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XMC1100

Microcontroller Series
for Industrial Applications

XMC1000 Family

ARM® Cortex™-M0
32-bit processor core

Data Sheet

V1.4 2014-05

Microcontrollers

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Revision History: V1.4 2014-05

Previous Version: V1.3	
Page	Subjects
Page 10	ADC channels of Table 2 is updated. Table 3 is added.
Page 10	Description for Chip Identification Number of Section 1.4 is updated.
Page 17	The pad type is corrected for P1.6 in Table 6.
Page 29	The t_{C12} , f_{C12}, t_{C10}, f_{C10}, t_{C8} and f_{C8} parameters are updated in Table 12.
Page 32	Figure 8 is added.
Page 33	The t_{SR} and t_{TSAL} parameters are updated in Table 13.
Page 36	Parameter name for t_{PSER} is updated. The $N_{WSFLASH}$ parameter and test condition for t_{RET} are added to Table 16.
Page 39	The min value for V_{DDPBO} parameter is added to Table 18. Footnote 1 is updated.
Page 41	The Δf_{LTT} parameter is added to Table 19.
Page 47	Figure 13 is added.

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About this Document

This Data Sheet is addressed to embedded hardware and software developers. It provides the reader with detailed descriptions about the ordering designations, available features, electrical and physical characteristics of the XMC1100 series devices.

The document describes the characteristics of a superset of the XMC1100 series devices. For simplicity, the various device types are referred to by the collective term XMC1100 throughout this document.

XMC1000 Family User Documentation

The set of user documentation includes:

- **Reference Manual**
  - decribes the functionality of the superset of devices.
- **Data Sheets**
  - list the complete ordering designations, available features and electrical characteristics of derivative devices.
- **Errata Sheets**
  - list deviations from the specifications given in the related Reference Manual or Data Sheets. Errata Sheets are provided for the superset of devices.

Attention: Please consult all parts of the documentation set to attain consolidated knowledge about your device.

Application related guidance is provided by **Users Guides** and **Application Notes**.

Please refer to **http://www.infineon.com/xmc1000** to get access to the latest versions of those documents.

1 Summary of Features

The XMC1100 devices are members of the XMC1000 family of microcontrollers based on the ARM Cortex-M0 processor core. The XMC1100 series devices are designed for general purpose applications.

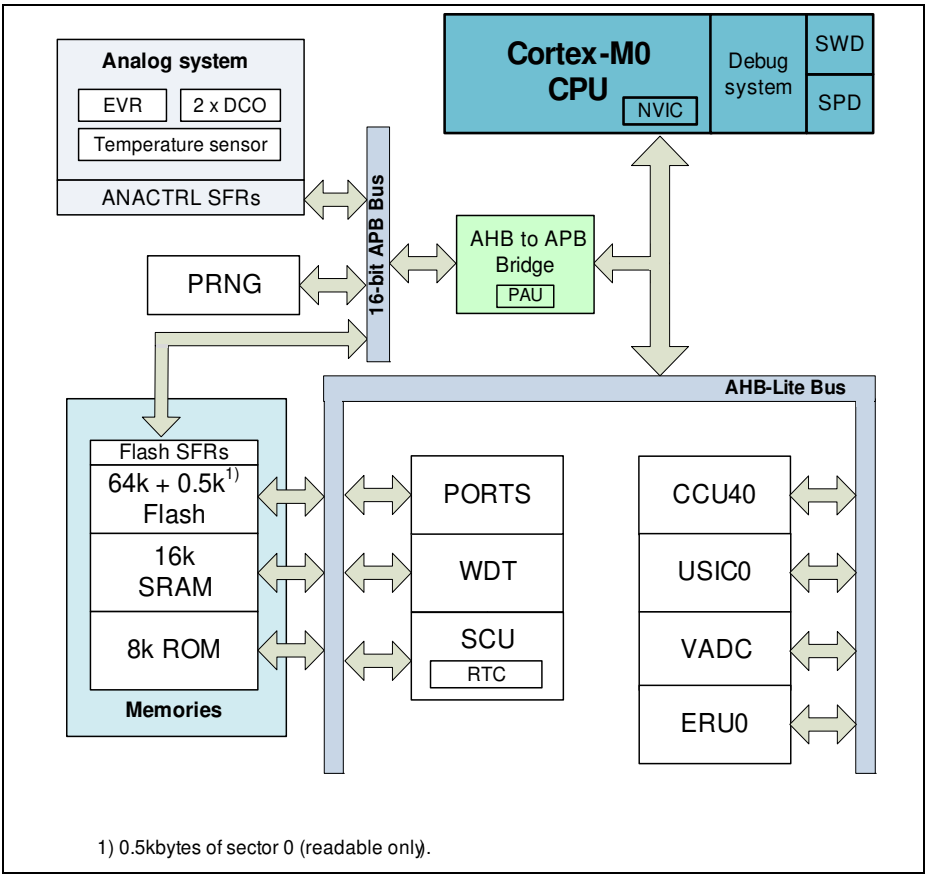

Figure 1 System Block Diagram

CPU Subsystem

- CPU Core
  - High Performance 32-bit ARM Cortex-M0 CPU
  - Most of 16-bit Thumb instruction set
  - Subset of 32-bit Thumb2 instruction set

  - High code density with 32-bit performance
  - Single cycle 32-bit hardware multiplier
  - System timer (SysTick) for Operating System support
  - Ultra low power consumption
- Nested Vectored Interrupt Controller (NVIC)
- Event Request Unit (ERU) for programmable processing of external and internal service requests

On-Chip Memories

- 8 kbytes on-chip ROM
- 16 kbytes on-chip high-speed SRAM
- up to 64 kbytes on-chip Flash program and data memory

On-Chip Peripherals

- Two Universal Serial Interface Channels (USIC), usable as UART, double-SPI, quad-SPI, IIC, IIS and LIN interfaces
- A/D Converters, up to 12 channels, includes a 12-bit analog to digital converter
- Capture/Compare Units 4 (CCU4) for use as general purpose timers
- Window Watchdog Timer (WDT) for safety sensitive applications
- Real Time Clock module with alarm support (RTC)
- System Control Unit (SCU) for system configuration and control
- Pseudo random number generator (PRNG), provides random data with fast generation times
- Temperature Sensor (TSE)

Input/Output Lines

- Programmable port driver control module (PORTS)
- Individual bit addressability
- Tri-stated in input mode
- Push/pull or open drain output mode
- Configurable pad hysteresis

On-Chip Debug Support

- Support for debug features: 4 breakpoints, 2 watchpoints
- Various interfaces: ARM serial wire debug (SWD), single pin debug (SPD)

1.1 Ordering Information

The ordering code for an Infineon microcontroller provides an exact reference to a specific product. The code “XMC1<DDD>-<Z><PPP><T><FFFF>” identifies:

- <DDD> the derivatives function set

- <Z> the package variant
  - T: TSSOP
  - Q: VQFN
- <PPP> package pin count
- <T> the temperature range:
  - F: -40°C to 85°C
  - X: -40°C to 105°C
- <FFFF> the Flash memory size.

For ordering codes for the XMC1100 please contact your sales representative or local distributor.

This document describes several derivatives of the XMC1100 series, some descriptions may not apply to a specific product. Please see **Table 1**.

For simplicity the term **XMC1100** is used for all derivatives throughout this document.

1.2 Device Types

These device types are available and can be ordered through Infineon's direct and/or distribution channels.

Table 1 Synopsis of XMC1100 Device Types

Derivative	Package	Flash Kbytes	SRAM Kbytes
XMC1100-T016F0008	PG-TSSOP-16-8	8	16
XMC1100-T016F0016	PG-TSSOP-16-8	16	16
XMC1100-T016F0032	PG-TSSOP-16-8	32	16
XMC1100-T016F0064	PG-TSSOP-16-8	64	16
XMC1100-T016X0064	PG-TSSOP-16-8	64	16
XMC1100-T038F0016	PG-TSSOP-38-9	16	16
XMC1100-T038F0032	PG-TSSOP-38-9	32	16
XMC1100-T038F0064	PG-TSSOP-38-9	64	16
XMC1100-T038X0064	PG-TSSOP-38-9	64	16
XMC1100-Q024F0008	PG-VQFN-24-19	8	16
XMC1100-Q024F0016	PG-VQFN-24-19	16	16
XMC1100-Q024F0032	PG-VQFN-24-19	32	16
XMC1100-Q024F0064	PG-VQFN-24-19	64	16
XMC1100-Q040F0016	PG-VQFN-40-13	16	16

Table 1 Synopsis of XMC1100 Device Types (cont'd)

Derivative	Package	Flash Kbytes	SRAM Kbytes
XMC1100-Q040F0032	PG-VQFN-40-13	32	16
XMC1100-Q040F0064	PG-VQFN-40-13	64	16

1.3 Device Type Features

The following table lists the available features per device type.

Table 2 Features of XMC1100 Device Types[1)]

Derivative	ADC channel
XMC1100-T016	6
XMC1100-T038	12
XMC1100-Q024	8
XMC1100-Q040	12

1) Features that are not included in this table are available in all the derivatives

Table 3 ADC Channels

Package	VADC0 G0	VADC0 G1
PG-TSSOP-16	CH0..CH5	–
PG-TSSOP-38	CH0..CH7	CH1, CH5 .. CH7
PG-VQFN-24	CH0..CH7	–
PG-VQFN-40	CH0..CH7	CH1, CH5 .. CH7

1.4 Chip Identification Number

The Chip Identification Number allows software to identify the marking. It is a 8 words value with the most significant 7 words stored in Flash configuration sector 0 (CS0) at address location : 1000 $0F00_H$ (MSB) - 1000 $0F1B_H$ (LSB). The least significant word and most significant word of the Chip Identification Number are the value of registers DBGROMID and IDCHIP, respectively.

Table 4 XMC1100 **Chip Identification Number**

Derivative	Value	Marking
XMC1100-T016F0008	00011032 01CF00FF 00001F37 00000000 00000B00 00001000 00003000 101ED083$_H$	AA
XMC1100-T016F0016	00011032 01CF00FF 00001F37 00000000 00000B00 00001000 00005000 101ED083$_H$	AA
XMC1100-T016F0032	00011032 01CF00FF 00001F37 00000000 00000B00 00001000 00009000 101ED083$_H$	AA
XMC1100-T016F0064	00011032 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA
XMC1100-T016X0064	00011033 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA
XMC1100-T038F0016	00011012 01CF00FF 00001F37 00000000 00000B00 00001000 00005000 101ED083$_H$	AA
XMC1100-T038F0032	00011012 01CF00FF 00001F37 00000000 00000B00 00001000 00009000 101ED083$_H$	AA
XMC1100-T038F0064	00011012 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA
XMC1100-T038X0064	00011013 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA
XMC1100-Q024F0008	00011062 01CF00FF 00001F37 00000000 00000B00 00001000 00003000 101ED083$_H$	AA
XMC1100-Q024F0016	00011062 01CF00FF 00001F37 00000000 00000B00 00001000 00005000 101ED083$_H$	AA
XMC1100-Q024F0032	00011062 01CF00FF 00001F37 00000000 00000B00 00001000 00009000 101ED083$_H$	AA
XMC1100-Q024F0064	00011062 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA
XMC1100-Q040F0016	00011042 01CF00FF 00001F37 00000000 00000B00 00001000 00005000 101ED083$_H$	AA
XMC1100-Q040F0032	00011042 01CF00FF 00001F37 00000000 00000B00 00001000 00009000 101ED083$_H$	AA
XMC1100-Q040F0064	00011042 01CF00FF 00001F37 00000000 00000B00 00001000 00011000 101ED083$_H$	AA

2 General Device Information

This section summarizes the logic symbols and package pin configurations with a detailed list of the functional I/O mapping.

2.1 Logic Symbols

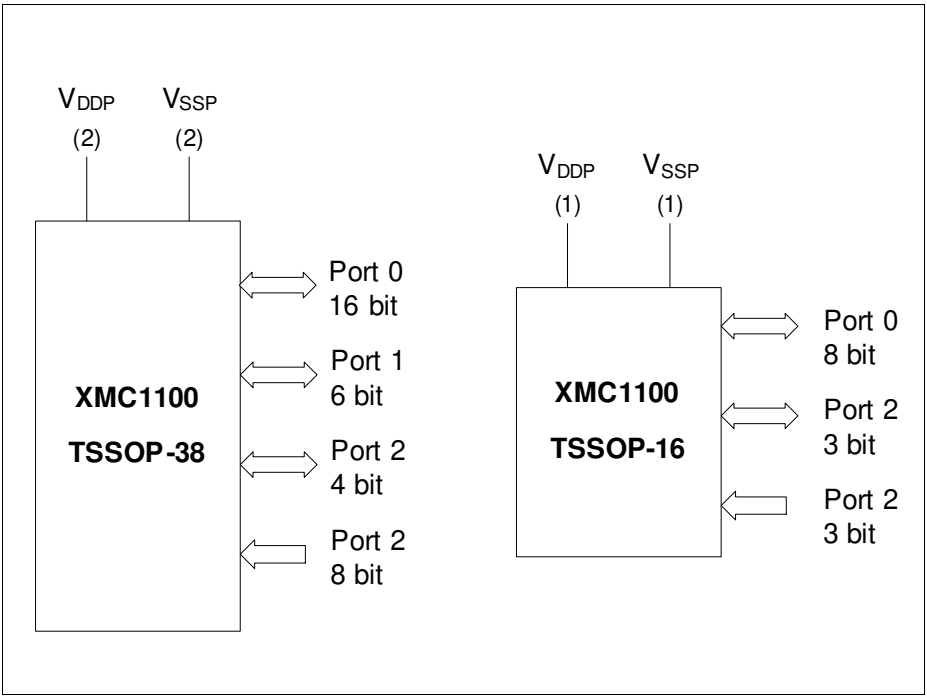

Figure 2 XMC1100 Logic Symbol for TSSOP-38 and TSSOP-16

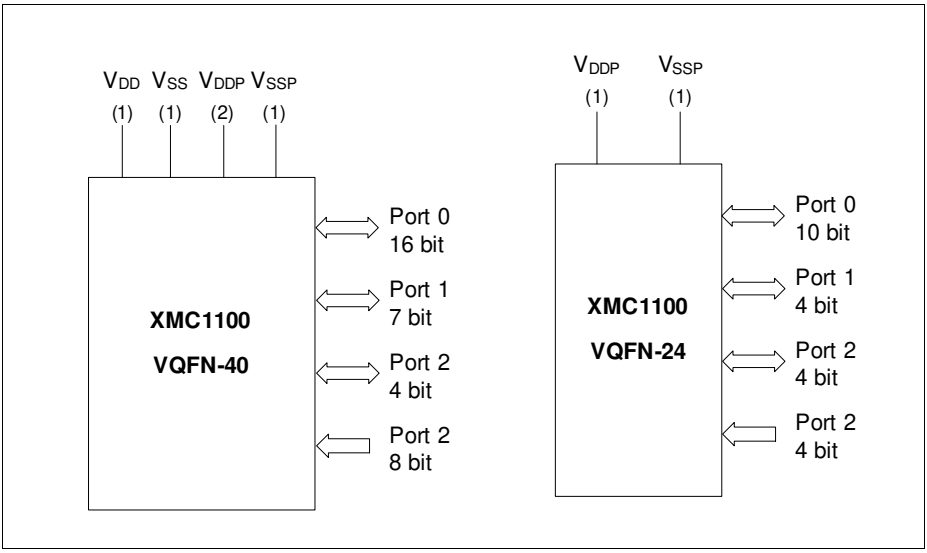

Figure 3 XMC1100 Logic Symbol for VQFN-24 and VQFN-40

2.2 Pin Configuration and Definition

The following figures summarize all pins, showing their locations on the different packages.

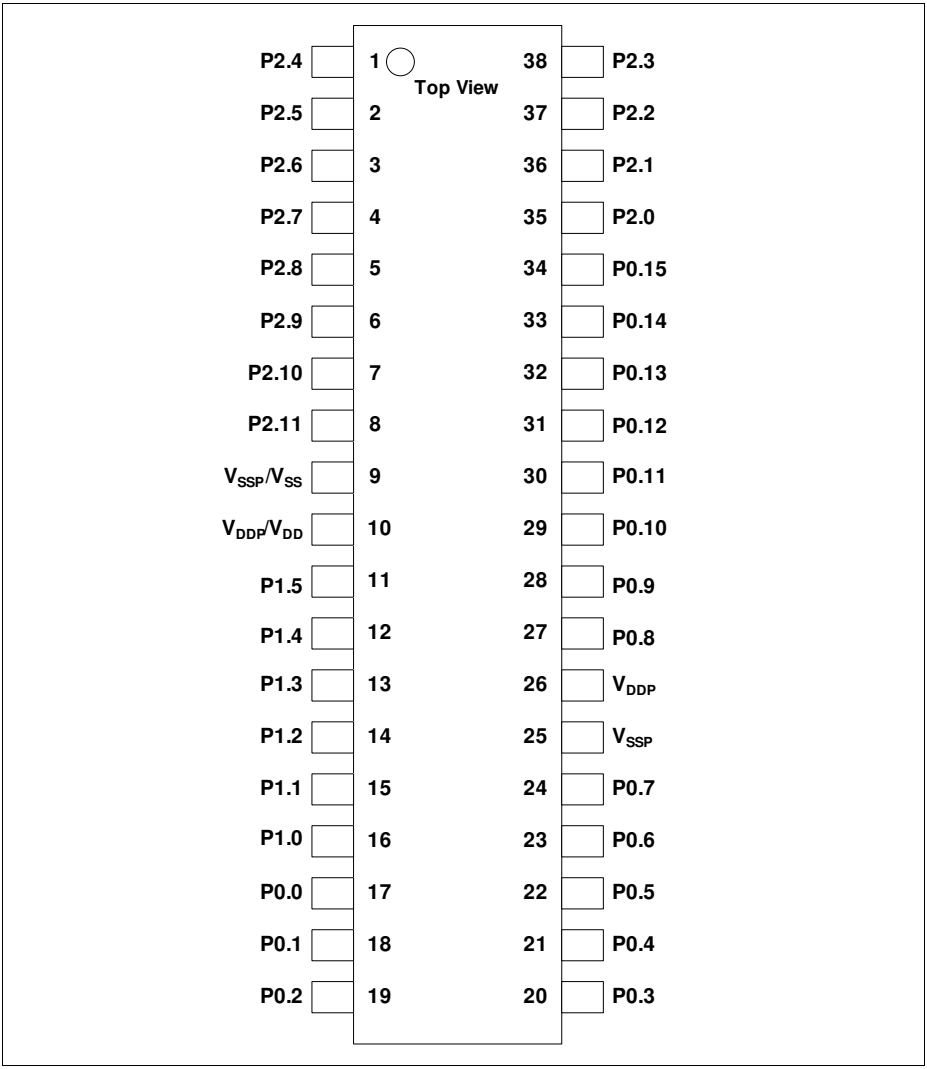

Figure 4 XMC1100 **PG-TSSOP-38 Pin Configuration** (top view)

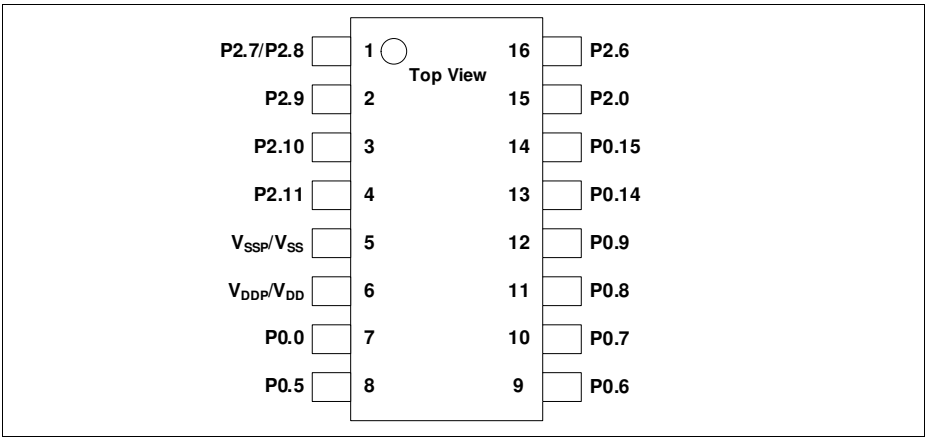

Figure 5 XMC1100 **PG-TSSOP-16 Pin Configuration** (top view)

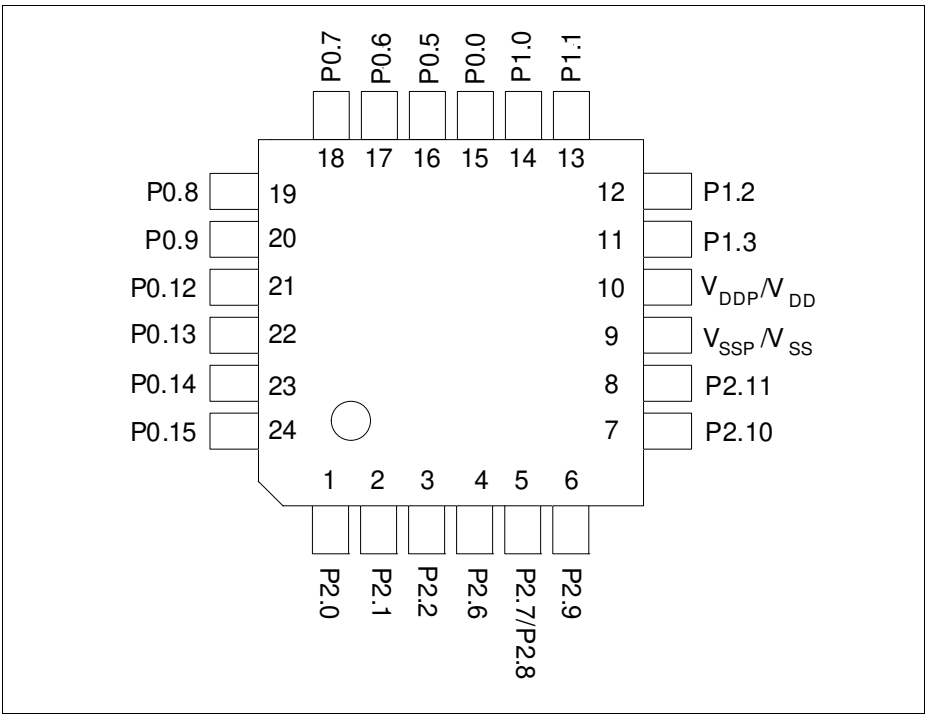

Figure 6 XMC1100 **PG-VQFN-24 Pin Configuration** (top view)

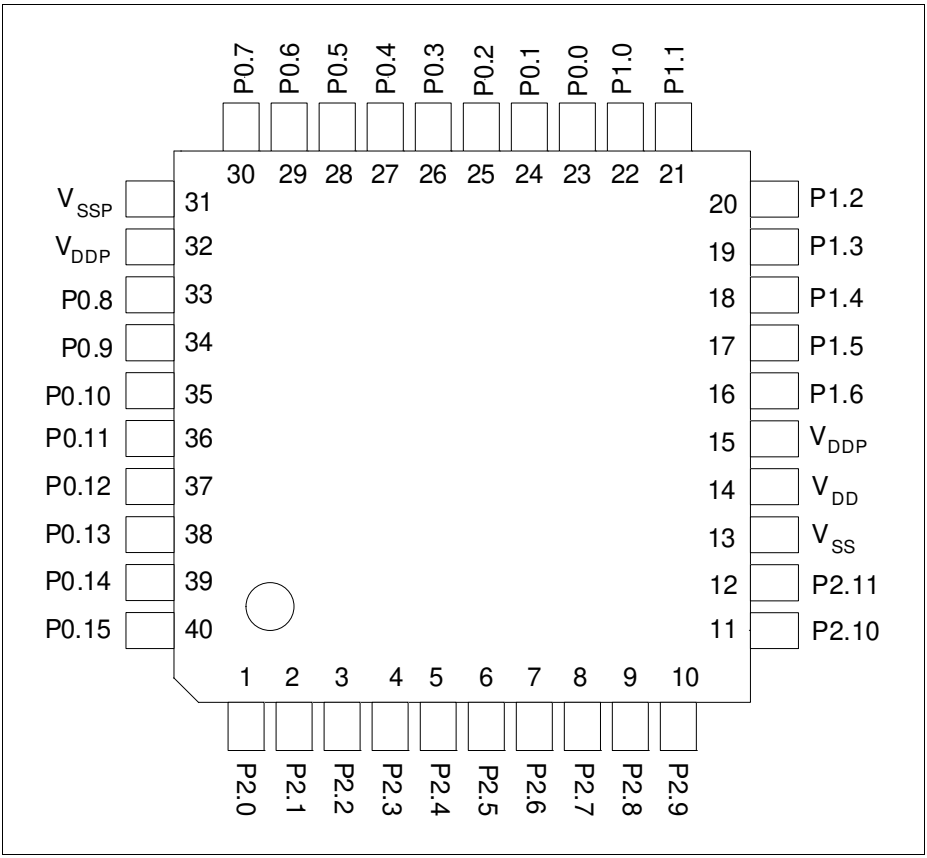

Figure 7 XMC1100 **PG-VQFN-40 Pin Configuration** (top view)

2.2.1 Package Pin Summary

The following general building block is used to describe each pin:

Table 5 Package Pin Mapping Description

Function	Package A	Package B	...	Pad Type
Px.y	N	N		Pad Class

The table is sorted by the “Function” column, starting with the regular Port pins (Px.y), followed by the supply pins.

The following columns, titled with the supported package variants, lists the package pin number to which the respective function is mapped in that package.

The “Pad Type” indicates the employed pad type:

- STD_INOUT (standard bi-directional pads)
- STD_INOUT/AN (standard bi-directional pads with analog input)
- High Current (high current bi-directional pads)
- STD_IN/AN (standard input pads with analog input)
- Power (power supply)

Details about the pad properties are defined in the Electrical Parameters.

Table 6 Package Pin Mapping

Function	VQFN 40	TSSOP 38	VQFN 24	TSSOP 16	Pad Type	Notes
P0.0	23	17	15	7	STD_INOUT	
P0.1	24	18	-	-	STD_INOUT	
P0.2	25	19	-	-	STD_INOUT	
P0.3	26	20	-	-	STD_INOUT	
P0.4	27	21	-	-	STD_INOUT	
P0.5	28	22	16	8	STD_INOUT	
P0.6	29	23	17	9	STD_INOUT	
P0.7	30	24	18	10	STD_INOUT	
P0.8	33	27	19	11	STD_INOUT	
P0.9	34	28	20	12	STD_INOUT	
P0.10	35	29	-	-	STD_INOUT	
P0.11	36	30	-	-	STD_INOUT	
P0.12	37	31	21	-	STD_INOUT	

Table 6 Package Pin Mapping

Function	VQFN 40	TSSOP 38	VQFN 24	TSSOP 16	Pad Type	Notes
P0.13	38	32	22	-	STD_INOUT	
P0.14	39	33	23	13	STD_INOUT	
P0.15	40	34	24	14	STD_INOUT	
P1.0	22	16	14	-	High Current	
P1.1	21	15	13	-	High Current	
P1.2	20	14	12	-	High Current	
P1.3	19	13	11	-	High Current	
P1.4	18	12	-	-	High Current	
P1.5	17	11	-	-	High Current	
P1.6	16	-	-	-	STD_INOUT	
P2.0	1	35	1	15	STD_INOUT/AN	
P2.1	2	36	2	-	STD_INOUT/AN	
P2.2	3	37	3	-	STD_IN/AN	
P2.3	4	38	-	-	STD_IN/AN	
P2.4	5	1	-	-	STD_IN/AN	
P2.5	6	2	-	-	STD_IN/AN	
P2.6	7	3	4	16	STD_IN/AN	
P2.7	8	4	5	1	STD_IN/AN	
P2.8	9	5	5	1	STD_IN/AN	
P2.9	10	6	6	2	STD_IN/AN	
P2.10	11	7	7	3	STD_INOUT/AN	
P2.11	12	8	8	4	STD_INOUT/AN	
VSS	13	9	9	5	Power	Supply GND, ADC reference GND
VDD	14	10	10	6	Power	Supply VDD, ADC reference voltage/ ORC reference voltage. VDD has to be supplied with the same voltage as VDDP

Table 6 Package Pin Mapping

Function	VQFN 40	TSSOP 38	VQFN 24	TSSOP 16	Pad Type	Notes
VDDP	15	10	10	6	Power	I/O port supply
VSSP	31	25	-	-	Power	I/O port ground
VDDP	32	26	-	-	Power	I/O port supply
VSSP	Exp. Pad	-	Exp. Pad	-	Power	**Exposed Die Pad** The exposed die pad is connected internally to VSSP. For proper operation, it is mandatory to connect the exposed pad to the board ground. For thermal aspects, please refer to the Package and Reliability chapter.

2.2.2 Port I/O Functions

The following general building block is used to describe each PORT pin:

Table 7 Port I/O Function Description

Function	Outputs			Inputs		
	ALT1	ALTn	HWO0	HWI0	Input	Input
P0.0		MODA.OUT	MODB.OUT	MODB.INA	MODC.INA	
Pn.y	MODA.OUT				MODA.INA	MODC.INB

Pn.y is the port pin name, defining the control and data bits/registers associated with it. As GPIO, the port is under software control. Its input value is read via Pn_IN.y, Pn_OUT defines the output value.

Up to seven alternate output functions (ALT1/2/3/4/5/6/7) can be mapped to a single port pin, selected by Pn_IOCR.PC. The output value is directly driven by the respective module, with the pin characteristics controlled by the port registers (within the limits of the connected pad).

The port pin input can be connected to multiple peripherals. Most peripherals have an input multiplexer to select between different possible input sources.

The input path is also active while the pin is configured as output. This allows to feedback an output to on-chip resources without wasting an additional external pin.

By Pn_HWSEL, it is possible to select between different hardware “masters” (HWO0/HWI0, HWO1/HWI1). The selected peripheral can take control of the pin(s). Hardware control overrules settings in the respective port pin registers.

Table 8 Port I/O Functions

Function	Outputs									Inputs								
	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	HWO0	HWO1	HWI0	HWI1	Input	Input	Input	Input	Input	Input	Input
P0.0	ERU0. PDOUT0		ERU0. GOUT0	CCU40.OUT0		USIC0_CH0. SELO0	USIC0_CH1. SELO0					CCU40.IN0C				USIC0_CH0. DX2A	USIC0_CH1. DX2A	
P0.1	ERU0. PDOUT1		ERU0. GOUT1	CCU40.OUT1			SCU. VDROP					CCU40.IN1C						
P0.2	ERU0. PDOUT2		ERU0. GOUT2	CCU40.OUT2		VADC0. EMUX02						CCU40.IN2C						
P0.3	ERU0. PDOUT3		ERU0. GOUT3	CCU40.OUT3		VADC0. EMUX01						CCU40.IN3C						
P0.4				CCU40.OUT1		VADC0. EMUX00	WWDT. SERVICE_OUT											
P0.5				CCU40.OUT0														
P0.6				CCU40.OUT0		USIC0_CH1. MCLKOUT	USIC0_CH1. DOUT0					CCU40.IN0B				USIC0_CH1. DX0C		
P0.7				CCU40.OUT1		USIC0_CH0. SCLKOUT	USIC0_CH1. DOUT0					CCU40.IN1B				USIC0_CH0. DX1C	USIC0_CH1. DX0D	USIC0_CH1. DX1C
P0.8				CCU40.OUT2		USIC0_CH0. SCLKOUT	USIC0_CH1. SCLKOUT					CCU40.IN2B				USIC0_CH0. DX1B	USIC0_CH1. DX1B	
P0.9				CCU40.OUT3		USIC0_CH0. SELO0	USIC0_CH1. SELO0					CCU40.IN3B				USIC0_CH0. DX2B	USIC0_CH1. DX2B	
P0.10						USIC0_CH0. SELO1	USIC0_CH1. SELO1									USIC0_CH0. DX2C	USIC0_CH1. DX2C	
P0.11				USIC0_CH0. MCLKOUT		USIC0_CH0. SELO2	USIC0_CH1. SELO2									USIC0_CH0. DX2D	USIC0_CH1. DX2D	
P0.12						USIC0_CH0. SELO3						CCU40.IN0A	CCU40.IN1A	CCU40.IN2A	CCU40.IN3A	USIC0_CH0. DX2E		
P0.13	WWDT. SERVICE_OUT					USIC0_CH0. SELO4										USIC0_CH0. DX2F		
P0.14						USIC0_CH0. DOUT0	USIC0_CH0. SCLKOUT									USIC0_CH0. DX0A	USIC0_CH0. DX1A	
P0.15						USIC0_CH0. DOUT0	USIC0_CH1. MCLKOUT									USIC0_CH0. DX0B		
P1.0		CCU40.OUT0					USIC0_CH0. DOUT0		USIC0_CH0. DOUT0		USIC0_CH0. HWIN0					USIC0_CH0. DX0C		
P1.1	VADC0. EMUX00	CCU40.OUT1				USIC0_CH0. DOUT0	USIC0_CH1. SELO0		USIC0_CH0. DOUT1		USIC0_CH0. HWIN1					USIC0_CH0. DX0D	USIC0_CH0. DX1D	USIC0_CH1. DX2E
P1.2	VADC0. EMUX01	CCU40.OUT2					USIC0_CH1. DOUT0		USIC0_CH0. DOUT2		USIC0_CH0. HWIN2					USIC0_CH1. DX0B		
P1.3	VADC0. EMUX02	CCU40.OUT3				USIC0_CH1. SCLKOUT	USIC0_CH1. DOUT0		USIC0_CH0. DOUT3		USIC0_CH0. HWIN3					USIC0_CH1. DX0A	USIC0_CH1. DX1A	
P1.4	VADC0. EMUX10	USIC0_CH1. SCLKOUT				USIC0_CH0. SELO0	USIC0_CH1. SELO1									USIC0_CH0. DX5E	USIC0_CH1. DX5E	
P1.5	VADC0. EMUX11	USIC0_CH0. DOUT0				USIC0_CH0. SELO1	USIC0_CH1. SELO2									USIC0_CH1. DX5F		

Table 8 Port I/O Functions (cont'd)

Function	Outputs									Inputs								
	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	HWO0	HWO1	HWI0	HWI1	Input	Input	Input	Input	Input	Input	Input
P1.6	VADC0.EMUX12	USIC0_CH1.DOUT0		USIC0_CH0.SCLKOUT		USIC0_CH0.SELO2	USIC0_CH1.SELO3							USIC0_CH0.DX5F				
P2.0	ERU0.PDOUT3	CCU40.OUT0	ERU0.GOUT3			USIC0_CH0.DOUT0	USIC0_CH0.SCLKOUT						VADC0.G0CH5		ERU0.0B0	USIC0_CH0.DX0E	USIC0_CH1.DX1E	USIC0_CH1.DX2F
P2.1	ERU0.PDOUT2	CCU40.OUT1	ERU0.GOUT2			USIC0_CH0.DOUT0	USIC0_CH1.SCLKOUT						VADC0.G0CH6		ERU0.1B0	USIC0_CH0.DX0F	USIC0_CH1.DX3A	USIC0_CH1.DX4A
P2.2													VADC0.G0CH7		ERU0.0B1	USIC0_CH0.DX3A	USIC0_CH0.DX4A	USIC0_CH1.DX5A
P2.3													VADC0.G1CH5		ERU0.1B1	USIC0_CH0.DX5B	USIC0_CH1.DX3C	USIC0_CH1.DX4C
P2.4													VADC0.G1CH6		ERU0.0A1	USIC0_CH0.DX3B	USIC0_CH0.DX4B	USIC0_CH1.DX5B
P2.5													VADC0.G1CH7		ERU0.1A1	USIC0_CH0.DX5D	USIC0_CH1.DX3E	USIC0_CH1.DX4E
P2.6													VADC0.G0CH0		ERU0.2A1	USIC0_CH0.DX3E	USIC0_CH0.DX4E	USIC0_CH1.DX5D
P2.7													VADC0.G1CH1		ERU0.3A1	USIC0_CH0.DX5C	USIC0_CH1.DX3D	USIC0_CH1.DX4D
P2.8													VADC0.G0CH1	VADC0.G1CH0	ERU0.3B1	USIC0_CH0.DX3D	USIC0_CH0.DX4D	USIC0_CH1.DX5C
P2.9													VADC0.G0CH2	VADC0.G1CH4	ERU0.3B0	USIC0_CH0.DX5A	USIC0_CH1.DX3B	USIC0_CH1.DX4B
P2.10	ERU0.PDOUT1	CCU40.OUT2	ERU0.GOUT1				USIC0_CH1.DOUT0						VADC0.G0CH3	VADC0.G1CH2	ERU0.2B0	USIC0_CH0.DX3C	USIC0_CH0.DX4C	USIC0_CH1.DX0F
P2.11	ERU0.PDOUT0	CCU40.OUT3	ERU0.GOUT0			USIC0_CH1.SCLKOUT	USIC0_CH1.DOUT0						VADC0.G0CH4	VADC0.G1CH3	ERU0.2B1	USIC0_CH1.DX0E	USIC0_CH1.DX1E	

3 Electrical Parameter

This section provides the electrical parameter which are implementation-specific for the XMC1100.

3.1 General Parameters

3.1.1 Parameter Interpretation

The parameters listed in this section represent partly the characteristics of the XMC1100 and partly its requirements on the system. To aid interpreting the parameters easily when evaluating them for a design, they are indicated by the abbreviations in the “Symbol” column:

- **CC**
  Such parameters indicate **C**ontroller **C**haracteristics, which are distinctive feature of the XMC1100 and must be regarded for a system design.
- **SR**
  Such parameters indicate **S**ystem **R**equirements, which must be provided by the application system in which the XMC1100 is designed in.

3.1.2 Absolute Maximum Ratings

Stresses above the values listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions may affect device reliability.

Table 9 Absolute Maximum Rating Parameters

Parameter	Symbol		Values			Unit	Note / Test Condition
			Min.	Typ.	Max.		
Junction temperature	T_J	SR	-40	–	115	°C	–
Storage temperature	T_S	SR	-40	–	125	°C	–
Voltage on power supply pin with respect to V_{SSP}	V_{DDP}	SR	-0.3	–	6	V	–
Voltage on any pin with respect to V_{SSP}	V_{IN}	SR	-0.5	–	V_{DDP} + 0.5 or max. 6	V	whichever is lower
Voltage on any analog input pin with respect to V_{SSP}	V_{AIN} V_{AREF}	SR	-0.5	–	V_{DDP} + 0.5 or max. 6	V	–
Input current on any pin during overload condition	I_{IN}	SR	-10	–	10	mA	–
Absolute sum of all input currents during overload condition	$\Sigma\|I_{IN}\|$	SR	–	–	50	mA	–
Analog comparator input voltage	V_{CM}	SR	-0.3	–	V_{DDP} + 0.3	V	

3.1.3 Operating Conditions

The following operating conditions must not be exceeded in order to ensure correct operation and reliability of the XMC1100. All parameters specified in the following tables refer to these operating conditions, unless noted otherwise.

Table 10 Operating Conditions Parameters

Parameter	Symbol	Values			Unit	Note / Test Condition
		Min.	Typ.	Max.		
Ambient Temperature	T_A SR	-40	–	85	°C	Temp. Range F
		-40	–	105	°C	Temp. Range X
Digital supply voltage[1)]	V_{DDP} SR	1.8	–	5.5	V	
MCLK Frequency	f_{MCLK} CC	–	–	33.2	MHz	CPU clock
PCLK Frequency	f_{PCLK} CC	–	–	66.4	MHz	Peripherals clock

1) See also the Supply Monitoring thresholds, **Chapter 3.3.3**.