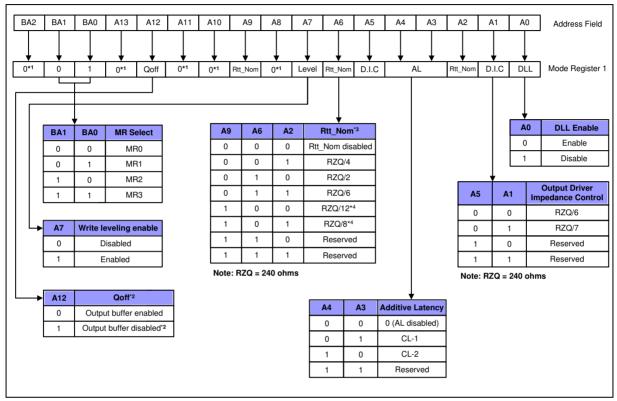
MR0 (bit A12) is used to select the DLL usage during precharge power down mode. When MR0 (A12 = 0), or 'slow-exit', the DLL is frozen after entering precharge power down (for potential power savings) and upon exit requires tXPDLL to be met prior to the next valid command. When MR0 (A12 = 1), or 'fast-exit', the DLL is maintained after entering precharge power down and upon exiting power down requires tXP to be met prior to the next valid command.

Publication Release Date: Nov. 22, 2017



8.3.2 Mode Register MR1

The Mode Register MR1 stores the data for enabling or disabling the DLL, output driver strength, Rtt_Nom impedance, additive latency, Write leveling enable and Qoff. The Mode Register 1 is written by asserting low on CS#, RAS#, CAS#, WE#, high on BA0 and low on BA1 and BA2, while controlling the states of address pins according to the Figure 6 below.



Notes:

- 1. BA2, A8, A10, A11 and A13 are reserved for future use and must be programmed to "0" during MRS.
- 2. Outputs disabled DQs. DQSs. DQS#s.
- 3. In Write leveling Mode (MR1 A[7] = 1) with MR1 A[12]=1, all Rtt_Nom settings are allowed; in Write Leveling Mode (MR1 A[7] = 1) with MR1 A[12]=0, only Rtt_Nom settings of RZQ/2, RZQ/4 and RZQ/6 are allowed.
- 4. If Rtt_Nom is used during Writes, only the values RZQ/2, RZQ/4 and RZQ/6 are allowed.

Figure 6 - MR1 Definition

8.3.2.1 DLL Enable/Disable

The DLL must be enabled for normal operation. DLL enable is required during power up initialization, and upon returning to normal operation after having the DLL disabled. During normal operation (DLL-on) with MR1 (A0 = 0), the DLL is automatically disabled when entering Self Refresh operation and is automatically re-enabled upon exit of Self Refresh operation. Any time the DLL is enabled and subsequently reset, tDLLK clock cycles must occur before a Read or synchronous ODT command can be issued to allow time for the internal clock to be synchronized with the external clock. Failing to wait for synchronization to occur may result in a violation of the tDQSCK, tAON or tAOF parameters. During tDLLK, CKE must continuously be registered high. DDR3L SDRAM does not require DLL for any Write operation, except when Rtt_WR is enabled and the DLL is required for proper ODT operation. For more detailed information on DLL Disable operation refer to section 8.6 "DLL-off Mode" on page 25.

The direct ODT feature is not supported during DLL-off mode. The on-die termination resistors must be disabled by continuously registering the ODT pin low and/or by programming the Rtt_Nom bits MR1{A9,A6,A2} to {0,0,0} via a mode register set command during DLL-off mode.

Publication Release Date: Nov. 22, 2017



The dynamic ODT feature is not supported at DLL-off mode. User must use MRS command to set Rtt_WR , $MR2 \{A10, A9\} = \{0,0\}$, to disable Dynamic ODT externally.

8.3.2.2 Output Driver Impedance Control

The output driver impedance of the DDR3L SDRAM device is selected by MR1 (bits A1 and A5) as shown in Figure 6.

8.3.2.3 ODT RTT Values

DDR3L SDRAM is capable of providing two different termination values (Rtt_Nom and Rtt_WR). The nominal termination value Rtt_Nom is programmed in MR1. A separate value (Rtt_WR) may be programmed in MR2 to enable a unique RTT value when ODT is enabled during writes. The Rtt_WR value can be applied during writes even when Rtt_Nom is disabled.

8.3.2.4 Additive Latency (AL)

Additive Latency (AL) operation is supported to make command and data bus efficient for sustainable bandwidths in DDR3L SDRAM. In this operation, the DDR3L SDRAM allows a read or write command (either with or without auto-precharge) to be issued immediately after the active command. The command is held for the time of the Additive Latency (AL) before it is issued inside the device. The Read Latency (RL) is controlled by the sum of the AL and CAS Latency (CL) register settings. Write Latency (WL) is controlled by the sum of the AL and CAS Write Latency (CWL) register settings. A summary of the AL register options are shown in Table 2.

 A4
 A3
 AL

 0
 0
 0 (AL Disabled)

 0
 1
 CL - 1

 1
 0
 CL - 2

 1
 1
 Reserved

Table 2 - Additive Latency (AL) Settings

Note:

AL has a value of CL - 1 or CL - 2 as per the CL values programmed in the MR0 register.

8.3.2.5 Write leveling

For better signal integrity, DDR3L memory module adopted fly-by topology for the commands, addresses, control signals, and clocks. The fly-by topology has the benefit of reducing the number of stubs and their length, but it also causes flight time skew between clock and strobe at every DRAM on the DIMM. This makes it difficult for the controller to maintain tDQSS, tDSS, and tDSH specification. Therefore, the DDR3L SDRAM supports a 'write leveling' feature to allow the controller to compensate for skew. See section 8.9 "Write Leveling" on page 30 for more details.

8.3.2.6 Output Disable

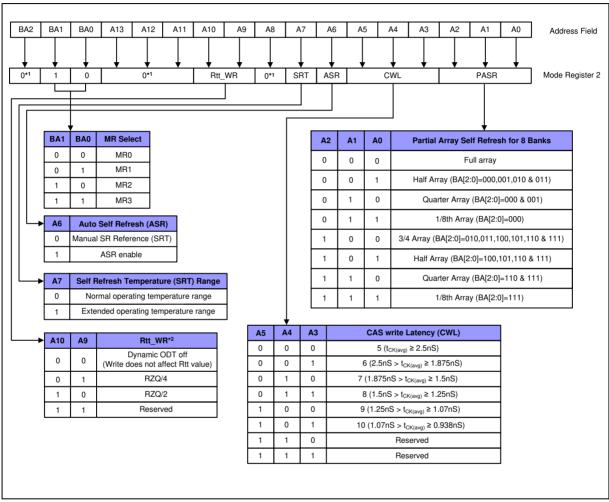
The DDR3L SDRAM outputs may be enabled/disabled by MR1 (bit A12) as shown in Figure 6. When this feature is enabled (A12 = 1), all output pins (DQs, DQS, DQS#, etc.) are disconnected from the device, thus removing any loading of the output drivers. This feature may be useful when measuring module power, for example. For normal operation, A12 should be set to '0'.

Publication Release Date: Nov. 22, 2017



8.3.3 Mode Register MR2

The Mode Register MR2 stores the data for controlling refresh related features, Rtt_WR impedance, and CAS write latency. The Mode Register 2 is written by asserting low on CS#, RAS#, CAS#, WE#, high on BA1 and low on BA0 and BA2, while controlling the states of address pins according to the Figure 7 below.



Notes:

- 1. BA2, A8, A11~A13 are reserved for future use and must be programmed to "0" during MRS.
- 2. The Rtt_WR value can be applied during writes even when Rtt_Nom is disabled. During write leveling, Dynamic ODT is not available.

Figure 7 - MR2 Definition

Publication Release Date: Nov. 22, 2017



8.3.3.1 Partial Array Self Refresh (PASR)

If PASR (Partial Array Self Refresh) is enabled, data located in areas of the array beyond the specified address range shown in Figure 7 will be lost if Self Refresh is entered. Data integrity will be maintained if tREFI conditions are met and no Self Refresh command is issued.

8.3.3.2 CAS Write Latency (CWL)

The CAS Write Latency is defined by MR2 (bits A3-A5), as shown in Figure 7. CAS Write Latency is the delay, in clock cycles, between the internal Write command and the availability of the first bit of input data.

DDR3L SDRAM does not support any half-clock latencies. The overall Write Latency (WL) is defined as Additive Latency (AL) + CAS Write Latency (CWL); WL = AL + CWL. For more information on the supported CWL and AL settings based on the operating clock frequency, refer to section 10.15 "Speed Bins" on page 133. For detailed Write operation refer to section 8.14 "WRITE Operation" on page 56.

8.3.3.3 Auto Self Refresh (ASR) and Self Refresh Temperature (SRT)

DDR3L SDRAM must support Self Refresh operation at all supported temperatures. Applications requiring Self Refresh operation in the Extended Temperature Range must use the ASR function or program the SRT bit appropriately.

When ASR enabled, DDR3L SDRAM automatically provides Self Refresh power management functions for all supported operating temperature values. If not enabled, the SRT bit must be programmed to indicate TOPER during subsequent Self Refresh operation.

ASR = 0, Self Refresh rate is determined by SRT bit A7 in MR2.

ASR = 1, Self Refresh rate is determined by on-die thermal sensor. SRT bit A7 in MR2 is don't care.

8.3.3.4 Dynamic ODT (Rtt_WR)

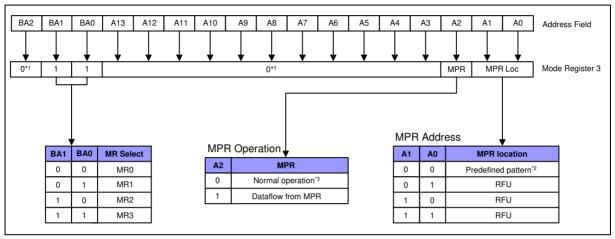
DDR3L SDRAM introduces a new feature "**Dynamic ODT**". In certain application cases and to further enhance signal integrity on the data bus, it is desirable that the termination strength of the DDR3L SDRAM can be changed without issuing an MRS command. MR2 Register locations A9 and A10 configure the Dynamic ODT settings. In Write leveling mode, only Rtt_Nom is available. For details on Dynamic ODT operation, refer to section 8.19.3 "**Dynamic ODT**" on page 83.

Publication Release Date: Nov. 22, 2017



8.3.4 Mode Register MR3

The Mode Register MR3 controls Multi purpose registers. The Mode Register 3 is written by asserting low on CS#, RAS#, CAS#, WE#, high on BA1 and BA0, and low on BA2 while controlling the states of address pins according to the Figure 8 below.



Notes:

- 1. BA2, A3~A13 are reserved for future use and must be programmed to "0" during MRS.
- 2. The predefined pattern will be used for read synchronization.
- 3. When MPR control is set for normal operation (MR3 A[2] = 0) then MR3 A[1:0] will be ignored.

Figure 8 - MR3 Definition

8.3.4.1 Multi Purpose Register (MPR)

The Multi Purpose Register (MPR) function is used to Read out a predefined system timing calibration bit sequence. To enable the MPR, a MODE Register Set (MRS) command must be issued to MR3 Register with bit A2 = 1. Prior to issuing the MRS command, all banks must be in the idle state (all banks precharged and tRP met). Once the MPR is enabled, any subsequent RD or RDA commands will be redirected to the Multi Purpose Register. When the MPR is enabled, only RD or RDA commands are allowed until a subsequent MRS command is issued with the MPR disabled (MR3 bit A2 = 0). Power Down mode, Self Refresh, and any other non-RD/RDA command is not allowed during MPR enable mode. The RESET function is supported during MPR enable mode. For detailed MPR operation refer to section 8.10 "Multi Purpose Register" on page 34.

Publication Release Date: Nov. 22, 2017



8.4 No OPeration (NOP) Command

The No OPeration (NOP) command is used to instruct the selected DDR3L SDRAM to perform a NOP (CS# LOW and RAS#, CAS#, and WE# HIGH). This prevents unwanted commands from being registered during idle or wait states. Operations already in progress are not affected.

8.5 Deselect Command

The DESELECT function (CS# HIGH) prevents new commands from being executed by the DDR3L SDRAM. The DDR3L SDRAM is effectively deselected. Operations already in progress are not affected.

8.6 DLL-off Mode

DDR3L DLL-off mode is entered by setting MR1 bit A0 to "1"; this will disable the DLL for subsequent operations until A0 bit is set back to "0". The MR1 A0 bit for DLL control can be switched either during initialization or later. Refer to section 8.8 "Input clock frequency change" on page 28.

The DLL-off Mode operations listed below are an optional feature for DDR3L. The maximum clock frequency for DLL-off Mode is specified by the parameter tCK(DLL_OFF). There is no minimum frequency limit besides the need to satisfy the refresh interval, tREFI.

Due to latency counter and timing restrictions, only one value of CAS Latency (CL) in MR0 and CAS Write Latency (CWL) in MR2 are supported. The DLL-off mode is only required to support setting of both CL=6 and CWL=6.

DLL-off mode will affect the Read data Clock to Data Strobe relationship (tDQSCK), but not the Data Strobe to Data relationship (tDQSQ, tQH). Special attention is needed to line up Read data to controller time domain.

Comparing with DLL-on mode, where tDQSCK starts from the rising clock edge (AL+CL) cycles after the Read command, the DLL-off mode tDQSCK starts (AL+CL - 1) cycles after the read command. Another difference is that tDQSCK may not be small compared to tCK (it might even be larger than tCK) and the difference between tDQSCK min and tDQSCK max is significantly larger than in DLL-on mode.

The timing relations on DLL-off mode READ operation is shown in the following Timing Diagram (CL=6, BL=8):

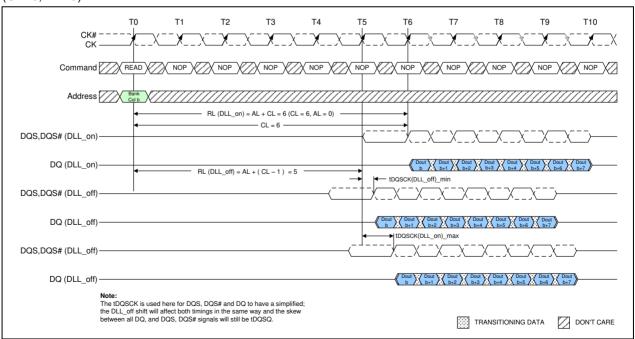


Figure 9 – DLL-off mode READ Timing Operation

Publication Release Date: Nov. 22, 2017