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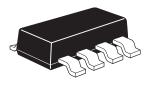




### **ANGLE SENSOR**

#### **DESCRIPTION**

The ZMT31 allows the contactless counting of the revolutions of a rotating magnet which is mounted on the axis of a wheel. Zero output voltages of the Wheatstones bridges are used as trigger signals. The sense of rotation of the wheel is taken into account by comparing the signal outputs of both Wheatstone bridges which are proportional to  $\sin 2(\alpha)$  or  $\sin 2(\alpha+45^\circ)$ . The angle can be determined by evaluating these signals. Alternatively it is possible to use the voltage signals of four half bridges which are trimmed on  $V_b/2$ .



SM8

### **FEATURES**

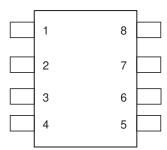
- Measures the magnetic field hrot (> 50kA/m) generated by a permanent magnet which rotates over the sensor
- Magnetic field hrot parallel to the chip surface causes a sinusoidal output signal
- Package: SM-8 (available on 12mm tape)

### **APPLICATION**

- Contactless counting of the revolutions of a rotating magnet (watermeters etc.)
- Contactless angular measurement
- Automotive (pedal position etc.)
- Contactless rotary switches
- Contactless potentiometer

#### ORDERING INFORMATION

DEVICE	REEL SIZE	TAPE WIDTH	QUANTITY PER REEL
ZMT31TA	7	12m m	1000
ZMT31TC	13	12m m	4000



Bridge1: pin 1: -V<sub>O</sub> pin 5: +VO

pin 8: -VB (GND) pin 4: +VB

**Bridge 2:** pin 2: -V<sub>O</sub> pin 6: +VO

pin 7: -VB (GND) pin 3: +VB

VO - output voltage VB - supply voltage

### **DEVICE MARKING**

ZMT31



## **ZMT31**

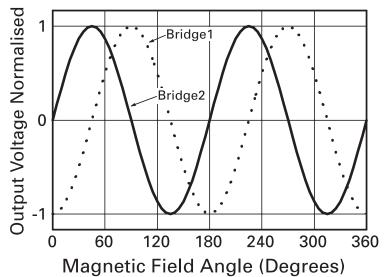
PARAMETER	SYMBOL	LIMIT	UNIT	
Supply voltage	V <sub>B</sub>	5	V	
Total power dissipation	P <sub>tot</sub>	120	m W	
Operating temperature range	T <sub>amb</sub>	-25 to +130	°C	
Storage temperature range	T <sub>stg</sub>	-40 to +130	°C	
Sensor chip alignment error	$\alpha_{e}$	≤2	0	

PARAM ETER	SYMBOL	MIN.	TYP.	MAX.	UNIT	TEST CONDITIONS	
Bridge resistance	R <sub>br</sub>	2.0	3.0	4.0	kΩ		
Offset voltage	V <sub>Off</sub> / V <sub>B</sub>	-2.0		+2.0	m V/V	bridge 1: $\alpha$ =45°; bridge 2: $\alpha$ =0°	
Sensitivity	$S_{\alpha}$	0.2			(m V/V)/°	bridge 1: $\alpha$ =0°; bridge 2: $\alpha$ =45°	
Half bridge symmetry	(V <sub>S</sub> /2-V <sub>O</sub> )/V <sub>B</sub>	-2.0		+2.0	m V/V	bridge 1: $\alpha$ =0°; bridge 2: $\alpha$ =45°	
Output voltage range	( Vmax + Vmin )/V <sub>B</sub>	16			m V/V		
Zero offset angle hysteresis	$\Delta \alpha$			2	0		
Temperature coefficient of the bridge resistance -25°C <t<sub>amb &lt;100°C</t<sub>	T <sub>CBR</sub>	0.25	0.30	0.35	%/K		
Temperature coefficient of	T <sub>CSV</sub>	-0.35	-0.30	-0.25	%/K	V <sub>B</sub> = const.	
the open circuit sensitivity -25°C <t<sub>amb &lt;100°C</t<sub>	T <sub>CSI</sub>	-0.05	0	0.05	%/K	I <sub>B</sub> = const	
Temperature coefficient of the offset voltage -25°C <t<sub>amb &lt;100°C</t<sub>	T <sub>COFF</sub>	-3		+3	(μV/V)/K		



## **ZMT31**

Output voltage of both Wheatstone bridges versus angle  $\boldsymbol{\alpha}$  of the magnetic field direction

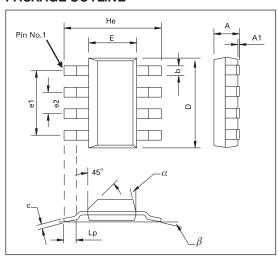


Output Voltage of both bridges vs Angle



### **ZMT31**

### **PACKAGE OUTLINE**



Controlling dimensions are in millimeters. Approximate conversions are given in inches

### **PACKAGE DIMENSIONS**

DIM	М	illimete	ers		Inches	;	DIM	Millimeters		ers	Inches		
DIIVI	Min	Max	Тур.	Min	Max	Тур.	DIIVI	Min	Max	Тур.	Min	Max	Тур.
Α	-	1.7	-	-	0.067	-	e1	-	-	4.59	-	-	0.1807
A1	0.02	0.1	-	0.008	0.004	-	e2	-	-	1.53	-	-	0.0602
b	-	-	0.7	-	-	0.0275	He	6.7	7.3	-	0.264	0.287	-
С	0.24	0.32	-	0.009	0.013	-	Lp	0.9	-	-	0.035	-	-
D	6.3	6.7	-	0.248	0.264	-	α	-	15°	-	-	15°	-
Е	3.3	3.7	-	0.130	0.145	-	β	-	-	10°	-	-	10°

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