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8-BIT MICROCONTROLLER

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1. GENERAL DESCRIPTION

The W77C032 is a fast 8051 compatible microcontroller with a redesigned processor core without wasted clock and memory cycles. As a result, it executes every 8051 instruction faster than the original 8051 for the same crystal speed. Typically, the instruction executing time of W77C032 is 1.5 to 3 times faster than that of traditional 8051, depending on the type of instruction. In general, the overall performance is about 2.5 times better than the original for the same crystal speed. Giving the same throughput with lower clock speed, power consumption has been improved. Consequently, the W77C032 is a fully static CMOS design; it can also be operated at a lower crystal clock. The W77C032 provides operating voltage from 4.5V to 5.5V. All W77C032 types also support on-chip 1KB SRAM without external memory component and glue logic, saving more I/O pins for users application usage if they use on-chip SRAM instead of external SRAM.

2. FEATURES

- 8-bit CMOS microcontroller
- High speed architecture of 4 clocks/machine cycle runs up to 40 MHz
- Pin compatible with standard 80C52
- Instruction-set compatible with MCS-51
- Four 8-bit I/O Ports
- One extra 4-bit I/O port and Wait State control signal (available on 44-pin PLCC/QFP package)
- Three 16-bit Timers
- 12 interrupt sources with two levels of priority
- On-chip oscillator and clock circuitry
- Two enhanced full duplex serial ports
- 256 bytes scratch-pad RAM
- 1KB on-chip SRAM for MOVX instruction
- Programmable Watchdog Timer
- Dual 16-bit Data Pointers
- Software programmable access cycle to external RAM/peripherals
- Packages:
 - Lead Free (RoHS) DIP 40: W77C032A40DL
 - Lead Free (RoHS) PLCC 44: W77C032A40PL
 - Lead Free (RoHS) PQFP 44: W77C032A40FL

3. PIN CONFIGURATIONS

40-Pin DIP

T2, P1.0	1	40	VDD
T2EX, P1.1	2	39	P0.0, AD0
RXD1, P1.2	3	38	P0.1, AD1
TXD1, P1.3	4	37	P0.2, AD2
INT2, P1.4	5	36	P0.3, AD3
INT3, P1.5	6	35	P0.4, AD4
INT4, P1.6	7	34	P0.5, AD5
INT5, P1.7	8	33	P0.6, AD6
RST	9	32	P0.7, AD7
RXD, P3.0	10	31	EA
TXD, P3.1	11	30	ALE
INT0, P3.2	12	29	PSEN
INT1, P3.3	13	28	P2.7, A15
T0, P3.4	14	27	P2.6, A14
T1, P3.5	15	26	P2.5, A13
WR, P3.6	16	25	P2.4, A12
RD, P3.7	17	24	P2.3, A11
XTAL2	18	23	P2.2, A10
XTAL1	19	22	P2.1, A9
VSS	20	21	P2.0, A8

44-Pin PLCC

INT3, P1.5	7	40	P0.4, AD4
INT4, P1.6	8	39	P0.5, AD5
INT5, P1.7	9	38	P0.6, AD6
RST	10	37	P0.7, AD7
RXD, P3.0	11	36	EA
P4.3	12	35	P4.1
TXD, P3.1	13	34	ALE
INT0, P3.2	14	33	PSEN
INT1, P3.3	15	32	P2.7, A15
T0, P3.4	16	31	P2.6, A14
T1, P3.5	17	30	P2.5, A13
	18	29	
	19	28	
	20	27	
	21	26	
	22	25	
	23	24	
	24	23	
	25	22	
	26	21	
	27	20	
	28	19	
	29	18	
	30	17	
	31	16	
	32	15	
	33	14	
	34	13	
	35	12	
	36	11	
	37	10	
	38	9	
	39	8	
	40	7	

44-Pin QFP

INT3, P1.5	1	33	P0.4, AD4
INT4, P1.6	2	32	P0.5, AD5
INT5, P1.7	3	31	P0.6, AD6
RST	4	30	P0.7, AD7
RXD, P3.0	5	29	EA
P4.3	6	28	P4.1
TXD, P3.1	7	27	ALE
INT0, P3.2	8	26	PSEN
INT1, P3.3	9	25	P2.7, A15
T0, P3.4	10	24	P2.6, A14
T1, P3.5	11	23	P2.5, A13
	12	22	
	13	21	
	14	20	
	15	19	
	16	18	
	17	17	
	18	16	
	19	15	
	20	14	
	21	13	
	22	12	
	23	11	
	24	10	
	25	9	
	26	8	
	27	7	
	28	6	
	29	5	
	30	4	
	31	3	
	32	2	
	33	1	

4. PIN DESCRIPTION

SYMBOL	TYPE	DESCRIPTIONS
\overline{EA}	I	EXTERNAL ACCESS ENABLE: It should be kept low.
\overline{PSEN}	O	PROGRAM STORE ENABLE: \overline{PSEN} enables the external ROM data onto the Port 0 address/data bus during fetch and MOV _C operations.
ALE	O	ADDRESS LATCH ENABLE: ALE is used to enable the address latch that separates the address from the data on Port 0.
RST	I	RESET: A high on this pin for two machine cycles while the oscillator is running resets the device.
XTAL1	I	CRYSTAL1: This is the crystal oscillator input. This pin may be driven by an external clock.
XTAL2	O	CRYSTAL2: This is the crystal oscillator output. It is the inversion of XTAL1.
VSS	I	GROUND: Ground potential
VDD	I	POWER SUPPLY: Supply voltage for operation.
P0.0–P0.7	I/O	PORT 0: Port 0 is an open-drain bi-directional I/O port. This port also provides a multiplexed low order address/data bus during accesses to external memory.
P1.0–P1.7	I/O	PORT 1: Port 1 is a bi-directional I/O port with internal pull-ups. The bits have alternate functions which are described below: T2(P1.0): Timer/Counter 2 external count input T2EX(P1.1): Timer/Counter 2 Reload/Capture/Direction control RXD1(P1.2): Serial port 1 RXD TXD1(P1.3): Serial port 1 TXD INT2(P1.4): External Interrupt 2 $\overline{INT3}$ (P1.5): External Interrupt 3 INT4(P1.6): External Interrupt 4 $\overline{INT5}$ (P1.7): External Interrupt 5
P2.0–P2.7	I/O	PORT 2: Port 2 is a bi-directional I/O port with internal pull-ups. This port also provides the upper address bits for accesses to external memory.
P3.0–P3.7	I/O	PORT 3: Port 3 is a bi-directional I/O port with internal pull-ups. All bits have alternate functions, which are described below: RXD(P3.0) : Serial Port 0 input TXD(P3.1) : Serial Port 0 output $\overline{INT0}$ (P3.2) : External Interrupt 0 $\overline{INT1}$ (P3.3) : External Interrupt 1 T0(P3.4) : Timer 0 External Input T1(P3.5) : Timer 1 External Input \overline{WR} (P3.6) : External Data Memory Write Strobe \overline{RD} (P3.7) : External Data Memory Read Strobe
P4.0–P4.3	I/O	PORT 4: Port 4 is a 4-bit bi-directional I/O port. The P4.0 also provides the alternate function \overline{WAIT} which is the wait state control signal.

* **Note:** TYPE I: input, O: output, I/O: bi-directional.

5. FUNCTIONAL DESCRIPTION

The W77C032 is 8052 pin compatible and instruction set compatible. It includes the resources of the standard 8052 such as four 8-bit I/O Ports, three 16-bit timer/counters, full duplex serial port and interrupt sources.

The W77C032 features a faster running and better performance 8-bit CPU with a redesigned core processor without wasted clock and memory cycles. It improves the performance not just by running at high frequency but also by reducing the machine cycle duration from the standard 8052 period of twelve clocks to four clock cycles for the majority of instructions. This improves performance by an average of 1.5 to 3 times. The W77C032 also provides dual Data Pointers (DPTRs) to speed up block data memory transfers. It can also adjust the duration of the MOVX instruction (access to off-chip data memory) between two machine cycles and nine machine cycles. This flexibility allows the W77C032 to work efficiently with both fast and slow RAMs and peripheral devices. In addition, the W77C032 contains on-chip 1KB MOVX SRAM, the address of which is between 0000H and 03FFH. It only can be accessed by MOVX instruction; this on-chip SRAM is optional under software control.

The W77C032 is an 8052 compatible device that gives the user the features of the original 8052 device, but with improved speed and power consumption characteristics. It has the same instruction set as the 8051 family, with one addition: DEC DPTR (op-code A5H, the DPTR is decreased by 1). While the original 8051 family was designed to operate at 12 clock periods per machine cycle, the W77C032 operates at a much reduced clock rate of only 4 clock periods per machine cycle. This naturally speeds up the execution of instructions. Consequently, the W77C032 can run at a higher speed as compared to the original 8052, even if the same crystal is used. Since the W77C032 is a fully static CMOS design, it can also be operated at a lower crystal clock, giving the same throughput in terms of instruction execution, yet reducing the power consumption.

The 4 clocks per machine cycle feature in the W77C032 is responsible for a three-fold increase in execution speed. The W77C032 has all the standard features of the 8052, and has a few extra peripherals and features as well.

I/O Ports

The W77C032 has four 8-bit ports and one extra 4-bit port. Port 0 can be used as an Address/Data bus when external program is running or external memory/device is accessed by MOVC or MOVX instruction. In these cases, it has strong pull-ups and pull-downs, and does not need any external pull-ups. Otherwise it can be used as a general I/O port with open-drain circuit. Port 2 is used chiefly as the upper 8-bits of the Address bus when port 0 is used as an address/data bus. It also has strong pull-ups and pull-downs when it serves as an address bus. Port 1 and 3 act as I/O ports with alternate functions. Port 4 is only available on 44-pin PLCC/QFP package type. It serves as a general purpose I/O port as Port 1 and Port 3. The P4.0 has an alternate function $\overline{\text{WAIT}}$ which is the wait state control signal. When wait state control signal is enabled, P4.0 is input only.

Serial I/O

The W77C032 has two enhanced serial ports that are functionally similar to the serial port of the original 8052 family. However the serial ports on the W77C032 can operate in different modes in order to obtain timing similarity as well. **Note that the serial port 0 can use Timer 1 or 2 as baud rate generator, but the serial port 1 can only use Timer 1 as baud rate generator.** The serial ports have the enhanced features of Automatic Address recognition and Frame Error detection.

Timers

The W77C032 has three 16-bit timers that are functionally similar to the timers of the 8052 family. When used as timers, they can be set to run at either 4 clocks or 12 clocks per count, thus providing the user with the option of operating in a mode that emulates the timing of the original 8052. The W77C032 has an additional feature, the watchdog timer. This timer is used as a System Monitor or as a very long time period timer.

Interrupts

The Interrupt structure in the W77C032 is slightly different from that of the standard 8052. Due to the presence of additional features and peripherals, the number of interrupt sources and vectors has been increased. The W77C032 provides 12 interrupt resources with two priority level, including six external interrupt sources, timer interrupts, serial I/O interrupts and power-fail interrupt.

Data Pointers

The original 8052 had only one 16-bit Data Pointer (DPL, DPH). In the W77C032, there is an additional 16-bit Data Pointer (DPL1, DPH1). This new Data Pointer uses two SFR locations which were unused in the original 8052. In addition there is an added instruction, DEC DPTR (op-code A5H), which helps in improving programming flexibility for the user.

Power Management

Like the standard 80C52, the W77C032 also has IDLE and POWER DOWN modes of operation. The W77C032 provides a new Economy mode which allow user to switch the internal clock rate divided by either 4, 64 or 1024. In the IDLE mode, the clock to the CPU core is stopped while the timers, serial ports and interrupts clock continue to operate. In the POWER DOWN mode, all the clock are stopped and the chip operation is completely stopped. This is the lowest power consumption state.

On-chip Data SRAM

The W77C032 has 1K Bytes of data space SRAM which is read/write accessible and is memory mapped. This on-chip MOVX SRAM is reached by the MOVX instruction. It is not used for executable program memory. There is no conflict or overlap among the 256 bytes Scratchpad RAM and the 1K Bytes MOVX SRAM as they use different addressing modes and separate instructions. The on-chip MOVX SRAM is enabled by setting the DME0 bit in the PMR register. After a reset, the DME0 bit is cleared such that the on-chip MOVX SRAM is disabled, and all data memory spaces 0000H–FFFFH access to the external memory.

6. MEMORY ORGANIZATION

The W77C032 separates the memory into two separate sections, the Program Memory and the Data Memory. The Program Memory is used to store the instruction op-codes, while the Data Memory is used to store data or for memory mapped devices.

6.1 Program Memory

The Program Memory on the W77C032 can be up to 64Kbytes long. All instructions are fetched for execution from this memory area. The MOVC instruction can also access this memory region.

6.2 Data Memory

The W77C032 can access up to 64Kbytes of external Data Memory. This memory region is accessed by the MOVX instructions. Unlike the 8051 derivatives, the W77C032 contains on-chip 1K bytes MOVX SRAM of Data Memory, which can only be accessed by MOVX instructions. These 1K bytes of SRAM are between address 0000H and 03FFH. Access to the on-chip MOVX SRAM is optional under software control. When enabled by software, any MOVX instruction that uses this area will go to the on-chip RAM. MOVX addresses greater than 03FFH automatically go to external memory through Port 0 and 2. When disabled, the 1KB memory area is transparent to the system memory map. Any MOVX directed to the space between 0000H and FFFFH goes to the expanded bus on Port 0 and 2. This is the default condition. In addition, the W77C032 has the standard 256 bytes of on-chip Scratchpad RAM. This can be accessed either by direct addressing or by indirect addressing. There are also some Special Function Registers (SFRs), which can only be accessed by direct addressing. Since the Scratchpad RAM is only 256 bytes, it can be used only when data contents are small. In the event that larger data contents are present, two selections can be used. One is on-chip MOVX SRAM, the other is the external Data Memory. The on-chip MOVX SRAM can only be accessed by a MOVX instruction, the same as that for external Data Memory. However, the on-chip RAM has the fastest access times.

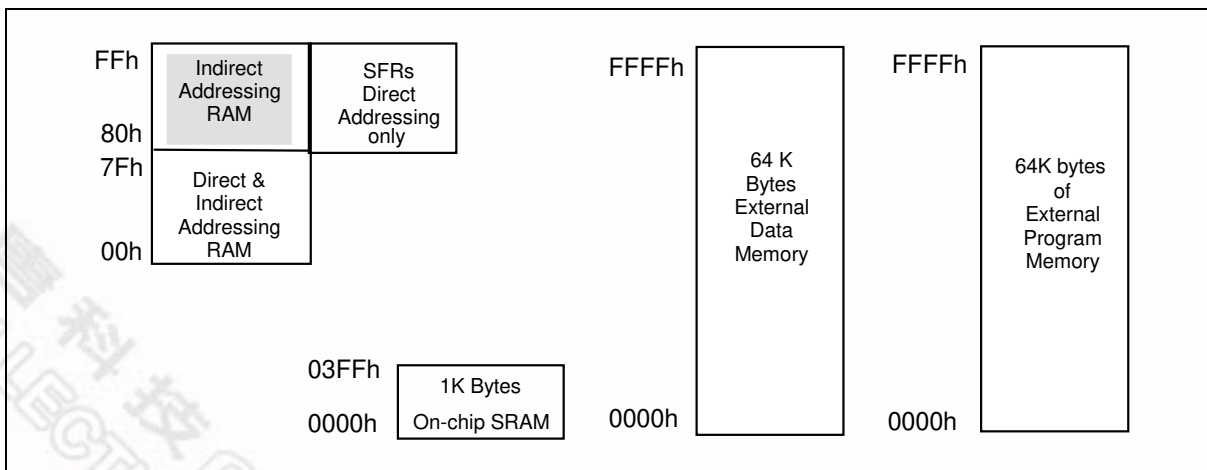


Figure 1. Memory Map

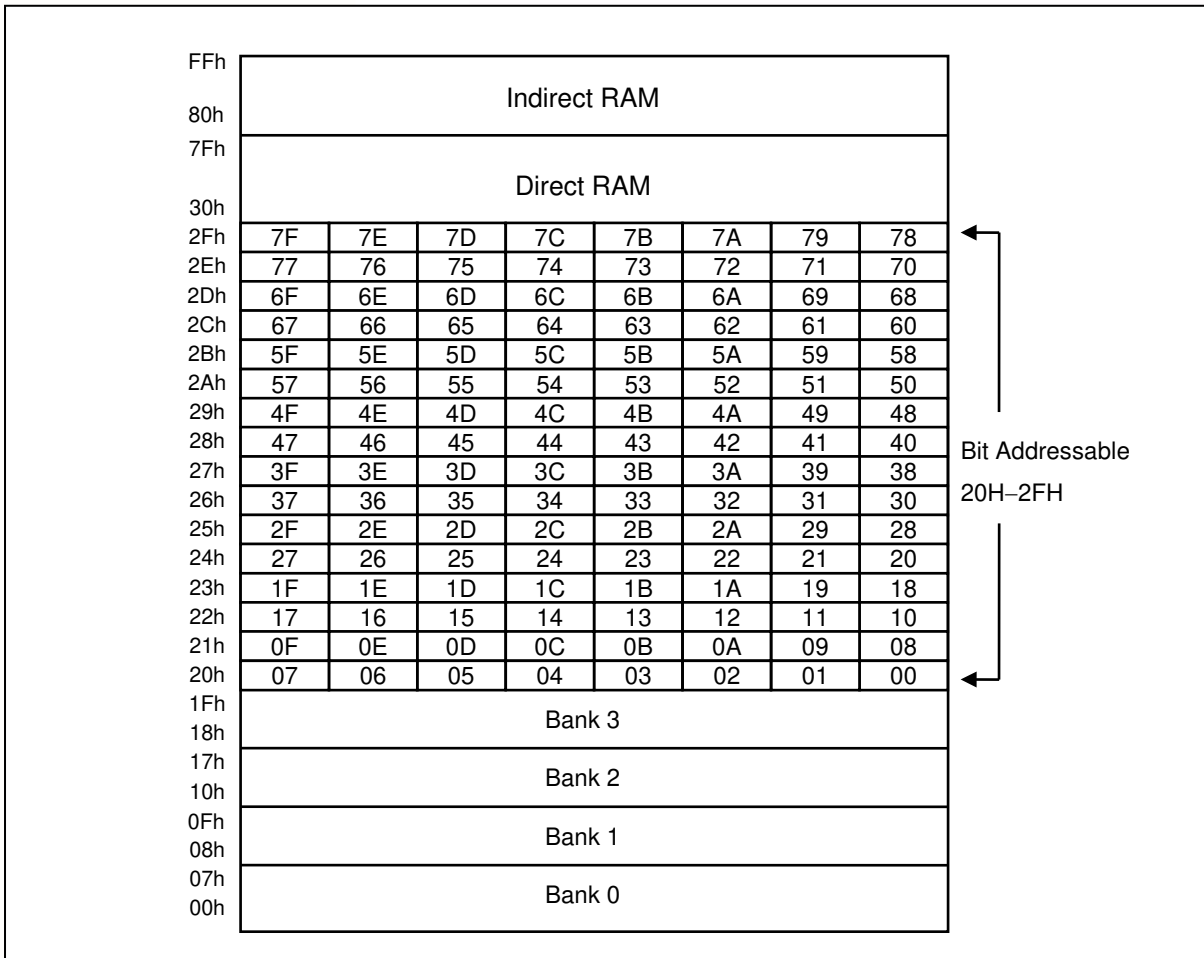


Figure 2. Scratchpad RAM / Register Addressing

7. SPECIAL FUNCTION REGISTERS

The W77C032 uses Special Function Registers (SFRs) to control and monitor peripherals and their Modes.

The SFRs reside in the register locations 80-FFh and are accessed by direct addressing only. Some of the SFRs are bit addressable. This is very useful in cases where one wishes to modify a particular bit without changing the others. The SFRs that are bit addressable are those whose addresses end in 0 or 8. The W77C032 contains all the SFRs present in the standard 8052. However, some additional SFRs have been added. In some cases unused bits in the original 8052 have been given new functions. The list of SFRs is as follows. The table is condensed with eight locations per row. Empty locations indicate that there are no registers at these addresses. When a bit or register is not implemented, it will read high.

Table 1. Special Function Register Location Table

F8	EIP							
F0	B							
E8	EIE							
E0	ACC							
D8	WDCON							
D0	PSW							
C8	T2CON	T2MOD	RCAP2L	RCAP2H	TL2	TH2		
C0	SCON1	SBUF1	ROMMAP		PMR	STATUS		TA
B8	IP	SADEN	SADEN1					
B0	P3							
A8	IE	SADDR	SADDR1					
A0	P2					P4		
98	SCON0	SBUF						
90	P1	EXIF						
88	TCON	TMOD	TL0	TL1	TH0	TH1	CKCON	
80	P0	SP	DPL	DPH	DPL1	DPH1	DPS	PCON

Note: The SFRs in the column with dark borders are bit-addressable.

A brief description of the SFRs now follows.

Port 0

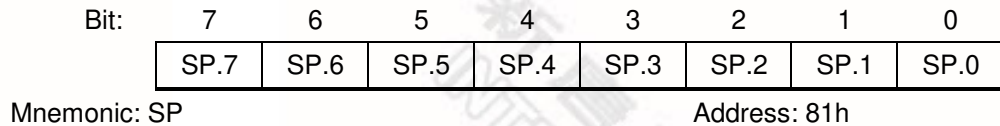
Bit:	7	6	5	4	3	2	1	0
	P0.7	P0.6	P0.5	P0.4	P0.3	P0.2	P0.1	P0.0

Mnemonic: P0

Address: 80h

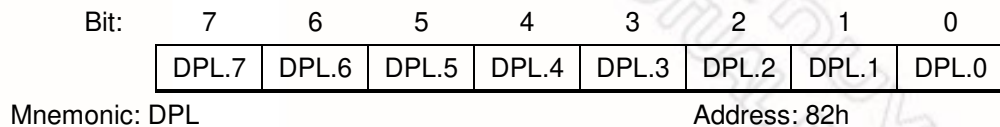
Port 0 is an open-drain bi-directional I/O port. This port also provides a multiplexed low order address/data bus during accesses to external memory.

Stack Pointer



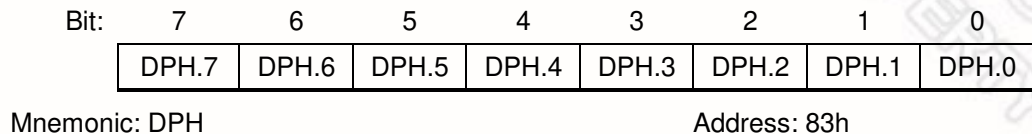
The Stack Pointer stores the Scratchpad RAM address where the stack begins. In other words, it always points to the top of the stack.

Data Pointer Low



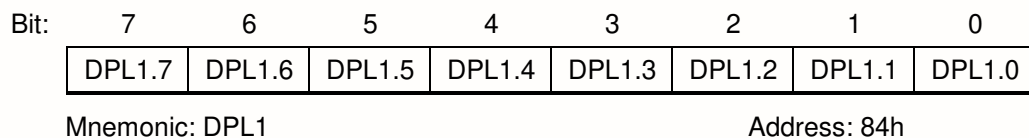
This is the low byte of the standard 8052 16-bit data pointer.

Data Pointer High



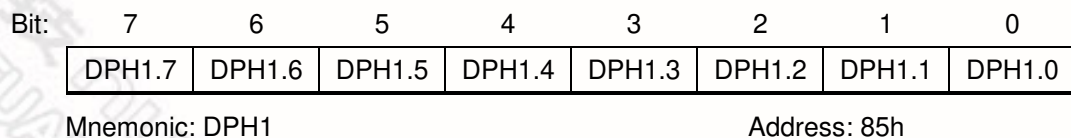
This is the high byte of the standard 8052 16-bit data pointer.

Data Pointer Low1



This is the low byte of the new additional 16-bit data pointer that has been added to the W77C032. The user can switch between DPL, DPH and DPL1, DPH1 simply by setting register DPS = 1. The instructions that use DPTR will now access DPL1 and DPH1 in place of DPL and DPH. If they are not required they can be used as conventional register locations by the user.

Data Pointer High1



This is the high byte of the new additional 16-bit data pointer that has been added to the W77C032. The user can switch between DPL, DPH and DPL1, DPH1 simply by setting register DPS = 1. The instructions that use DPTR will now access DPL1 and DPH1 in place of DPL and DPH. If they are not required they can be used as conventional register locations by the user.

Data Pointer Select

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	-	-	-	DPS.0

Mnemonic: DPS

Address: 86h

DPS.0: This bit is used to select either the DPL, DPH pair or the DPL1, DPH1 pair as the active Data Pointer. When set to 1, DPL1, DPH1 will be selected, otherwise DPL, DPH will be selected.

DPS.1-7: These bits are reserved, but will read 0.

Power Control

Bit:	7	6	5	4	3	2	1	0
	SMOD	SMOD0	-	-	GF1	GF0	PD	IDL

Mnemonic: PCON

Address: 87h

SMOD: This bit doubles the serial port baud rate in mode 1, 2, and 3 when set to 1.

SMOD0: Framing Error Detection Enable: When SMOD0 is set to 1, then SCON.7(SCON1.7) indicates a Frame Error and acts as the FE(FE_1) flag. When SMOD0 is 0, then SCON.7(SCON1.7) acts as per the standard 8052 function.

GF1-0: These two bits are general purpose user flags.

PD: Setting this bit causes the W77C032 to go into the POWER DOWN mode. In this mode all the clocks are stopped and program execution is frozen.

IDL: Setting this bit causes the W77C032 to go into the IDLE mode. In this mode the clocks to the CPU are stopped, so program execution is frozen. But the clock to the serial, timer and interrupt blocks is not stopped, and these blocks continue operating.

Timer Control

Bit:	7	6	5	4	3	2	1	0
	TF1	TR1	TF0	TR0	IE1	IT	IE0	IT

Mnemonic: TCON

Address: 88h

TF1: Timer 1 overflow flag: This bit is set when Timer 1 overflows. It is cleared automatically when the program does a timer 1 interrupt service routine. Software can also set or clear this bit.

TR1: Timer 1 run control: This bit is set or cleared by software to turn timer/counter on or off.

TF0: Timer 0 overflow flag: This bit is set when Timer 0 overflows. It is cleared automatically when the program does a timer 0 interrupt service routine. Software can also set or clear this bit.

TR0: Timer 0 run control: This bit is set or cleared by software to turn timer/counter on or off.

IE1: Interrupt 1 edge detect: Set by hardware when an edge/level is detected on $\overline{INT1}$. This bit is cleared by hardware when the service routine is vectored to only if the interrupt was edge triggered. Otherwise it follows the pin.

IT1: Interrupt 1 type control: Set/cleared by software to specify falling edge/ low level triggered external inputs.

IT0: Interrupt 0 type control: Set/cleared by software to specify falling edge/ low level triggered external inputs.

Bit: 7 6 5 4 3 2 1 0

GATE	C/\bar{T}	M1	M0	GATE	C/\bar{T}	M1	M0
------	-------------	----	----	------	-------------	----	----

TIMER1 TIMER0

Address: 89h

C/ \bar{T} : Timer or Counter Select: When cleared, the timer is incremented by internal clocks. When set, the timer counts high-to-low edges of the Tx pin.

M1	M0	Mode
0	0	Mode 0: 8-bits with 5-bit prescale.
0	1	Mode 1: 16-bits, no prescale.
1	0	Mode 2: 8-bits with auto-reload from THx
1	1	Mode 3: (Timer 0) TL0 is an 8-bit timer/counter controlled by the standard Timer 0 control bits. TH0 is a 8-bit timer only controlled by Timer 1 control bits. (Timer 1) Timer/counter is stopped.

Bit:	7	6	5	4	3	2	1	0
	TL0.7	TL0.6	TL0.5	TL0.4	TL0.3	TL0.2	TL0.1	TL0.0

Address: 8Ah

TL0.7-0: Timer 0 LSB

Timer 1 LSB

Bit:	7	6	5	4	3	2	1	0
	TL1.7	TL1.6	TL1.5	TL1.4	TL1.3	TL1.2	TL1.1	TL1.0

Mnemonic: TL1

Address: 8Bh

TL1.7-0: Timer 1 LSB

Timer 0 MSB

Bit:	7	6	5	4	3	2	1	0
	TH0.7	TH0.6	TH0.5	TH0.4	TH0.3	TH0.2	TH0.1	TH0.0

Mnemonic: TH0

Address: 8Ch

TH0.7-0: Timer 0 MSB

Timer 1 MSB

Bit:	7	6	5	4	3	2	1	0
	TH1.7	TH1.6	TH1.5	TH1.4	TH1.3	TH1.2	TH1.1	TH1.0

Mnemonic: TH1

Address: 8Dh

TH1.7-0: Timer 1 MSB

Clock Control

Bit:	7	6	5	4	3	2	1	0
	WD1	WD0	T2M	T1M	T0M	MD2	MD1	MD0

Mnemonic: CKCON

Address: 8Eh

WD1-0: Watchdog timer mode select bits: These bits determine the time-out period for the watchdog timer. In all four time-out options the reset time-out is 512 clocks more than the interrupt time-out period.

WD1	WD0	Interrupt time-out	Reset time-out
0	0	2^{17}	$2^{17} + 512$
0	1	2^{20}	$2^{20} + 512$
1	0	2^{23}	$2^{23} + 512$
1	1	2^{26}	$2^{26} + 512$

T2M: Timer 2 clock select: When T2M is set to 1, timer 2 uses a divide by 4 clock, and when set to 0 it uses a divide by 12 clock

T1M: Timer 1 clock select: When T1M is set to 1, timer 1 uses a divide by 4 clock, and when set to 0 it uses a divide by 12 clock.

T0M: Timer 0 clock select: When T0M is set to 1, timer 0 uses a divide by 4 clock, and when set to 0 it uses a divide by 12 clock.

MD2-0: Stretch MOVX select bits: These three bits are used to select the stretch value for the MOVX instruction. Using a variable MOVX length enables the user to access slower external memory devices or peripherals without the need for external circuits. The \overline{RD} or \overline{WR} strobe will be stretched by the selected interval. When accessing the on-chip SRAM, the MOVX instruction is always in 2 machine cycles regardless of the stretch setting. By default, the stretch has value of 1. If the user needs faster accessing, then a stretch value of 0 should be selected.

MD2	MD1	MD0	Stretch value	MOVX duration
0	0	0	0	2 machine cycles
0	0	1	1	3 machine cycles (<i>Default</i>)
0	1	0	2	4 machine cycles
0	1	1	3	5 machine cycles
1	0	0	4	6 machine cycles
1	0	1	5	7 machine cycles
1	1	0	6	8 machine cycles
1	1	1	7	9 machine cycles

Port 1

Bit:	7	6	5	4	3	2	1	0
	P1.7	P1.6	P1.5	P1.4	P1.3	P1.2	P1.1	P1.0
Mnemonic: P1	Address: 90h							

P1.7-0: General purpose I/O port. Most instructions will read the port pins in case of a port read access, however in case of read-modify-write instructions, the port latch is read. Some pins also have alternate input or output functions. This alternate functions are described below:

P1.0: T2	External I/O for Timer/Counter 2
P1.1: T2EX	Timer/Counter 2 Capture/Reload Trigger
P1.2: RXD1	Serial Port 1 Receive
P1.3: TXD1	Serial Port 1 Transmit
P1.4: INT2	External Interrupt 2
P1.5: $\overline{INT3}$	External Interrupt 3
P1.6: INT4	External Interrupt 4
P1.7: $\overline{INT5}$	External Interrupt 5

7.1 External Interrupt Flag

Bit:	7	6	5	4	3	2	1	0
	IE5	IE4	IE3	IE2	XT/RG	RGMD	RGSL	BGS

Mnemonic: EXIF Address: 91h

IE5: External Interrupt 5 flag. Set by hardware when a falling edge is detected on $\overline{\text{INT5}}$.

IE4: External Interrupt 4 flag. Set by hardware when a rising edge is detected on INT4.

IE3: External Interrupt 3 flag. Set by hardware when a falling edge is detected on $\overline{\text{INT5}}$.

IE2: External Interrupt 2 flag. Set by hardware when a rising edge is detected on INT2.

XT/ $\overline{\text{RG}}$ RG: Crystal/RC Oscillator Select. Setting this bit selects crystal or external clock as system clock source. Clearing this bit selects the on-chip RC oscillator as clock source. XTUP(STATUS.4) must be set to 1 and XTOFF (PMR.3) must be cleared before this bit can be set. Attempts to set this bit without obeying these conditions will be ignored. This bit is set to 1 after a power-on reset and unchanged by other forms of reset.

RGMD: RC Mode Status. This bit indicates the current clock source of microcontroller. When cleared, CPU is operating from the external crystal or oscillator. When set, CPU is operating from the on-chip RC oscillator. This bit is cleared to 0 after a power-on reset and unchanged by other forms of reset.

RGSL: RC Oscillator Select. This bit selects the clock source following a resume from Power Down Mode. Setting this bit allows device operating from RC oscillator when a resume from Power Down Mode. When this bit is cleared, the device will hold operation until the crystal oscillator has warmed-up following a resume from Power Down Mode. This bit is cleared to 0 after a power-on reset and unchanged by other forms of reset.

Serial Port Control

Bit:	7	6	5	4	3	2	1	0
	SM0/FE	SM1	SM2	REN	TB8	RB8	TI	RI

Mnemonic: SCON Address: 98h

SM0/FE: Serial port 0, Mode 0 bit or Framing Error Flag: The SMOD0 bit in PCON SFR determines whether this bit acts as SM0 or as FE. The operation of SM0 is described below. When used as FE, this bit will be set to indicate an invalid stop bit. This bit must be manually cleared in software to clear the FE condition.

SM1: Serial port Mode bit 1:

SM0	SM1	Mode	Description	Length	Baud rate
0	0	0	Synchronous	8	4/12 Tclk
0	1	1	Asynchronous	10	variable
1	0	2	Asynchronous	11	64/32 Tclk
1	1	3	Asynchronous	11	variable

SM2: Multiple processors communication. Setting this bit to 1 enables the multiprocessor communication feature in mode 2 and 3. In mode 2 or 3, if SM2 is set to 1, then RI will not be activated if the received 9th data bit (RB8) is 0. In mode 1, if SM2 = 1, then RI will not be activated if a valid stop bit was not received. In mode 0, the SM2 bit controls the serial port clock. If set to 0, then the serial port runs at a divide by 12 clock of the oscillator. This gives compatibility with the standard 8052. When set to 1, the serial clock become divide by 4 of the oscillator clock. This results in faster synchronous serial communication.

REN: Receive enable: When set to 1 serial reception is enabled, otherwise reception is disabled.

TB8: This is the 9th bit to be transmitted in modes 2 and 3. This bit is set and cleared by software as desired.

RB8: In modes 2 and 3 this is the received 9th data bit. In mode 1, if SM2 = 0, RB8 is the stop bit that was received. In mode 0 it has no function.

TI: Transmit interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or at the beginning of the stop bit in all other modes during serial transmission. This bit must be cleared by software.

RI: Receive interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or halfway through the stop bits time in the other modes during serial reception. However the restrictions of SM2 apply to this bit. This bit can be cleared only by software

Serial Data Buffer

Bit:	7	6	5	4	3	2	1	0
	SBUF.7	SBUF.6	SBUF.5	SBUF.4	SBUF.3	SBUF.2	SBUF.1	SBUF.0

Mnemonic: SBUF Address: 99h

SBUF.7-0: Serial data on the serial port 0 is read from or written to this location. It actually consists of two separate internal 8-bit registers. One is the receive register, and the other is the transmit buffer. Any read access gets data from the receive data buffer, while write access is to the transmit data buffer.

Port 2

Bit:	7	6	5	4	3	2	1	0
	P2.7	P2.6	P2.5	P2.4	P2.3	P2.2	P2.1	P2.0

Mnemonic: P2 Address: A0h

P2.7-0: Port 2 is a bi-directional I/O port with internal pull-ups. This port also provides the upper address bits for accesses to external memory.

Port 4

Bit:	7	6	5	4	3	2	1	0
	-	-	-	-	P4.3	P4.2	P4.1	P4.0

Mnemonic: P4 Address: A5h

P4.3-0: Port 4 is a bi-directional I/O port with internal pull-ups.

Interrupt Enable

Bit:	7	6	5	4	3	2	1	0
	EA	ES1	ET2	ES	ET1	EX1	ET0	EX0

Mnemonic: IE Address: A8h

EA: Global enable. Enable/disable all interrupts.

ES1: Enable Serial Port 1 interrupt.

ET2: Enable Timer 2 interrupt.

ES: Enable Serial Port 0 interrupt.

ET1: Enable Timer 1 interrupt

EX1: Enable external interrupt 1

ET0: Enable Timer 0 interrupt

EX0: Enable external interrupt 0

Slave Address

Bit:	7	6	5	4	3	2	1	0

Mnemonic: SADDR Address: A9h

SADDR: The SADDR should be programmed to the given or broadcast address for serial port 0 to which the slave processor is designated.

Slave Address 1

Bit:	7	6	5	4	3	2	1	0

Mnemonic: SADDR1 Address: Aah

SADDR1: The SADDR1 should be programmed to the given or broadcast address for serial port 1 to which the slave processor is designated.

Port 3

Bit:	7	6	5	4	3	2	1	0
	P3.7	P3.6	P3.5	P3.4	P3.3	P3.2	P3.1	P3.0

Mnemonic: P3 Address: B0h



P3.7-0: General purpose I/O port. Each pin also has an alternate input or output function. The alternate functions are described below.

P3.7	\overline{RD}	Strobe for read from external RAM
P3.6	\overline{WR}	Strobe for write to external RAM
P3.5	T1	Timer/counter 1 external count input
P3.4	T0	Timer/counter 0 external count input
P3.3	$\overline{INT1}$	External interrupt 1
P3.2	$\overline{INT0}$	External interrupt 0
P3.1	TxD	Serial port 0 output
P3.0	RxD	Serial port 0 input

Interrupt Priority

Bit:	7	6	5	4	3	2	1	0
	-	PS1	PT2	PS	PT1	PX1	PT0	PX0

Mnemonic: IP Address: B8h

IP.7: This bit is un-implemented and will read high.

PS1: This bit defines the Serial port 1 interrupt priority.

PT2: This bit defines the Timer 2 interrupt priority.

PS: This bit defines the Serial port 0 interrupt priority.

PT1: This bit defines the Timer 1 interrupt priority.

PX1: This bit defines the External interrupt 1 priority.

PT0: This bit defines the Timer 0 interrupt priority.

PX0: This bit defines the External interrupt 0 priority.

PS = 1 sets it to higher priority level.

PT2 = 1 sets it to higher priority level.

PS = 1 sets it to higher priority level.

PT1 = 1 sets it to higher priority level.

PX1 = 1 sets it to higher priority level.

PT0 = 1 sets it to higher priority level.

PX0 = 1 sets it to higher priority level.

Slave Address Mask Enable

Bit:	7	6	5	4	3	2	1	0

Mnemonic: SADEN Address: B9h

SADEN: This register enables the Automatic Address Recognition feature of the Serial port 0. When a bit in the SADEN is set to 1, the same bit location in SADDR will be compared with the incoming serial data. When SADEN.n is 0, then the bit becomes a "don't care" in the comparison. This register enables the Automatic Address Recognition feature of the Serial port 0. When all the bits of SADEN are 0, interrupt will occur for any incoming address.

Slave Address Mask Enable 1

Bit:	7	6	5	4	3	2	1	0

Mnemonic: SADEN1 Address: Bah

SADEN1: This register enables the Automatic Address Recognition feature of the Serial port 1. When a bit in the SADEN1 is set to 1, the same bit location in SADDR1 will be compared with the incoming serial data. When SADEN1.n is 0, then the bit becomes a "don't care" in the

comparison. This register enables the Automatic Address Recognition feature of the Serial port 1. When all the bits of SADEN1 are 0, interrupt will occur for any incoming address.

Serial Port Control 1

Bit:	7	6	5	4	3	2	1	0
	SM0_1/FE_1	SM1_1	SM2_1	REN_1	TB8_1	RB8_1	TI_1	RI_1

Mnemonic: SCON1

Address: C0h

SM0_1/FE_1: Serial port 1, Mode 0 bit or Framing Error Flag 1: The SMOD0 bit in PCON SFR determines whether this bit acts as SM0_1 or as FE_1. the operation of SM0_1 is described below. When used as FE_1, this bit will be set to indicate an invalid stop bit. This bit must be manually cleared in software to clear the FE_1 condition.

SM1_1: Serial port 1 Mode bit 1:

SM0_1	SM1_1	Mode	Description	Length	Baud rate
0	0	0	Synchronous	8	4/12 Tclk
0	1	1	Asynchronous	10	variable
1	0	2	Asynchronous	11	64/32 Tclk
1	1	3	Asynchronous	11	variable

SM2_1: Multiple processors communication. Setting this bit to 1 enables the multiprocessor communication feature in mode 2 and 3. In mode 2 or 3, if SM2_1 is set to 1, then RI_1 will not be activated if the received 9th data bit (RB8_1) is 0. In mode 1, if SM2_1 = 1, then RI_1 will not be activated if a valid stop bit was not received. In mode 0, the SM2_1 bit controls the serial port 1 clock. If set to 0, then the serial port 1 runs at a divide by 12 clock of the oscillator. This gives compatibility with the standard 8052. When set to 1, the serial clock become divide by 4 of the oscillator clock. This results in faster synchronous serial communication.

REN_1: Receive enable: When set to 1 serial reception is enabled, otherwise reception is disabled.

TB8_1: This is the 9th bit to be transmitted in modes 2 and 3. This bit is set and cleared by software as desired.

RB8_1: In modes 2 and 3 this is the received 9th data bit. In mode 1, if SM2_1 = 0, RB8_1 is the stop bit that was received. In mode 0 it has no function.

TI_1: Transmit interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or at the beginning of the stop bit in all other modes during serial transmission. This bit must be cleared by software.

RI_1: Receive interrupt flag: This flag is set by hardware at the end of the 8th bit time in mode 0, or halfway through the stop bits time in the other modes during serial reception. However the restrictions of SM2_1 apply to this bit. This bit can be cleared only by software

Serial Data Buffer 1

Bit:	7	6	5	4	3	2	1	0
	SBUF1.7	SBUF1.6	SBUF1.5	SBUF1.4	SBUF1.3	SBUF1.2	SBUF1.1	SBUF1.0

Mnemonic: SBUF1

Address: C1h

SBUF1.7-0: Serial data of the serial port 1 is read from or written to this location. It actually consists of two separate 8-bit registers. One is the receive register, and the other is the transmit

buffer. Any read access gets data from the receive data buffer, while write accesses are to the transmit data buffer.

ROMMAP

Bit:	7	6	5	4	3	2	1	0
	WS	1	-	-	-	-	-	-

Mnemonic: ROMMAP

Address: C2h

WS: Wait State Signal Enable. Setting this bit enables the $\overline{\text{WAIT}}$ signal on P4.0. The device will sample the wait state control signal $\overline{\text{WAIT}}$ via P4.0 during MOVX instruction. This bit is time access protected

Power Management Register

Bit:	7	6	5	4	3	2	1	0
	CD1	CD0	SWB	-	XTOFF	ALE-OFF	-	DME0

Mnemonic: PMR

Address: C4h

CD1, CD0: Clock Divide Control. These bit selects the number of clocks required to generate one machine cycle. There are three modes including divide by 4, 64 or 1024. Switching between modes must first go back divide by 4 mode. For instance, to go from 64 to 1024 clocks/machine cycle the device must first go from 64 to 4 clocks/machine cycle, and then from 4 to 1024 clocks/machine cycle.

CD1,	CD0	Clocks/machine cycle
0	0	Reserved
0	1	4
1	0	64
1	1	1024

SWB: Switchback Enable. Setting this bit allows an enabled external interrupt or serial port activity to force the CD1,CD0 to divide by 4 state (0,1). The device will switch modes at the start of the jump to interrupt service routine while a external interrupt is enabled and actually recongnized by microcontroller. While a serial port reception, the switchback occurs at the start of the instruction following the falling edge of the start bit.

XTOFF: Crystal Oscillator Disable. Setting this bit disables the external crystal oscillator. This bit can only be set to 1 while the microcontroller is operating from the RC oscillator. Clearing this bit restarts the crystal oscillator, the XTUP (STATUS.4) bit will be set after crystal oscillator warmed-up has completed.

ALEOFF: This bit disables the expression of the ALE signal on the device pin during all on-board program and data memory accesses. External memory accesses will automatically enable ALE independent of ALEOFF.

0 = ALE expression is enable; 1 = ALE expression is disable

DME0: This bit determines the on-chip MOVX SRAM to be enabled or disabled.
Set this bit to 1 will enable the on-chip 1KB MOVX SRAM.

Status Register

Bit:	7	6	5	4	3	2	1	0
	-	HIP	LIP	XTUP	SPTA1	SPRA1	SPTA0	SPRA0

Mnemonic: STATUS

Address: C5h

HIP: High Priority Interrupt Status. When set, it indicates that software is servicing a high priority interrupt. This bit will be cleared when the program executes the corresponding RETI instruction.

LIP: Low Priority Interrupt Status. When set, it indicates that software is servicing a low priority interrupt. This bit will be cleared when the program executes the corresponding RETI instruction.

XTUP: Crystal Oscillator Warm-up Status. When set, this bit indicates CPU has detected clock to be ready. Each time the crystal oscillator is restarted by exit from power down mode or the XT0FF bit is set, hardware will clear this bit. This bit is set to 1 after a power-on reset. When this bit is cleared, it prevents software from setting the XT/RG bit to enable CPU operation from crystal oscillator.

SPTA1: Serial Port 1 Transmit Activity. This bit is set during serial port 1 is currently transmitting data. It is cleared when TI_1 bit is set by hardware. Changing the Clock Divide Control bits CD0, CD1 will be ignored when this bit is set to 1 and SWB = 1.

SPRA1: Serial Port 1 Receive Activity. This bit is set during serial port 1 is currently receiving a data. It is cleared when RI_1 bit is set by hardware. Changing the Clock Divide Control bits CD0, CD1 will be ignored when this bit is set to 1 and SWB = 1.

SPTA0: Serial Port 0 Transmit Activity. This bit is set during serial port 0 is currently transmitting data. It is cleared when TI bit is set by hardware. Changing the Clock Divide Control bits CD0, CD1 will be ignored when this bit is set to 1 and SWB = 1.

SPRA0: Serial Port 0 Receive Activity. This bit is set during serial port 0 is currently receiving a data. It is cleared when RI bit is set by hardware. Changing the Clock Divide Control bits CD0, CD1 will be ignored when this bit is set to 1 and SWB = 1.

Timed Access

Bit:	7	6	5	4	3	2	1	0
	TA.7	TA.6	TA.5	TA.4	TA.3	TA.2	TA.1	TA.0

Mnemonic: TA

Address: C7h

TA: The Timed Access register controls the access to protected bits. To access protected bits, the user must first write AAH to the TA. This must be immediately followed by a write of 55H to TA. Now a window is opened in the protected bits for three machine cycles, during which the user can write to these bits.

Timer 2 Control

Bit:	7	6	5	4	3	2	1	0
	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	C/T ₂	CP/RL ₂

Mnemonic: T2CON

Address: C8h

TF2: Timer 2 overflow flag: This bit is set when Timer 2 overflows. It is also set when the count is equal to the capture register in down count mode. It can be set only if RCLK and TCLK are both 0. It is cleared only by software. Software can also set or clear this bit.

- EXF2:** Timer 2 External Flag: A negative transition on the T2EX pin (P1.1) or timer 2 overflow will cause this flag to set based on the $\overline{CP/RL2}$, EXEN2 and DCEN bits. If set by a negative transition, this flag must be cleared by software. Setting this bit in software or detection of a negative transition on T2EX pin will force a timer interrupt if enabled.
- RCLK:** Receive Clock Flag: This bit determines the serial port 0 time-base when receiving data in serial modes 1 or 3. If it is 0, then timer 1 overflow is used for baud rate generation, otherwise timer 2 overflow is used. Setting this bit forces timer 2 in baud rate generator mode.
- TCLK:** Transmit Clock Flag: This bit determines the serial port 0 time-base when transmitting data in modes 1 and 3. If it is set to 0, the timer 1 overflow is used to generate the baud rate clock, otherwise timer 2 overflow is used. Setting this bit forces timer 2 in baud rate generator mode.
- EXEN2:** Timer 2 External Enable. This bit enables the capture/reload function on the T2EX pin if Timer 2 is not generating baud clocks for the serial port. If this bit is 0, then the T2EX pin will be ignored, otherwise a negative transition detected on the T2EX pin will result in capture or reload.
- TR2:** Timer 2 Run Control. This bit enables/disables the operation of timer 2. Clearing this bit will halt the timer 2 and preserve the current count in TH2, TL2.
- C/ $\overline{T2}$:** Counter/Timer Select. This bit determines whether timer 2 will function as a timer or a counter. Independent of this bit, the timer will run at 2 clocks per tick when used in baud rate generator mode. If it is set to 0, then timer 2 operates as a timer at a speed depending on T2M bit (CKCON.5), otherwise it will count negative edges on T2 pin.
- $\overline{CP/RL2}$:** Capture/Reload Select. This bit determines whether the capture or reload function will be used for timer 2. If either RCLK or TCLK is set, this bit will be ignored and the timer will function in an auto-reload mode following each overflow. If the bit is 0 then auto-reload will occur when timer 2 overflows or a falling edge is detected on T2EX pin if EXEN2 = 1. If this bit is 1, then timer 2 captures will occur when a falling edge is detected on T2EX pin if EXEN2 = 1.

7.2 Timer 2 Mode Control

Bit:	7	6	5	4	3	2	1	0
	HC5	HC4	HC3	HC2	T2CR	-	T2OE	DCEN

Mnemonic: T2MOD

Address: C9h

- HC5:** Hardware Clear $\overline{INT5}$ flag. Setting this bit allows the flag of external interrupt 5 to be automatically cleared by hardware while entering the interrupt service routine.
- HC4:** Hardware Clear INT4 flag. Setting this bit allows the flag of external interrupt 4 to be automatically cleared by hardware while entering the interrupt service routine.
- HC3:** Hardware Clear $\overline{INT3}$ flag. Setting this bit allows the flag of external interrupt 3 to be automatically cleared by hardware while entering the interrupt service routine.
- HC2:** Hardware Clear INT2 flag. Setting this bit allows the flag of external interrupt 2 to be automatically cleared by hardware while entering the interrupt service routine.
- T2CR:** Timer 2 Capture Reset. In the Timer 2 Capture Mode this bit enables/disables hardware automatically reset Timer 2 while the value in TL2 and TH2 have been transferred into the capture register.
- T2OE:** Timer 2 Output Enable. This bit enables/disables the Timer 2 clock out function.

DCEN: Down Count Enable: This bit, in conjunction with the T2EX pin, controls the direction that timer 2 counts in 16-bit auto-reload mode.

7.2.1 Timer 2 Capture LSB

Bit:	7	6	5	4	3	2	1	0
	RCAP2L.7	RCAP2L.6	RCAP2L.5	RCAP2L.4	RCAP2L.3	RCAP2L.2	RCAP2L.1	RCAP2L.0

Mnemonic: RCAP2L

Address: Cah

RCAP2L: This register is used to capture the TL2 value when a timer 2 is configured in capture mode. RCAP2L is also used as the LSB of a 16-bit reload value when timer 2 is configured in auto-reload mode.

Timer 2 Capture MSB

Bit:	7	6	5	4	3	2	1	0
	RCAP2H.7	RCAP2H.6	RCAP2H.5	RCAP2H.4	RCAP2H.3	RCAP2H.2	RCAP2H.1	RCAP2H.0

Mnemonic: RCAP2H

Address: CBh

RCAP2H: This register is used to capture the TH2 value when a timer 2 is configured in capture mode. RCAP2H is also used as the MSB of a 16-bit reload value when timer 2 is configured in auto-reload mode.

Timer 2 LSB

Bit:	7	6	5	4	3	2	1	0
	TL2.7	TL2.6	TL2.5	TL2.4	TL2.3	TL2.2	TL2.1	TL2.0

Mnemonic: TL2

Address: CCh

TL2: Timer 2 LSB

Timer 2 MSB

Bit:	7	6	5	4	3	2	1	0
	TH2.7	TH2.6	TH2.5	TH2.4	TH2.3	TH2.2	TH2.1	TH2.0

Mnemonic: TH2

Address: CDh

TH2: Timer 2 MSB

Program Status Word

Bit:	7	6	5	4	3	2	1	0
	CY	AC	F0	RS1	RS0	OV	F1	P

Mnemonic: PSW

Address: D0h

CY: Carry flag: Set for an arithmetic operation which results in a carry being generated from the ALU. It is also used as the accumulator for the bit operations.

AC: Auxiliary carry: Set when the previous operation resulted in a carry from the high order nibble.

F0: User flag 0: General purpose flag that can be set or cleared by the user.

RS.1-0: Register bank select bits:

RS1	RS0	Register bank	Address
0	0	0	00-07h
0	1	1	08-0Fh
1	0	2	10-17h
1	1	3	18-1Fh

OV: Overflow flag: Set when a carry was generated from the seventh bit but not from the 8th bit as a result of the previous operation, or vice-versa.

F1: User Flag 1: General purpose flag that can be set or cleared by the user by software

P: Parity flag: Set/cleared by hardware to indicate odd/even number of 1's in the accumulator.

Watchdog Control

Bit:	7	6	5	4	3	2	1	0
	SMOD_1	POR	-	-	WDIF	WTRF	EWT	RWT

Mnemonic: WDCON

Address: D8h

SMOD_1: This bit doubles the Serial Port 1 baud rate in mode 1, 2, and 3 when set to 1.

POR: Power-on reset flag. Hardware will set this flag on a power up condition. This flag can be read or written by software. A write by software is the only way to clear this bit once it is set.

WDIF: Watchdog Timer Interrupt Flag. If the watchdog interrupt is enabled, hardware will set this bit to indicate that the watchdog interrupt has occurred. If the interrupt is not enabled, then this bit indicates that the time-out period has elapsed. This bit must be cleared by software.

WTRF: Watchdog Timer Reset Flag. Hardware will set this bit when the watchdog timer causes a reset. Software can read it but must clear it manually. A power-fail reset will also clear the bit. This bit helps software in determining the cause of a reset. If EWT = 0, the watchdog timer will have no affect on this bit.

EWT: Enable Watchdog timer Reset. Setting this bit will enable the Watchdog timer Reset function.

RWT: Reset Watchdog Timer. This bit helps in putting the watchdog timer into a know state. It also helps in resetting the watchdog timer before a time-out occurs. Failing to set the RWT before time-out will cause an interrupt, if EWDI (EIE.4) is set, and 512 clocks after that a watchdog timer reset will be generated if EWT is set. This bit is self-clearing by hardware.

The WDCON SFR is set to a 0x0x0xx0b on an external reset. WTRF is set to a 1 on a Watchdog timer reset, but to a 0 on power on/down resets. WTRF is not altered by an external reset. POR is set to 1 by a power-on reset. EWT is set to 0 on a Power-on reset and unaffected by other resets.

All the bits in this SFR have unrestricted read access. POR, EWT, WDIF and RWT require Timed Access procedure to write. The remaining bits have unrestricted write accesses.