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### GENERAL DESCRIPTION

The XR16L784<sup>1</sup> (784) is a quad Universal Asynchronous Receiver and Transmitter (UART). The device is designed for high bandwidth requirement in communication systems. The global interrupt source register provides a complete interrupt status indication for all 4 channels to speed up interrupt parsing. Each UART has its own 16C550 compatible set of configuration registers, transmit and receive FIFOs of 64 bytes, fully programmable transmit and receive FIFO level triggers, transmit and receive FIFO level counters, automatic RTS/CTS or DTR/DSR hardware flow control with programmable hysteresis, automatic software (Xon/Xoff) flow control, IrDA (Infrared Data Association) encoder/decoder, and a 16-bit general purpose timer/counter.

**NOTE:** 1 Covered by U.S. Patents #5,649,122 and #5,949,787

# **APPLICATIONS**

- Remote Access Servers
- Ethernet Network to Serial Ports
- Network Management
- Factory Automation and Process Control
- Point-of-Sale Systems
- Multi-port RS-232/RS-422/RS-485 Cards

# FIGURE 1. BLOCK DIAGRAM

# **FEATURES**

- 2.97V to 5.5V operation with 5V Tolerant Inputs
- 8-bit Intel or Motorola Data Bus Interface
- Single Open Drain Interrupt output for all 4 channels
- Global Interrupt Source Registers for all channels
- 5G (Fifth Generation) "Flat" Register Set
- Each UART is Independently Controlled with:
  - 16C550 Compatible Registers
  - 64-byte Transmit and Receive FIFOs
  - Transmit and Receive FIFO Level Counters
  - Programmable TX and RX FIFO Trigger Levels
  - Automatic RTS/CTS or DTR/DSR Flow Control
  - Selectable RTS Flow Control Hysteresis
  - Automatic Xon/Xoff Software Flow Control
  - Automatic RS485 Half-duplex Control Output with 16 Selectable Turn-around Delay
  - Infrared (IrDA 1.1) Data Encoder/Decoder
  - Programmable Data Rate with Prescaler
  - Up to 3.12 (16x) and 6.25 (8x) Mbps Data Rate
- A General Purpose 16-bit Timer/Counter
- Sleep Mode with Automatic Wake-up Indicator
- 64-pin LQFP Package (10x10x1.4 mm)

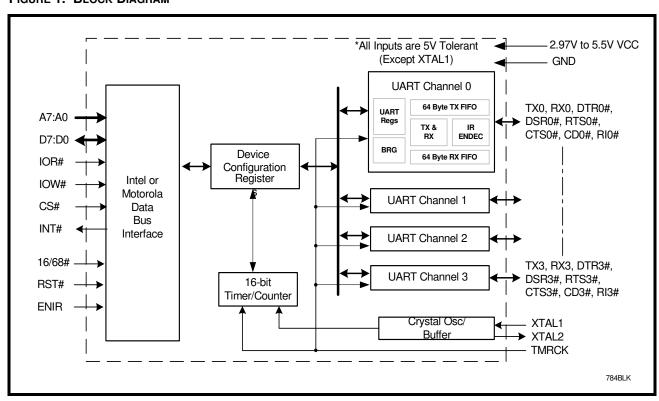
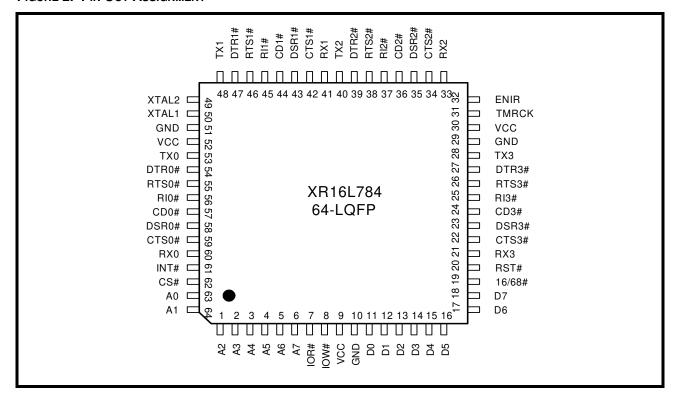




FIGURE 2. PIN OUT ASSIGNMENT



# **ORDERING INFORMATION**

PART NUMBER	Package	OPERATING TEMPERATURE RANGE	DEVICE STATUS
XR16L784CV	64-Lead LQFP	0°C to +70°C	Active
XR16L784IV	64-Lead LQFP	-40°C to +85°C	Active



# **PIN DESCRIPTIONS**

# **Pin Descriptions**

NAME	Pin#	Түре	DESCRIPTION
DATA BUS INTE	RFACE		
A7-A0	6-1,64,63	I	Address data lines [7:0]. A0:A3 selects individual UART's 16 configuration registers, A4:A6 selects UART channel 0 to 3, and A7 selects the global device configuration registers
D7:D0	18-11	Ю	Data bus lines (7:0] (bidirectional).
IOR#	7	I	When 16/68# pin is HIGH, it selects Intel bus interface and this input is read strobe (active low). The falling edge instigates an internal read cycle and retrieves the data byte from an internal register pointed by the address lines [A7:A0], puts it on the data bus to allow the host processor to read it on the leading edge.  When 16/68# pin is LOW, it selects Motorola bus interface and this input should be connected to VCC.
IOW# (R/W#)	8	I	When 16/68# pin is HIGH, it selects Intel bus interface and this input becomes write strobe (active low). The falling edge instigates the internal write cycle and the leading edge transfers the data byte on the data bus to an internal register pointed by the address lines.  When 16/68# pin is LOW, it selects Motorola bus interface and this input becomes read (logic 1) and write (logic 0) signal.
CS#	62	I	When 16/68# pin is HIGH, this input is chip select (active low) to enable the XR16L784 device.  When 16/68# pin is LOW, this input becomes the read and write strobe (active low) for the Motorola bus interface.
INT#	61	OD	Global interrupt output from XR16L784 (open drain, active low). This output requires an external pull-up resistor (47K-100K ohms) to operate properly. It may be shared with other devices in the system to form a single interrupt line to the host processor and have the software driver polls each device for the interrupt status.
MODEM OR SE	RIAL I/O INTERF	ACE	
TX0	53	0	UART channel 0 Transmit Data or infrared transmit data. Normal TXD output idles HIGH while infrared TXD output idles LOW.
RX0	60	I	UART channel 0 Receive Data or infrared receive data. Normal RXD input idles HIGH while infrared RXD input idles LOW. In the infrared mode, the polarity of the incoming RXD signal can be selected via FCTR bit-4. If this bit is a logic 0, a LOW on the RXD input is considered a mark and if this bit is a logic 1, a HIGH on the RXD input is considered a space.
RTS0#	55	0	UART channel 0 Request to Send or general purpose output (active low). This port must be asserted prior using for one of two functions:  1) auto RTS flow control, see EFR bit-6, MCR bits-1 & 2, FCTR bits 0-3 and IER bit-6  2) Auto RS485 half-duplex direction control, see FCTR bit-5, MCR bit-2 and MSR bits 4-7.
CTS0#	59	I	UART channel 0 Clear to Send or general purpose input (active low). It can be used for auto CTS flow control, see EFR bit-7, MCR bit-2 and IER bit-7.

# REV. 1.2.3



# **Pin Descriptions**

NAME	Pin#	Түре	DESCRIPTION
DTR0#	54	0	UART channel 0 Data Terminal Ready or general purpose output (active low). This port must be asserted prior using for one of two functions:  1) auto DTR flow control, see EFR bit-6, FCTR bits-0 to 3, MCR bits-0 & 2, and IER bit-6  2) Auto RS485 half-duplex direction control, see FCTR bit-5, MCR bit-2 and MSR bit 4-7.
DSR0#	58	I	UART channel 0 Data Set Ready or general purpose input (active low). It can be used for auto DSR flow control, see EFR bit-7, MCR bit-2 and IER bit-7.
CD0#	57	I	UART channel 0 Carrier Detect or general purpose input (active low).
RI0#	56	I	UART channel 0 Ring Indicator or general purpose input (active low).
TX1	48	0	UART channel 1 Transmit Data or infrared transmit data. Normal TXD output idles HIGH while infrared TXD output idles LOW.
RX1	41	ı	UART channel 1 Receive Data or infrared receive data. Normal RXD input idles HIGH while infrared RXD input idles LOW. In the infrared mode, the polarity of the incoming RXD signal can be selected via FCTR bit-4. If this bit is a logic 0, a LOW on the RXD input is considered a mark and if this bit is a logic 1, a HIGH on the RXD input is considered a space.
RTS1#	46	0	UART channel 1 Request to Send or general purpose output (active low). See description of RTS0# pin.
CTS1#	42	1	UART channel 1 Clear to Send or general purpose input (active low). See description of CTS0# pin.
DTR1#	47	0	UART channel 1 Data Terminal Ready or general purpose output (active low). See description of DTS0# pin.
DSR1#	43	1	UART channel 1 Data Set Ready or general purpose input (active low). See description of DSR0# pin.
CD1#	44	I	UART channel 1 Carrier Detect or general purpose input (active low).
RI1#	45	I	UART channel 1 Ring Indicator or general purpose input (active low).
TX2	40	0	UART channel 2 Transmit Data or infrared transmit data. Normal TXD output idles HIGH while infrared TXD output idles LOW.
RX2	33	I	UART channel 2 Receive Data or infrared receive data. Normal RXD input idles HIGH while infrared RXD input idles LOW. In the infrared mode, the polarity of the incoming RXD signal can be selected via FCTR bit-4. If this bit is a logic 0, a LOW on the RXD input is considered a mark and if this bit is a logic 1, a HIGH on the RXD input is considered a space.
RTS2#	38	0	UART channel 2 Request to Send or general purpose output (active low). See description of RTS0# pin.
CTS2#	34	I	UART channel 2 Clear to Send or general purpose input (active low). See description of CTS0# pin.
DTR2#	39	0	UART channel 2 Data Terminal Ready or general purpose output (active low). See description of DTS0# pin.
DSR2#	35	I	UART channel 2 Data Set Ready or general purpose input (active low). See description of DSR0# pin.
CD2#	36	I	UART channel 2 Carrier Detect or general purpose input (active low).
RI2#	37	I	UART channel 2 Ring Indicator or general purpose intput (active low).



# **Pin Descriptions**

NAME	Pin#	Түре	DESCRIPTION
TX3	28	0	UART channel 3 Transmit Data or infrared transmit data. Normal TXD output idles HIGH while infrared TXD output idles LOW.
RX3	21	I	UART channel 3 Receive Data or infrared receive data. Normal RXD input idles HIGH while infrared RXD input idles LOW. In the infrared mode, the polarity of the incoming RXD signal can be selected via FCTR bit-4. If this bit is a logic 0, a LOW on the RXD input is considered a mark and if this bit is a logic 1, a HIGH on the RXD input is considered a space.
RTS3#	26	0	UART channel 3 Request to Send or general purpose output (active low). See description of RTS0# pin.
CTS3#	22	1	UART channel 3 Clear to Send or general purpose input (active low).d. See description of CTS0# pin.
DTR3#	27	0	UART channel 3 Data Terminal Ready or general purpose output (active low). See description of DTS0# pin.
DSR3#	23	I	UART channel 3 Data Set Ready or general purpose input (active low). See description of DSR0# pin.
CD3#	24	ı	UART channel 3 Carrier Detect or general purpose input (active low).
RI3#	25	ı	UART channel 3 Ring Indicator or general purpose input (active low).
ANCILLARY SIG	NALS		
XTAL1	50	I	Crystal or external clock input. Caution: this input is not 5V tolerant.
XTAL2	49	0	Crystal or buffered clock output.
TMRCK	31	I	16-bit timer/counter external clock input.
ENIR	32	I	Infrared mode enable (active high). This pin is sampled during power up, following a hardware reset (RST#) or soft-reset (register RESET). It can be used to start up all 8 UARTs in the infrared mode. The sampled logic state is transferred to MCR bit-6 in the UART.
RST#	20	I	Reset (active low). The configuration and UART registers are reset to default values, see Table-15.
16/68#	19	I	Intel or Motorola data bus interface select. HIGH selects Intel bus interface and LOW selects Motorola interface. This input affects the functionality of IOR#, IOW# and CS# pins.
VCC	9,30,52		+5V or +3.3V supply, all inputs are 5V tolerant except for XTAL1.
GND	10,29,51		Power supply common, ground.

**Note:** Pin type: I=Input, O=Output, IO= Input/output, OD=Output Open Drain.

**RFV 123** 

#### 1.0 DESCRIPTION

The XR16L784 (784) integrates the functions of 4 enhanced 16550 UARTs, a general purpose 16-bit timer/counter and an on-chip oscillator. The device configuration registers include a set of four consecutive interrupt source registers that provides interrupt-status for all 4 UARTs, timer/counter and a sleep wake up indicator. Each UART channel has its own 16550 UART compatible configuration register set for individual channel control, status, and data transfer. Additionally, each UART channel has 64-byte of transmit and receive FIFOs, automatic RTS/CTS or DTR/DSR hardware flow control with hysteresis control, automatic Xon/Xoff and special character software flow control, programmable transmit and receive FIFO trigger levels, FIFO level counters, infrared encoder and decoder (IrDA ver 1.0), programmable baud rate generator with a prescaler of divide by 1 or 4, and data rate up to 6.25 Mbps with 8X sampling clock rate or 3.125Mbps in the 16X rate. The XR16L784 is a 5V and 3.3V device with 5 volt tolerant inputs (except XTAL1).

#### 2.0 FUNCTIONAL DESCRIPTIONS

#### 2.1 Device Reset

#### 2.1.1 Hardware Reset

The RST# input resets the internal registers and the serial interface outputs in all 4 channels to their default state (see Table 19). A LOW pulse of longer than 40 ns duration will be required to activate the reset function in the device.

#### 2.1.2 Software Reset

The internal registers of each UART can be reset by writing to the RESET register in the Device Configuration Registers. For more details, see the RESET register description on page 23.

#### 2.2 UART Channel Selection

The UART provides the user with the capability to bi-directionally transfer information between an external CPU and an external serial communication device. A logic 0 on the chip select pins, CS#, allows the user to select one of the UART channels to configure, send transmit data and/or unload receive data to/from the UART. When address line A7 = 0, address lines A5:A4 are used to select one of the eight channels. See Table 1 below for UART channel selection.

**A7 A6 A5 A4 FUNCTION** 0 Channel 0 Selected 0 0 0 0 0 0 1 Channel 1 Selected 0 0 1 0 Channel 2 Selected 0 0 1 1 Channel 3 Selected 1 Χ Χ 0 Reserved

**TABLE 1: UART CHANNEL SELECTION** 

# 2.3 Simultaneous Write to All Channels

During a write cycle, the setting of REGB bit-0 to a logic 1 will override the channel selection of address A5:A4 and allow a simultaneous write to all 4 UART channels when any channel is written to. This functional capability allow the registers in all 8 UART channels to be modified concurrently, saving individual channel initialization time. Caution should be considered, however, when using this capability. Any in-process serial data transfer may be disrupted by changing an active channel's mode. Also, REGB bit-0 should be reset to a logic 0 before attempting to read from the UART.



# 2.4 INT# Ouput

The INT# interrupt output changes according to the operating mode and enhanced features setup. Table 2 and 3 summarize the operating behavior for the transmitter and receiver.

TABLE 2: INT# PIN OPERATION FOR TRANSMITTER

	Auto RS485 Mode	FCR Bit-0 = 0 (FIFO DISABLED)	FCR BIT-0 = 1 (FIFO ENABLED)
INT# Pin	NO	_	HIGH = FIFO above trigger level LOW = FIFO below trigger level or FIFO empty
INT# Pin	YES	•	HIGH = FIFO above trigger level LOW = FIFO below trigger level or transmitter empty

TABLE 3: INT# PIN OPERATION FOR RECEIVER

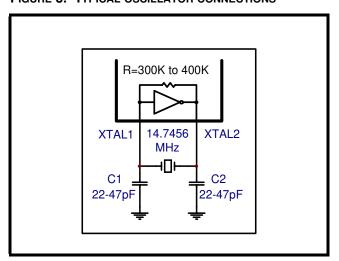
	FCR Bit-0 = 0 (FIFO DISABLED)	FCR Bit-0 = 1 (FIFO ENABLED)
INT# Pin		HIGH = FIFO below trigger level LOW = FIFO above trigger level

# 2.5 CRYSTAL OSCILLATOR / BUFFER

The 784 includes an on-chip oscillator (XTAL1 and XTAL2). The crystal oscillator provides the system clock to the Baud Rate Generators (BRG) in each of the 8 UARTs, the 16-bit general purpose timer/counter and internal logics. XTAL1 is the input to the oscillator or external clock buffer input with XTAL2 pin being the output. For programming details, see "Section 2.6, Programmable Baud Rate Generator" on page 8.

The on-chip oscillator is designed to use an industry standard microprocessor crystal (parallel resonant, fundamental frequency with 10-22 pF capacitance load, ESR of 20-120 ohms and 100ppm frequency tolerance) connected externally between the XTAL1 and XTAL2 pins (see Figure 3). Alternatively, an external clock can be connected to the XTAL1 pin to clock the internal 8 baud rate generators for standard or custom rates. Typically, the oscillator connections are shown in Figure 3. For further reading on oscillator circuit please see application note DAN108 on EXAR's web site.

FIGURE 3. TYPICAL OSCILLATOR CONNECTIONS

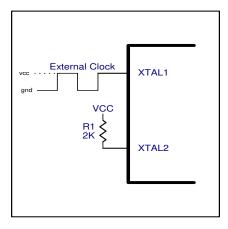




# 2.6 Programmable Baud Rate Generator

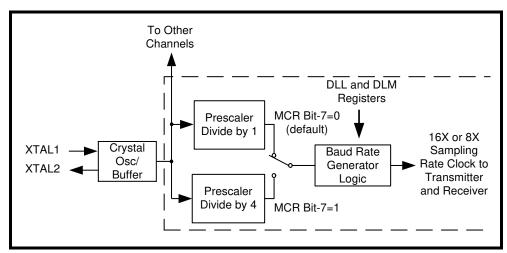
A single Baud Rate Generator (BRG) is provided for the transmitter and receiver, allowing independent TX/RX channel control. The programmable Baud Rate Generator is capable of operating with a crystal frequency of up to 24 MHz. However, with an external clock input on XTAL1 pin and a 2K ohms pull-up resistor on XTAL2 pin (as shown in Figure 4) it can extend its operation up to 50 MHz (3.125 Mbps serial data rate) at room temperature and 5.0V.

FIGURE 4. EXTERNAL CLOCK CONNECTION FOR EXTENDED DATA RATE



Each UART has its own Baud Rate Generator (BRG) with a prescaler for the transmitter and receiver. The prescaler is controlled by a software bit in the MCR register. The MCR register bit-7 sets the prescaler to divide the input crystal or external clock by 1 or 4. The output of the prescaler clocks to the BRG. The BRG further divides this clock by a programmable divisor between 1 and (2<sup>16</sup>-1) to obtain a 16X or 8X sampling clock of the serial data rate. The sampling clock is used by the transmitter for data bit shifting and receiver for data sampling. The BRG divisor (DLL and DLM registers) defaults to a random value upon power up. Therefore, the BRG must be programmed during initialization to the operating data rate.

FIGURE 5. BAUD RATE GENERATOR





Programming the Baud Rate Generator Registers DLM and DLL provides the capability of selecting the operating data rate. Table 4 shows the standard data rates available with a 14.7456 MHz crystal or external clock at 16X clock rate. At 8X sampling rate, these data rates would double. When using a non-standard data rate crystal or external clock, the divisor value can be calculated for channel 'N' with the following equation(s).

divisor (decimal) = (XTAL1 clock frequency / prescaler) / (serial data rate x 16), **when 8XMODE-BIT N is 0** divisor (decimal) = (XTAL1 clock frequency / prescaler) / (serial data rate x 8), **when 8XMODE-BIT N is 1** 

TABLE 4: TYPICAL DATA RATES WITH A 14.7456 MHz CRYSTAL OR EXTERNAL CLOCK AT 16X SAMPLING

Оитрит Data Rate MCR Bit-7=1	Оитрит Data Rate MCR Bit-7=0	DIVISOR FOR 16x Clock (Decimal)	DIVISOR FOR 16x Clock (HEX)	DLM PROGRAM VALUE (HEX)	DLL PROGRAM VALUE (HEX)	DATA RATE ERROR (%)
100	400	2304	900	09	00	0
600	2400	384	180	01	80	0
1200	4800	192	C0	00	C0	0
2400	9600	96	60	00	60	0
4800	19.2k	48	30	00	30	0
9600	38.4k	24	18	00	18	0
19.2k	76.8k	12	0C	00	0C	0
38.4k	153.6k	6	06	00	06	0
57.6k	230.4k	4	04	00	04	0
115.2k	460.8k	2	02	00	02	0
230.4k	921.6k	1	01	00	01	0

#### 2.7 Transmitter

The transmitter section comprises of an 8-bit Transmit Shift Register (TSR) and 64 bytes of FIFO which includes a byte-wide Transmit Holding Register (THR). TSR shifts out every data bit with the 16X internal clock. A bit time is 16 clock periods (see EMSR bit-7). The transmitter sends the start-bit followed by the number of data bits, inserts the proper parity-bit if enabled, and adds the stop-bit(s). The status of the FIFO and TSR are reported in the Line Status Register (LSR bit-5 and bit-6).

# 2.7.1 Transmit Holding Register (THR) - Write Only

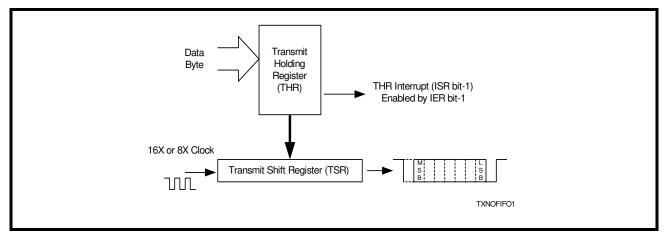
The transmit holding register is an 8-bit register providing a data interface to the host processor. The host writes transmit data byte to the THR to be converted into a serial data stream including start-bit, data bits, parity-bit and stop-bit(s). The least-significant-bit (Bit-0) becomes first data bit to go out. The THR is the input register to the transmit FIFO of 64 bytes when FIFO operation is enabled by FCR bit-0. Every time a write operation is made to the THR, the FIFO data pointer is automatically bumped to the next sequential data location.

#### 2.7.2 Transmitter Operation in non-FIFO Mode

The host loads transmit data to THR one character at a time. The THR empty flag (LSR bit-5) is set when the data byte is transferred to TSR. THR flag can generate a transmit empty interrupt (ISR bit-1) when it is enabled by IER bit-1. The TSR flag (LSR bit-6) is set when TSR becomes completely empty.



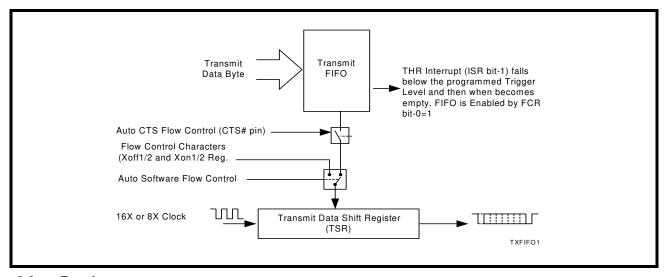
FIGURE 6. TRANSMITTER OPERATION IN NON-FIFO MODE



# 2.7.3 Transmitter Operation in FIFO Mode

The host may fill the transmit FIFO with up to 64 bytes of transmit data. The THR empty flag (LSR bit-5) is set whenever the FIFO is empty. The THR empty flag can generate a transmit empty interrupt (ISR bit-1) when the amount of data in the FIFO falls below its programmed trigger level. The transmit empty interrupt is enabled by IER bit-1. The TSR flag (LSR bit-6) is set when TSR/FIFO becomes empty.

FIGURE 7. TRANSMITTER OPERATION IN FIFO AND FLOW CONTROL MODE



# 2.8 Receiver

The receiver section contains an 8-bit Receive Shift Register (RSR) and 64 bytes of FIFO which includes a byte-wide Receive Holding Register (RHR). The RSR uses the 16X for timing. It verifies and validates every bit on the incoming character in the middle of each data bit. On the falling edge of a start or false start bit, an internal receiver counter starts counting at the 16X. After 8 clocks the start bit period should be at the center of the start bit. At this time the start bit is sampled and if it is still a logic 0 it is validated. Evaluating the start bit in this manner prevents the receiver from assembling a false character. The rest of the data bits and stop bits are sampled and validated in this same manner to prevent false framing. If there were any error(s), they are reported in the LSR register bits 2-4. Upon unloading the receive data byte from RHR, the receive FIFO pointer is bumped and the error tags are immediately updated to reflect the status of the data byte in RHR register. RHR can generate a receive data ready interrupt upon receiving a character or delay until it reaches the FIFO trigger level. Furthermore, data delivery to the host is guaranteed by a receive data ready time-out interrupt when data is not received for 4 word lengths as defined by LCR[1:0] plus 12 bits time. This is equivalent to 3.7-4.6 character times. The RHR interrupt is enabled by IER bit-0.



# 2.8.1 Receive Holding Register (RHR) - Read-Only

The Receive Holding Register is an 8-bit register that holds a receive data byte from the Receive Shift Register. It provides the receive data interface to the host processor. The RHR register is part of the receive FIFO of 64 bytes by 11-bits wide, the 3 extra bits are for the 3 error tags to be reported in LSR register. When the FIFO is enabled by FCR bit-0, the RHR contains the first data character received by the FIFO. After the RHR is read, the next character byte is loaded into the RHR and the errors associated with the current data byte are immediately updated in the LSR bits 2-4.

FIGURE 8. RECEIVER OPERATION IN NON-FIFO MODE

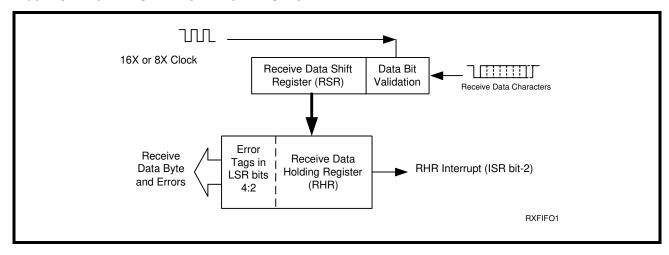
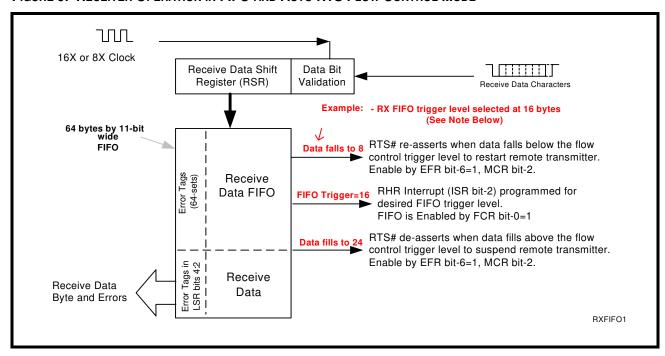


FIGURE 9. RECEIVER OPERATION IN FIFO AND AUTO RTS FLOW CONTROL MODE



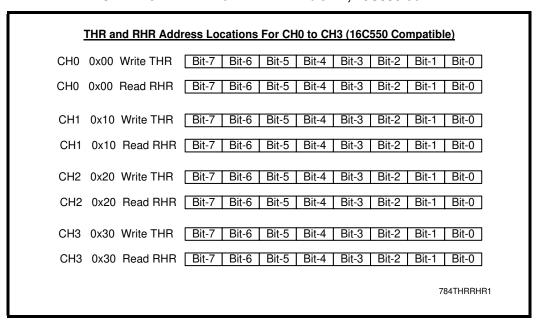
**NOTE:** Table-B selected as Trigger Table for Figure 9 (Table 14).



# 2.9 THR and RHR Register Locations

The THR and RHR register addresses for channel 0 to channel 7 is shown in Table 5 below. The THR and RHR for channels 0 to 3 are located at address 0x00, 0x10, 0x20 and 0x30 respectively. Transmit data byte is loaded to the THR when writing to that address and receive data is unloaded from the RHR register when reading that address. Both THR and RHR registers are 16C550 compatible in 8-bit format, so each bus operation can only write or read in bytes.

TABLE 5: TRANSMIT AND RECEIVE DATA REGISTER, 16C550 COMPATIBLE



# 2.10 Automatic RTS/DTR Hardware Flow Control Operation

Automatic RTS/DTR flow control is used to prevent data overrun to the local receiver FIFO. The RTS#/DTR# output pin is used to request remote unit to suspend/resume data transmission. The flow control features are individually selected to fit specific application requirement (see Figure 10):

- Select RTS (and CTS) or DTR (and DSR) through MCR bit-2.
- Enable auto RTS/DTR flow control using EFR bit-6.
- The auto RTS or auto DTR function must be started by asserting the RTS# or DTR# output pin (MCR bit-1 or bit-0 to a logic 1, respectively) after it is enabled.
- If using programmable RX FIFO trigger levels, hysteresis levels can be selected via FCTR bits 3-0.

With the Auto RTS function enabled, the RTS# output pin will not be de-asserted (HIGH) when the receive FIFO reaches the programmed trigger level, but will be de-asserted when the FIFO reaches the next trigger level for Trigger Tables A-C (See Table 14). The RTS# output pin will be asserted (LOW) again after the FIFO is unloaded to the next trigger level below the programmed trigger level.

For Trigger Table D (or programmable trigger levels), the RTS# output pin is de-asserted when the the RX FIFO level reaches the RX trigger level plus the hysteresis level and is asserted when the RX FIFO level falls below the RX trigger level minus the hysteresis level.

However, even under these conditions, the 788 will continue to accept data until the receive FIFO is full if the remote UART transmitter continues to send data.

• If used, enable RTS/DTR interrupt through IER bit-6 (after setting EFR bit-4). The UART issues an interrupt when the RTS#/DTR# pin makes a transition: ISR bit-5 will be set to 1.



#### 2.10.1 Auto CTS/DSR Flow Control

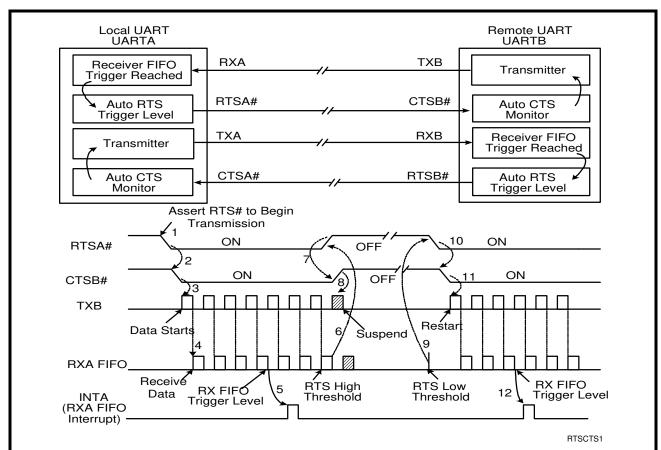
Automatic CTS/DSR flow control is used to prevent data overrun to the remote receiver FIFO. The CTS/DSR pin is monitored to suspend/restart local transmitter. The flow control features are individually selected to fit specific application requirement (see Figure 10):

- Select CTS (and RTS) or DSR (and DTR) through MCR bit-2.
- Enable auto CTS/DSR flow control using EFR bit-7.

With the Auto CTS or Auto DTR function enabled, the UART will suspend transmission as soon as the stop bit of the character in the Transmit Shift Register has been shifted out. Transmission is resumed after the CTS#/DTR# input is re-asserted (logic 0), indicating more data may be sent.

• If used, enable CTS/DSR interrupt through IER bit-7 (after setting EFR bit-4). The UART issues an interrupt when the CTS#/DSR# pin makes a transition: ISR bit-5 will be set to a logic 1, and UART will suspend TX transmissions as soon as the stop bit of the character in process is shifted out. Transmission is resumed after the CTS#/DSR# input returns LOW, indicating more data may be sent.

FIGURE 10. AUTO RTS/DTR AND CTS/DSR FLOW CONTROL OPERATION



The local UART (UARTA) starts data transfer by asserting RTSA# (1). RTSA# is normally connected to CTSB# (2) of remote UART (UARTB). CTSB# allows its transmitter to send data (3). TXB data arrives and fills UARTA receive FIFO (4). When RXA data fills up to its receive FIFO trigger level, UARTA activates its RXA data ready interrupt (5) and continues to receive and put data into its FIFO. If interrupt service latency is long and data is not being unloaded, UARTA monitors its receive data fill level to match the upper threshold of RTS delay and de-assert RTSA# (6). CTSB# follows (7) and request UARTB transmitter to suspend data transfer. UARTB stops or finishes sending the data bits in its transmit shift register (8). When receive FIFO data in UARTA is unloaded to match the lower threshold of RTS delay (9), UARTA re-asserts RTSA# (10), CTSB# recognizes the change (11) and restarts its transmitter and data flow again until next receive FIFO trigger (12). This same event applies to the reverse direction when UARTA sends data to UARTB with RTSB# and CTSA# controlling the data flow.



# 2.11 Auto Xon/Xoff (Software) Flow Control

When software flow control is enabled (See Table 18), the 784 compares one or two sequential receive data characters with the programmed Xon or Xoff-1,2 character value(s). If receive character(s) (RX) match the programmed values, the 784 will halt transmission (TX) as soon as the current character has completed transmission. When a match occurs, the Xoff (if enabled via IER bit-5) flag will be set and the interrupt output pin will be activated. Following a suspension due to a match of the Xoff character, the 784 will monitor the receive data stream for a match to the Xon-1,2 character. If a match is found, the 784 will resume operation and clear the flags (ISR bit-4).

Reset initially sets the contents of the Xon/Xoff 8-bit flow control registers to a logic 0. Following reset, any desired Xon/Xoff value can be used for software flow control. Different conditions can be set to detect Xon/Xoff characters (See Table 18) and suspend/resume transmissions. When double 8-bit Xon/Xoff characters are selected, the 784 compares two consecutive receive characters with two software flow control 8-bit values (Xon1, Xon2, Xoff1, Xoff2) and controls TX transmissions accordingly. Under the above described flow control mechanisms, flow control characters are not placed (stacked) in the user accessible RX data buffer or FIFO.

In the event that the receive buffer is overfilling and flow control needs to be executed, the 784 automatically sends an Xoff message (when enabled) via the serial TX output to the remote modem. The 784 sends the Xoff-1,2 characters two character times (= time taken to send two characters at the programmed baud rate) after the receive FIFO crosses the programmed trigger level (for all trigger tables A-D). To clear this condition, the 784 will transmit the programmed Xon-1,2 characters as soon as receive FIFO is less than one trigger level below the programmed trigger level (for Trigger Tables A, B, and C) or when receive FIFO is less than the trigger level minus the hysteresis value (for Trigger Table D). This hysteresis value is the same as the Auto RTS/DTR Hysteresis value in Table 17. Table 6 below explains this when Trigger Table-B (See Table 14) is selected.

RX TRIGGER LEVEL	INT PIN ACTIVATION	XOFF CHARACTER(S) SENT (CHARACTERS IN RX FIFO)	XON CHARACTER(S) SENT (CHARACTERS IN RX FIFO)
8	8	8*	0
16	16	16*	8
24	24	24*	16
28	28	28*	24

TABLE 6: AUTO XON/XOFF (SOFTWARE) FLOW CONTROL

# 2.12 Special Character Detect

A special character detect feature is provided to detect an 8-bit character when bit-5 is set in the Enhanced Feature Register (EFR). When this character (Xoff2) is detected, it will be placed in the FIFO along with normal incoming RX data.

The 784 compares each incoming receive character with Xoff-2 data. If a match exists, the received data will be transferred to FIFO and ISR bit-4 will be set to indicate detection of special character. Although the Internal Register Table shows Xon, Xoff Registers with eight bits of character information, the actual number of bits is dependent on the programmed word length. Line Control Register (LCR) bits 0-1 defines the number of character bits, i.e., either 5 bits, 6 bits, 7 bits, or 8 bits. The word length selected by LCR bits 0-1 also determines the number of bits that will be used for the special character comparison. Bit-0 in the Xon, Xoff Registers corresponds with the LSB bit for the receive character.

<sup>\*</sup> After the trigger level is reached, an xoff character is sent after a short span of time (= time required to send 2 characters); for example, after 2.083ms has elapsed for 9600 baud and 10-bit word length setting.



# 2.13 Auto RS485 Half-duplex Control

The auto RS485 half-duplex direction control changes the behavior of the transmitter when enabled by FCTR bit-5. It asserts RTS# or DTR# (LOW) after a specified delay indicated in MSR[7:4] following the last stop bit of the last character that has been transmitted. This helps in turning around the transceiver to receive the remote station's response. The delay optimizes the time needed for the last transmission to reach the farthest station on a long cable network before switching off the line driver. This delay prevents undesirable line signal disturbance that causes signal degradation. When the host is ready to transmit next polling data packet again, it only has to load data bytes to the transmit FIFO. The transmitter automatically de-asserts RTS# or DTR# output (HIGH) prior to sending the data. The auto RS485 half-duplex direction control also changes the transmitter empty interrupt to TSR empty instead of THR empty.

# 2.14 Infrared Mode

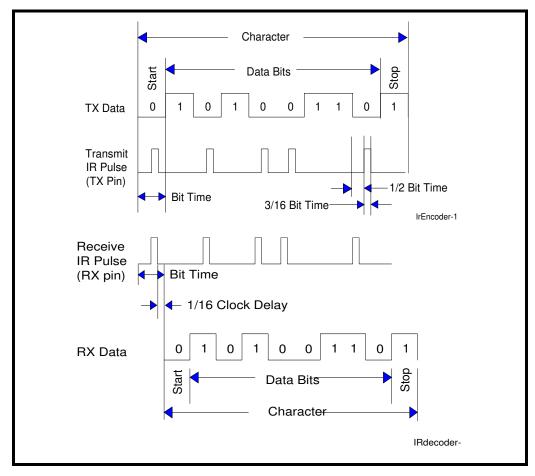
Each UART in the 784 includes the infrared encoder and decoder compatible to the IrDA (Infrared Data Association) version 1.0. The input pin ENIR conveniently activates all 8 UART channels to start up in the infrared mode. Note that the ENIR pin is sampled when the RST# input is de-asserted. This global control pin enables the MCR bit-6 function in every UART channel register. After power up or a reset, the software can overwrite MCR bit-6 if so desired. ENIR and MCR bit-6 also disable the receiver while the transmitter is sending data. This prevents echoed data from reaching the receiver. The global activation ENIR pin prevents the infrared emitter from turning on and drawing large amount of current while the system is starting up. When the infrared feature is enabled, the transmit data outputs, TX[3:0], would idle at logic zero level. Likewise, the RX [3:0] inputs assume an idle level of logic zero.

The infrared encoder sends out a 3/16 of a bit wide HIGH-pulse for each "0" bit in the transmit data stream. This signal encoding reduces the on-time of the infrared LED, hence reduces the power consumption. See Figure 11.

The infrared decoder receives the input pulse from the infrared sensing diode on RX pin. Each time it senses a light pulse, it returns a logic zero to the data bit stream. The decoder also accepts (when FCTR bit-4 = 1) an inverted IR-encoded input signal. This option supports active low instead of normal active high pulse from some infrared modules on the market.

REV. 1.2.3

FIGURE 11. INFRARED TRANSMIT DATA ENCODING AND RECEIVE DATA DECODING





# 2.15 Sleep Mode with Wake-Up Indicator

The 784 supports low voltage system designs, hence, a sleep mode is included to reduce its power consumption when the chip is not actively used.

All of these conditions must be satisfied for the 784 to enter sleep mode:

- no interrupts pending for all 8 channels of the 784 (ISR bit-0 = 1)
- SLEEP register = 0x0F
- $\blacksquare$  modem inputs are not toggling (MSR bits 0-3 = 0)
- RX input pin of all 4 channels are idling HIGH

The 784 stops its crystal oscillator to conserve power in the sleep mode. User can check the XTAL2 pin for no clock output as an indication that the device has entered the sleep mode.

The 784 resumes normal operation by any of the following:

- a receive data start bit transition (HIGH to LOW)
- a data byte is loaded to the transmitter, THR or FIFO
- a change of logic state on any of the modem or general purpose serial inputs: CTS#, DSR#, CD#, RI#

If the 784 is awakened by any one of the above conditions, it will return to the sleep mode automatically after all interrupting conditions have been serviced and cleared. If the 784 is awakened by the modem inputs, a read to the MSR is required to reset the modem inputs. In any case, the sleep mode will not be entered while an interrupt is pending in any channel. Also, a special interrupt is generated with an indication of no pending interrupt. Reading INT0 will clear this special interrupt. The 784 will stay in the sleep mode of operation until it is disabled by setting SLEEP = 0x00.

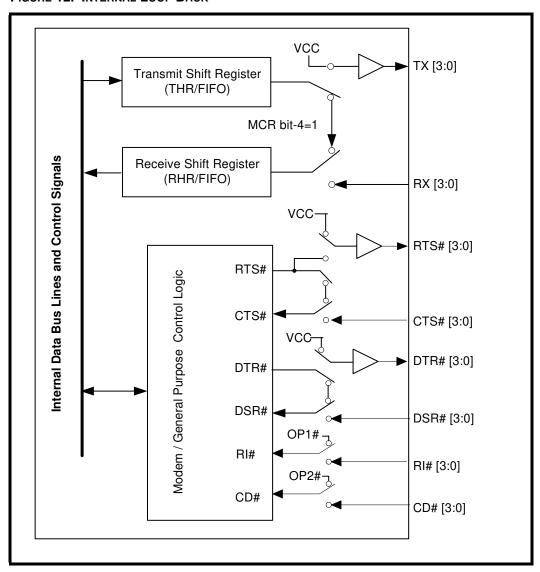
A word of caution: owing to the starting up delay of the crystal oscillator after waking up from sleep mode, the first few receive characters may be lost. The number of characters lost during the restart also depends on your operating data rate. More characters are lost when operating at higher data rate.



# 2.16 Internal Loopback

Each UART channel provides an internal loopback capability for system diagnostic purposes. The internal loopback mode is enabled by setting MCR register bit-4 to logic 1. All regular UART functions operate normally. Figure 12 shows how the modem port signals are re-configured. Transmit data from the transmit shift register output is internally routed to the receive shift register input allowing the system to receive the same data that it was sending. The TX, RTS# and DTR# pins are held HIGH (idle or de-asserted state), and the CTS#, DSR# CD# and RI# inputs are ignored.

FIGURE 12. INTERNAL LOOP BACK

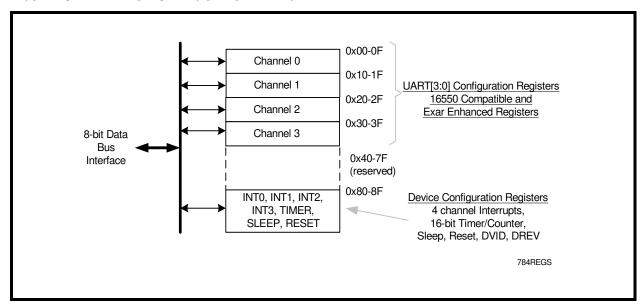




# 3.0 XR16L784 REGISTERS

The XR16L784 quad UART register set consists of the <u>Device Configuration Registers</u> that are accessible directly from the data bus for programming general operating conditions of the UARTs and monitoring the status of various functions. These functions include all 4 channel UART's interrupt control and status, 16-bit general purpose timer control and status, sleep mode, soft-reset, and device identification and revision. Also, each UART channel has its own set of internal <u>UART Configuration Registers</u> for its own operation control, status reporting and data transfer. These registers are mapped into a 256-byte of the data memory address space. The following paragraphs describe all the registers in detail.

FIGURE 13. THE XR16L784 REGISTERS MAPPING



#### 3.1 DEVICE CONFIGURATION REGISTER SET

The device configuration registers are directly accessible from the bus. This provides easy programming of general operating parameters to the 784 UART and for monitoring the status of various functions. The device configuration registers are mapped onto address 0x80-8F as shown on the register map in Table 8 and Figure 13. These registers provide global controls and status of all 4 channel UARTs that include interrupt status, 16-bit general purpose timer control and status, 8X or 16X sampling clock, sleep mode control, soft-reset control, simultaneous UART initialization, and device identification and revision.

TABLE 7: XR16L784 REGISTER SETS

Address [A7:A0]	UART CHANNEL SPACE	REFERENCE	Соммент
0x00 - 0x0F	UART channel 0 Registers	(Table 11 & 12)	First 8 registers are 16550 compatible
0x10 - 0x1F	UART channel 1 Registers	(Table 11 & 12)	
0x20 - 0x2F	UART channel 2 Registers	(Table 11 & 12)	
0x30 - 0x3F	UART channel 3 Registers	(Table 11 & 12)	
0x40 - 0x7F	None		Reserved
0x80 - 0x8F	Device Configuration Registers	(Table 8)	Interrupt registers and global controls

REV. 1.2.3

**TABLE 8: DEVICE CONFIGURATION REGISTERS** 

Address [A7:A0]		REGISTED	Віт 7	Віт 6	Віт 5	Віт 4	Віт 3	Віт 2	Віт 1	Віт 0
0x80	R	INT0 Source	Rsvd	Rsvd	Rsvd	Rsvd	UART 3	UART 2	UART 1	UART 0
0x81	R	INT1	UART 2 bit 1	source bit 0	UART 1 bit 2	interrupt bit 1	source bit 0	UART 0 bit 2	interrupt bit 1	source bit 0
0x82	R	INT2	Rsvd	Rsvd	Rsvd	Rsvd	UART 3 bit 2	interrupt bit 1	source bit 0	UART 2 bit 2
0x83	R	INT3	Rsvd	Rsvd	Rsvd	Rsvd	Rsvd	Rsvd	Rsvd	Rsvd
0x84	R/W	TIMER CTRL	0	0	0	0	clock source	function select	start timer	enable timer INT
0x85	R	TIMER	0	0	0	0	0	0	0	0
0x86	R/W	TIMER LSB	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
0x87	R/W	TIMER MSB	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
0x88	R/W	8X MODE	Rsvd	Rsvd	Rsvd	Rsvd	UART 3	UART 2	UART 1	UART 0
0x89	R	REG 1	0	0	0	0	0	0	0	0
0x8A	W	RESET	Rsvd	Rsvd	Rsvd	Rsvd	Reset UART 3	Reset UART 2	Reset UART 1	Reset UART 0
0x8B	R/W	SLEEP	Rsvd	Rsvd	Rsvd	Rsvd	Enable sleep UART 3	Enable sleep UART 2	Enable sleep UART 1	Enable sleep UART 0
0x8C	R	DREV	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
0x8D	R	DVID	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
0x8E	R/W	REG 2	0	0	0	0	0	0	0	Write to all UARTs



# 3.1.1 The Global Interrupt Source Registers

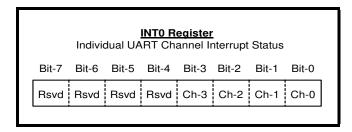
The XR16L784 has a global interrupt source register set that consists of 4 consecutive registers [INT0, INT1, INT2 and INT3]. Register INT3 is not used in the 784 UART, only in the 8-channel XR16L788. The 3 registers are in the device configuration register address space.

INT3 (Rsvd)	INT2	INT1	INT0
[0x00]	[0x00]	[0x00]	[0x00]

All 4 registers default to logic zero (as indicated in square braces) for no interrupt pending. All 4 channel interrupts are enabled or disabled in each channel's IER register. INTO shows individual status for each channel while INT1 and INT2 show the details of the source of each channel's interrupt with its unique 3-bit encoding. Figure 14 shows the 4 interrupt registers in sequence for clarity. The 16-bit timer and sleep wake-up interrupts are masked in the device configuration registers, TIMERCNTL and SLEEP. An interrupt is generated by the 784 when awakened from sleep if all 4 channels were placed in the sleep mode previously. Reading INTO will clear this wake-up interrupt.

Each bit in the INTO register gives an indication of the channel that has requested service.

# 3.1.1.1 INTO Channel Interrupt Indicator:



For example, bit-0 represents channel 0 and bit-3 indicates channel 3. Bits 4 to 7 are reserved and remains at logic zero. Logic one indicates the channel N [3:0] has called for service. The interrupt bit clears after reading the appropriate register of the interrupting UART channel register (ISR, LSR and MSR). See Table 13 for interrupt clearing details.

# 3.1.1.2 INT1 and INT2 Interrupt Source Locator

INT2 and INT1 provide a 12-bit (3 bits per channel) encoded interrupt indicator. Table 9 shows the 3 bit encoding and their priority order. The 16-bit Timer time-out interrupt will show up only as a channel 0 interrupt. For other channels, interrupt 7 is reserved.

FIGURE 14. THE GLOBAL INTERRUPT REGISTERS, INTO, INT1, INT2 AND INT3

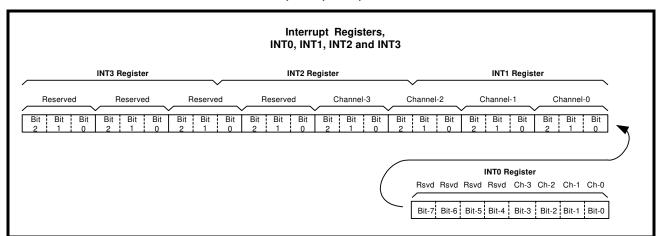




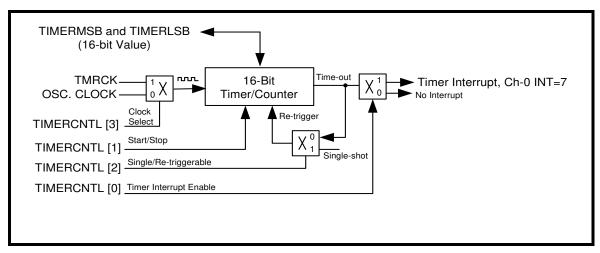
TABLE 9: UART CHANNEL	[3:0]	INTERRUPT SOURCE ENCODING AND CLEARING
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PRIORITY	Віт2	Віт1	Віт0	INTERRUPT SOURCE(S) AND CLEARING	
Х	0	0	0	None	
1	0	0	1	RXRDY & RX Line Status (logic OR of LSR[4:1]). RXRDY INT clears by reading data in the RX FIFO until it falls below the trigger level; RX Line Status INT cleared after reading LSR register.	
2	0	1	0	RXRDY Time-out: Cleared when the FIFO becomes empty.	
3	0	1	1	TXRDY, THR or TSR (auto RS485 mode) empty, clears after reading ISR register.	
4	1	0	0	MSR, RTS/CTS or DTR/DSR delta or Xoff/Xon or special character detected. The first two clear after reading MSR register; Xoff/Xon or special char. detect INT clears after reading ISR register.	
5	1	0	1	Reserved.	
6	1	1	0	Reserved.	
7	1	1	1	TIMER Time-out, shows up as a channel 0 INT. It clears after reading the TIMERCNTL register. Reserved in other channels.	

# 3.1.2 General Purpose 16-bit Timer/Counter. [TIMERMSB, TIMELSB, TIMER, TIMECNTL] (DEFAULT 0xXX-XX-00-00)

A 16-bit down-count timer for general purpose timer or counter. Its clock source may be selected from internal crystal oscillator or externally on pin TMRCK. The timer can be set to be a single-shot for a one-time event or re-triggerable for a periodic event. An interrupt may be generated in the INT Register when the timer times out. It is controlled through 4 configuration registers [TIMERCNTL, TIMER, TIMELSB, TIMERMSB]. These registers provide start/stop and re-triggerable or one-shot operation. The time-out output of the Timer can be set to generate an interrupt for system or event alarm.

FIGURE 15. TIMER/COUNTER CIRCUIT.



**TABLE 10: TIMER CONTROL REGISTER** 

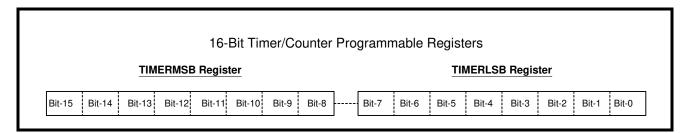
TIMERCNTL [0]	Logic 0 (default) disables Timer-Counter interrupt and logic one enables the interrupt, reading the TIMERCNTL clears the interrupt.
TIMERCNLT [1]	Logic 0 (default) stops/pauses the timer and logic one starts/re-starts the timer/counter.
TIMERCNTL [2]	Logic0 (default) selects re-trigger timer function and logic one selects one-shot (timer function.
TIMERCNTL [3]	Logic 0 (default) selects internal and logic one selects external clock to the timer/counter.
TIMERCNTL [7:4]	Reserved (defaults to zero).

REV. 1.2.3

#### **TIMERCNTL** Register Bit-7 Bit-6 Bit-5 Bit-4 Bit-3 Bit-2 Bit-1 Bit-0 Clock Single/ Start/ INT Rsvd Rsvd Rsvd Rsvd Select Re-trigger Stop Enable

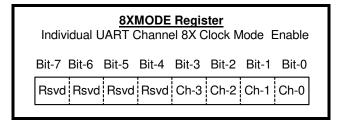
TIMER [7:0] (default 0x00): Reserved.
TIMERMSB [7:0] and TIMERLSB [7:0]

TIMERMSB and TIMERLSB form a 16-bit value. The least-significant bit of the timer is being bit [0] of the TIMERLSB with most-significant-bit being bit [7] in TIMERMSB. Reading the TIMERCNTL register will clear its interrupt. Default value is zero upon powerup and reset.



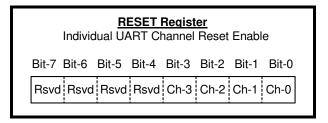
# 3.1.3 8XMODE [7:0] (default 0x00)

Each bit selects 8X or 16X sampling rate for that UART channel, bit-0 is channel 0. Logic 0 (default) selects normal 16X sampling with logic one selects 8X sampling rate. Transmit and receive data rates will double by selecting 8X.



# 3.1.4 REGA [7:0] reserved (default 0x00)

# 3.1.5 RESET [7:0] (default 0x00)



The 8-bit Reset register [RESET] provides the software with the ability to reset individual UART(s) when there is a need. Each bit is self-resetting after it is written a logic 1 to perform a reset to that channel. All registers in that channel will be reset to the default condition, see **Table 19** for details. As an example, bit-0 =1 resets UART channel 0 with bit-3=1 resets channel 3.

RFV 123

# 3.1.6 SLEEP [7:0] - (default 0x00)

The 8-bit Sleep register enables each UART separately to enter Sleep mode. Sleep mode reduces power consumption when the system needs to put the UART(s) to idle. The UART enters sleep mode when there is no interrupt pending. When all 4 UARTs are put to sleep, the on-chip oscillator shuts off to further conserve power. In this case, the quad UART is awakened by any of the UART channel on from a receive data byte or a change on the modem port (CTS#, DSR#, CD# and RI#). The UART is ready after 32 crystal clocks to ensure full functionality. Also, a special interrupt is generated with an indication of no pending interrupt. Reading INT0 will clear this wake-up interrupt. Logic 0 (default) and logic 1 disable and enable sleep mode respectively.

# SLEEP Register Individual UART Channel Sleep Enable Bit-7 Bit-6 Bit-5 Bit-4 Bit-3 Bit-2 Bit-1 Bit-0 Rsvd Rsvd Rsvd Rsvd Ch-3 Ch-2 Ch-1 Ch-0

# 3.1.7 Device Identification and Revision

There are 2 internal registers that provide device identification and revision, DVID and DREV registers. The 8-bit content in the DVID register provides device identification. A return value of 0x24 from this register indicates the device is a XR16L784. The DREV register returns a 8-bit value of 0x01 for revision A, 0x02 for revision B and so on. This information is very useful to the software driver for identifying which device it is communicating with and to keep up with revision changes.

# DVID [7:0] (default 0x24)

Device identification for the type of UART. The upper nibble indicates it is a XR16L78x series with lower nibble indicating the number of channels.

# Examples:

XR16L784 = 0x24

XR16L788 = 0x28

# **DREV [7:0]**

Revision number of the XR16L784. A 0x01 represents "revision-A" with 0x02 for rev-B and so forth.

# 3.1.8 REGB [7:0] - (default 0x00)

REGB register provides a control for simultaneous write to all 4 UARTs configuration registers or individually. This is very useful for device intialization in the power up and reset routines.

REGB[0]	Logic 0 (default) write to each UART configuration registers individually.			
	Logic 1 enables simultaneous write to all 4 UARTs configuration register. Useful during device initialization.			
REGB[7:1]	Reserved			



# 3.2 UART CHANNEL CONFIGURATION REGISTERS

The first 8 registers are 16550 compatible with EXAR enhanced feature registers located on the upper 8 addresses. The 4 sets of UART configuration registers are decoded using address lines A0 to A3 as shown below.

**TABLE 11: UART CHANNEL CONFIGURATION REGISTERS** 

<u>Address</u>				REGISTER	READ/WRITE	COMMENTS				
А3	A2	A1	A0							
	16550 COMPATIBLE REGISTERS									
0	0	0	0	RHR - Receive Holding Register	Read-only	LCR[7] = 0				
0	0	0	0	THR - Transmit Holding Register	Write-only	LCR[7] = 0				
0	0	0	0	DLL - Div Latch Low	Read/Write	LCR[7] = 1				
0	0	0	1	DLM - Div Latch High	Read/Write	LCR[7] = 1				
0	0	0	1	IER - Interrupt Enable Register	Read/Write	LCR[7] = 0				
0	0	1	0	ISR - Interrupt Status Register	Read-only					
0	0	1	0	FCR - FIFO Control Register	Write-only					
0	0	1	1	LCR - Line Control Register	Read/Write					
0	1	0	0	MCR - Modem Control Register	Read/Write					
0	1	0	1	LSR - Line Status Register	Read-only					
0	1	1	0	MSR - Modem Status Register	Read-only					
0	1	1	0	RS485 Turn-Around Delay Register	Write-only					
0	1	1	1	SPR - Scratch Pad Register	Read/Write					
		l .	1	ENHANCED REGISTERS						
1	0	0	0	FCTR - Feature Control Register	Read/Write					
1	0	0	1	EFR - Enhanced Function Register	Read/Write					
1	0	1	0	TXCNT - Transmit FIFO Level Counter	Read-only					
1	0	1	0	TXTRG - Transmit FIFO Trigger Level	Write-only					
1	0	1	1	RXCNT - Receive FIFO Level Counter	Read-only					
1	0	1	1	RXTRG - Receive FIFO Trigger Level	Write-only					
1	1	0	0	Xoff-1 - Xoff Character 1	Write-only					
1	1	0	0	Xchar	Read-only	Xon,Xoff Rcvd. Flags				
1	1	0	1	Xoff-2 - Xoff Character 2	Write-only					
1	1	1	0	Xon-1 - Xon Character 1	Write-only					
1	1	1	1	Xon-2 - Xon Character 2	Write-only					